#### Introduction to Probabilistic Reasoning

#### - inference, forecasting, decision -

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- Part 2 -

"Probability is good sense reduced to a calculus" (Laplace)

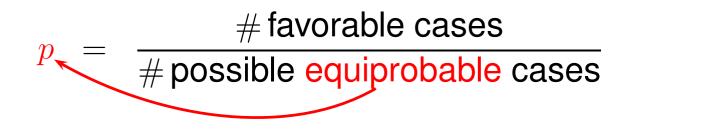
# What is probability?

# favorable cases

 $p = \frac{1}{\# \text{possible equiprobable cases}}$ 

 $p = \frac{\# \text{ times the event has occurred}}{\# \text{ independent trials under same conditions}}$ 

It is easy to check that 'scientific' definitions suffer of circularity

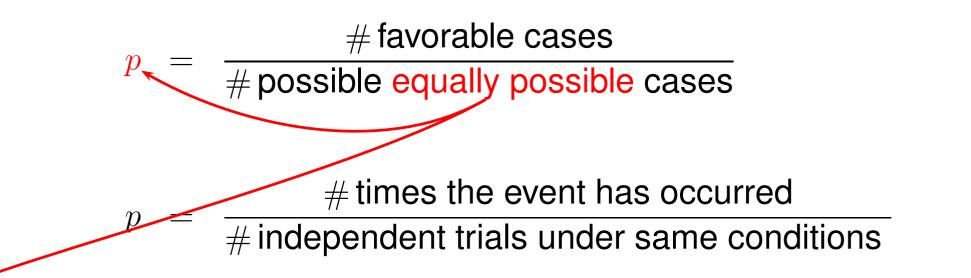


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# times the event has occurred

=  $\frac{1}{\#}$  independent trials under same conditions

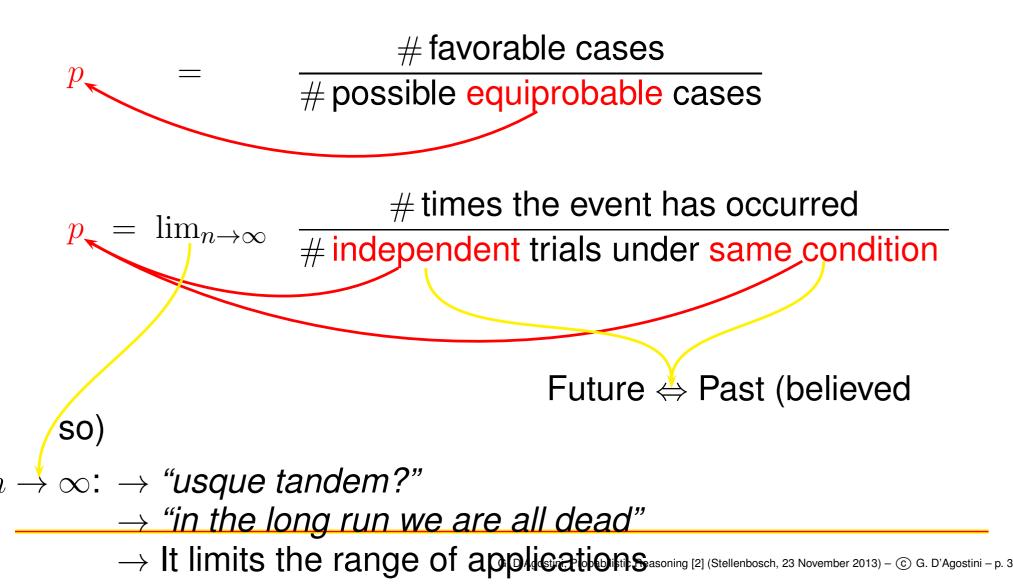
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aplace: *"lorsque rien ne porte à <mark>croire</mark> que l'un de ces cas doit arriver plutot que les autres"* 

Pretending that replacing 'equi-probable' by 'equi-possible' is just cheating students (as I did in my first lecture on the subject...).

It is easy to check that 'scientific' definitions suffer of circularity, plus other problems



#### $\textbf{Definitions} \rightarrow \textbf{evaluation rules}$

Very useful evaluation rules

$$A) \quad p = \frac{\# \text{favorable cases}}{\# \text{possible equiprobable cases}}$$

B) 
$$p = \frac{\# \text{ times the event has occurred}}{\# \text{ independent trials under same condition}}$$

If the implicit beliefs are well suited for each case of application.

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BUT they cannot define the concept of probability!

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In the probabilistic approach we are going to see

- Rule A will be recovered immediately (under the assumption of equiprobability, when it applies).
- Rule *B* will result from a theorem (under well defined
   G. D'Agostini, Probabilistic Reasoning [2] (Stellenbosch, 23 November 2013) © G. D'Agostini p. 4

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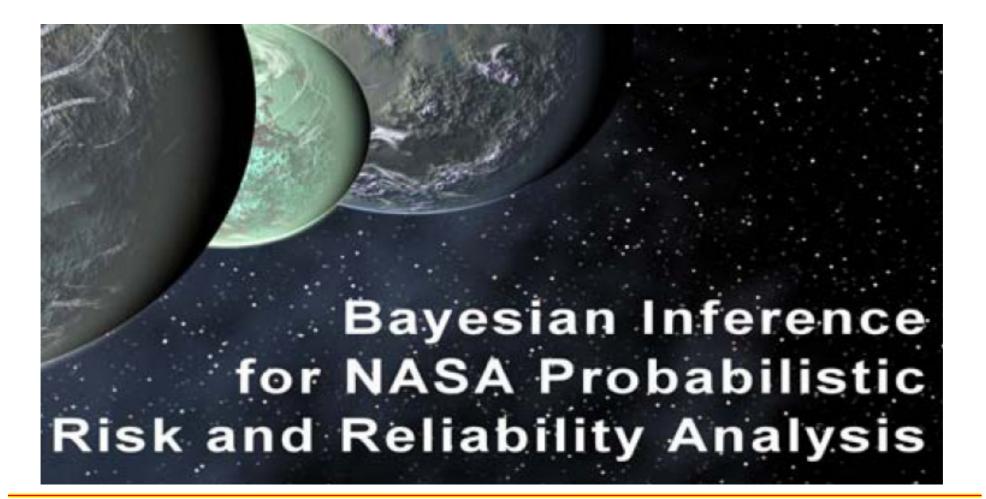
It is what everybody knows what it is before going at school

- → how much we are confident that something is true
- $\rightarrow$  how much we believe something
- → "A measure of the degree of belief that an event will occur"

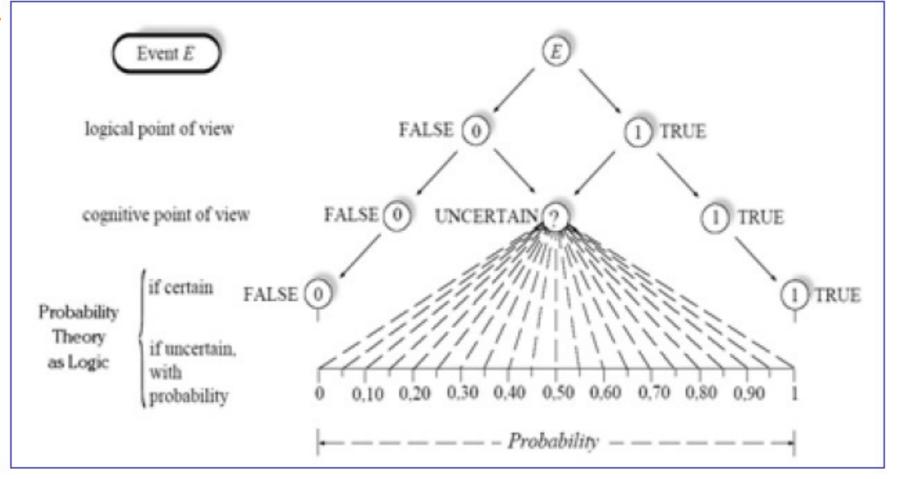
[Remark: 'will' does not imply future, but only uncertainty.]

# An helpful diagram

The previous diagram seems to help the understanding of the concept of probability



# An helpful diagram



• Figure 2-1. Graphical abstraction of probability as a measure of information (adapted from "Probability and Measurement Uncertainty in Physics" by D'Agostini, [1995]).

(... but NASA guys are afraid of 'subjective', or 'psychological')

Remarks:

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"The usual touchstone, whether that which someone asserts is merely his persuasion - or at least his subjective conviction, that is, his firm belief – is betting. It often happens that someone propounds his views with such positive and uncompromising assurance that he seems to have entirely set aside all thought of possible error. A bet disconcerts him. Sometimes it turns out that he has a conviction which can be estimated at a value of one ducat, but not of ten. For he is very willing to venture one ducat, but when it is a question of ten he becomes aware, as he had not previously been, that it may very well be that he is in error." (Kant)

Remarks:

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G. D'Agostini, Probabilistic Heasoning [2] (Stellenbosch, 23 November 2013) – ⓒ G. D'Agostini – p. 8

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  - you state the odds according on your beliefs;
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"His [Bouvard] calculations give him the mass of Saturn as 3,512th part of that of the sun. Applying my probabilistic formulae to these observations, I find that the odds are 11,000 to 1 that the error in this result is not a hundredth of its value." (Laplace)

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 $\rightarrow P(3477 \le M_{Sun}/M_{Sat} \le 3547 \,|\, I(\text{Laplace})) = 99.99\%$ 

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For more on the subject:
http://arxiv.org/abs/1112.3620
http://www.romal.infn.it/~dagos/badmath/#added

#### **Mathematics of beliefs**

#### The good news:

The basic laws of degrees of belief are the same we get from the inventory of favorable and possible cases, or from events occurred in the past.

[Details skipped...]

#### **Basic rules of probability**

- $1. \quad 0 \le P(A \mid \mathbf{I}) \le 1$
- 2.  $P(\Omega \mid \mathbf{I}) = 1$
- 3.  $P(A \cup B \mid \mathbf{I}) = P(A \mid \mathbf{I}) + P(B \mid \mathbf{I}) \quad [\text{ if } P(A \cap B \mid \mathbf{I}) = \emptyset]$
- 4.  $P(A \cap B \mid I) = P(A \mid B, I) \cdot P(B \mid I) = P(B \mid A, I) \cdot P(A \mid I)$

Remember that probability is always conditional probability! *I* is the background condition (related to information ' $I'_s$ )  $\rightarrow$  usually implicit (we only care on 're-conditioning')

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Remember that probability is always conditional probability!

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- $\rightarrow$  usually implicit (we only care on 're-conditioning')
- Note: 4. <u>does not</u> define conditional probability. (Probability is always conditional probability!)

#### **Mathematics of beliefs**

An even better news:

# The fourth basic rule can be fully exploided!

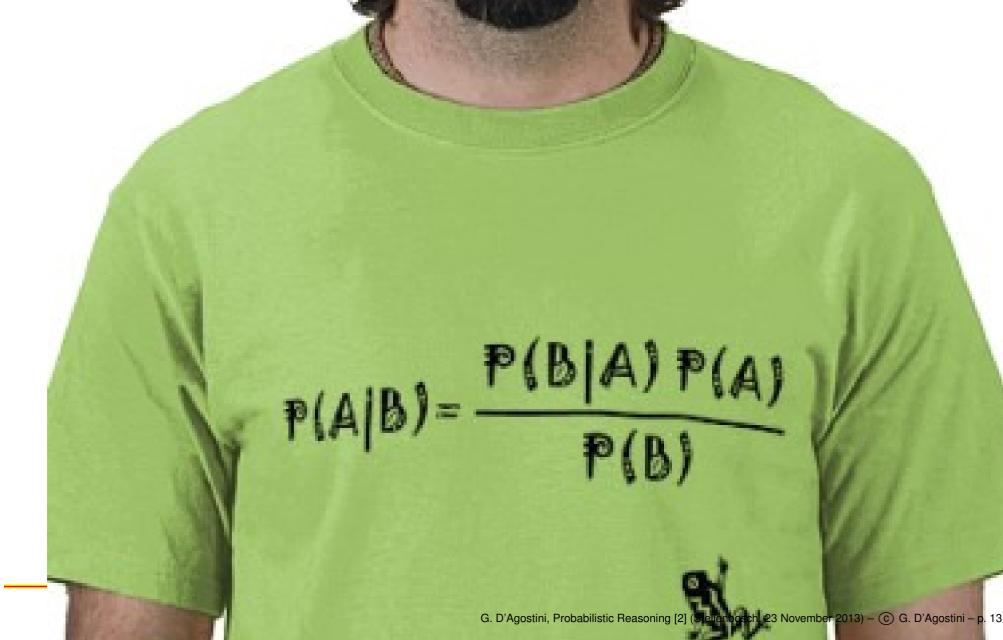
#### **Mathematics of beliefs**

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# The fourth basic rule can be fully exploided!

(Liberated by a curious ideology that forbits its use)

#### A simple, powerful formula



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 $P(A \mid B \mid I) P(B \mid I) = P(B \mid A, I) P(A \mid I)$   $P(A \mid B) = \frac{P(B \mid A) P(A)}{P(B)}$ 

#### A simple, powerful formula

# $P(A|B) = \frac{P(B|A) P(A)}{P(B)}$ $P(A|B) = \frac{P(B|A) P(A)}{P(B)}$ P(B)Take the courage to use it!

# A simple, powerful formula

# $P(A|B) = \frac{P(B|A) P(A)}{P(B)}$ P(B) It's easy if you try.

# Telling it with Gauss' words

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$$P(C_i | \text{data}) = \frac{P(\text{data} | C_i)}{P(\text{data})} P_0(C_i)$$

"post illa observationes" "ante illa observationes" (Gauss)

$$\frac{P(C_i \mid E, I)}{P(C_i \mid I)} = \frac{P(E \mid C_i, I)}{P(E \mid I)}$$

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$$P(C_i \mid E, I) \propto P(E \mid C_i, I) \cdot P(C_i \mid I)$$

The essence is all contained in the fourth basic rule of probability theory:

$$\frac{P(C_i \mid E, I)}{P(C_i \mid I)} = \frac{P(E \mid C_i, I)}{P(E \mid I)}$$

$$P(C_i \mid E, I) = \frac{P(E \mid C_j, I)}{P(E \mid I)} P(C_i \mid I)$$

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$$P(C_i \mid E, I) \propto P(E \mid C_i, I) \cdot P(C_i \mid I)$$

or even (my preferred form to grasp its meaning):

$P(C_i \mid E \mid I)$	$P(E \mid C_i \mid I)$	$P(C_i \mid I)$
$\overline{P(C_j \mid E \mid I)}  -$	$\overline{P(E \mid C_j \mid I)}$	$\overline{P(C_j \mid I)}$

# **Bayesian parametric inference**

If we want to infer a continuous parameter *p* from a set of data

 $\rightarrow\,$  straghtforwad extension to probability density functions (pdf)

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 $f(p \mid \text{data}, I) \propto f(\text{data} \mid p, I) \cdot f(p \mid I)$ 

# **Bayesian parametric inference**

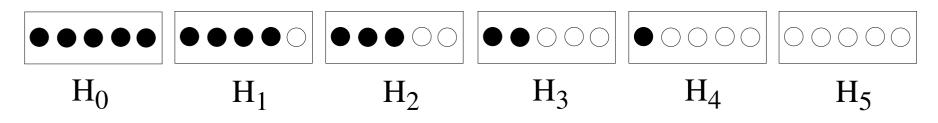
If we want to infer a continuous parameter *p* from a set of data

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$$f(p \mid \text{data}, I) \propto f(\text{data} \mid p, I) \cdot f(p \mid I)$$

$$f(p \mid \text{data}, I) = \frac{f(\text{data} \mid p, I) \cdot f(p \mid I)}{\int_{p} f(\text{data} \mid p, I) \cdot f(p \mid I) \, dp}$$

# Application to the six box problem



### Remind:

- $E_1 = White$
- $E_2 = \mathsf{Black}$

$$P(H_j | E_i, I) = \frac{P(E_i | H_j, I)}{P(E_i | I)} P(H_j | I)$$

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•  $P(E_i | I) = 1/2$   
•  $P(E_i | H_j, I)$  :  
•  $P(E_1 | H_j, I) = j/5$   
•  $P(E_2 | H_j, I) = (5-j)/5$ 

Our tool:

$$P(H_j | E_i, I) = \frac{P(E_i | H_j, I)}{P(E_i | I)} P(H_j | I)$$

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-Our prior belief about  $H_j$ 

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- Probability of  $E_i$  under a well defined hypothesis  $H_j$ It corresponds to the 'response of the apparatus in measurements.

 $\rightarrow$  likelihood (traditional, rather confusing name!)

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- Probability of  $E_i$  taking account all possible  $H_j$  $\rightarrow$  How much we are confident that  $E_i$  will occur.

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- Probability of  $E_i$  taking account all possible  $H_j$   $\rightarrow$  How much we are confident that  $E_i$  will occur. We can rewrite it as  $P(E_i | I) = \sum_j P(E_i | H_j, I) \cdot P(H_j | I)$ 

# We are ready

Now that we have set up our formalism, let's play a little

- analyse real data
- some simulations

Then

- $I \hspace{0.1cm} I \hspace{0.1cm} \longmapsto j \hspace{0.1cm} \longleftrightarrow \hspace{0.1cm} p_{j}$
- $\bullet$  extending p to a continuum:
  - $\Rightarrow$  Bayes' billiard

(prototype for all questions related to efficiencies, branching ratios)

• On the meaning of p

# Which box? Which ball?

Inferential/forecasting history:

- **1.** k = 0 $P_0(H_j) = P(H_j | I_0)$  (priors)
- 2. begin loop:
  - k = k + 1 $\Rightarrow E^{(k)}$  (k-th extraction)
- **3.**  $P_k(H_j | I_k) \propto P(E^{(k)} | H_j) \times P_{k-1}(H_j | I_k)$

 $P_k(E_i \mid I_k) = \sum_j P(E_i \mid H_j) \cdot P_k(H_j \mid I_k)$ 4.  $\rightarrow$  go to 2

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### 4. $\rightarrow$ go to 2

# Let's play!

# **Bayes' billiard**

This is the original problem in the theory of chances solved by Thomas Bayes in late '700:

- imagine you roll a ball at random on a billiard;
- you mark the relative position of the ball along the billiard's length (l/L) and remove the ball
- then you roll at random other balls
  - write down if it stopped left or right of the first ball;
  - remove it and go on with n balls.
- Somebody has to guess the position of the first ball knowing only how mane balls stopped left and how many stoppe right

It is easy to recongnize the analogy:

- Left/Right  $\rightarrow$  Success/Failure
- if Left  $\leftrightarrow$  Success:
  - $l/L \leftrightarrow p$  of binomial (Bernoulli trials)

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$$f(p \mid S, S, F) \propto f(F \mid p) \cdot f(p \mid S, S) = p^{2}(1-p)$$

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- $\textbf{ Left/Right} \rightarrow \textbf{Success/Failure}$
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$$\begin{aligned} f(p \mid S) &\propto f(S \mid p) = p \\ f(p \mid S, S) &\propto f(S \mid p) \cdot f(p \mid S) = p^2 \\ f(p \mid S, S, F) &\propto f(F \mid p) \cdot f(p \mid S, S) = p^2 (1 - p) \\ & \dots \\ f(p \mid \#S, \#F) &\propto p^{\#S} (1 - p)^{\#F} = p^{\#S} (1 - p)^{(1 - \#S)} \end{aligned}$$

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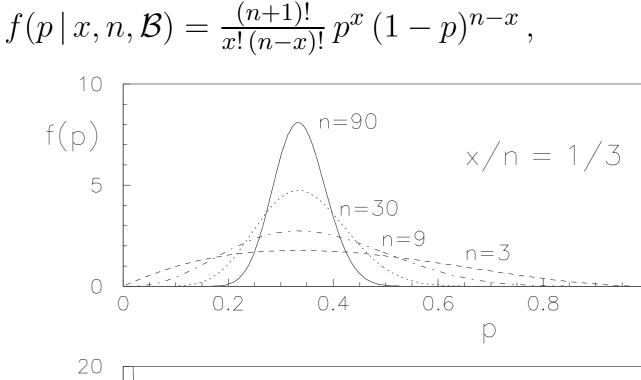
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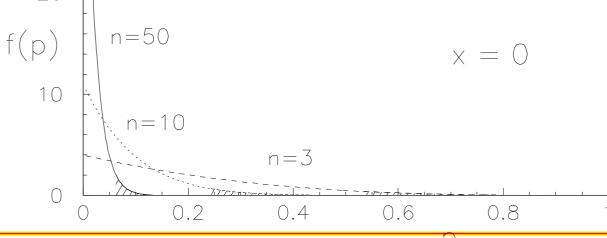
Solution with modern notation: Imagine a sequence  $\{S, S, F, S, ...\}$  [ $f_0$  is uniform]:

 $f(p \mid S) \propto f(S \mid p) = p$   $f(p \mid S, S) \propto f(S \mid p) \cdot f(p \mid S) = p^{2}$   $f(p \mid S, S, F) \propto f(F \mid p) \cdot f(p \mid S, S) = p^{2}(1-p)$ ....  $f(p \mid \#S, \#F) \propto p^{\#S}(1-p)^{\#F} = p^{\#S}(1-p)^{(1-\#s)}$ 

 $f(p | x, n) \propto p^{x} (1-p)^{(n-x)} \qquad [x = \#S]$ 

# Inferring the Binomial p





# Inferring the Binomial p

$$f(p \mid x, n, \mathcal{B}) = \frac{(n+1)!}{x! (n-x)!} p^x (1-p)^{n-x},$$

$$E(p) = \frac{x+1}{n+2}$$
Laplace's rule of successions
$$Var(p) = \frac{(x+1)(n-x+1)}{(n+3)(n+2)^2}$$

$$= E(p) (1 - E(p)) \frac{1}{n+3}.$$

# Interpretation of $\mathbf{E}(p)$

Think at any future event  $E_{i>n}$  $\Rightarrow$  if we were sure of p, then our confidence on  $E_{i>n}$  will be exactly p, i.e.

 $P(E_i \mid p) = p.$ 

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But we are uncertain about *p*. How much should we believe  $E_{i>n}$ ?

$$P(E_{i>n} | x, n, \mathcal{B}) = \int_0^1 P(E_i | p) f(p | x, n, \mathcal{B}) dp$$
  
= 
$$\int_0^1 p f(p | x, n, \mathcal{B}) dp$$
  
= 
$$\mathbf{E}(p)$$
  
= 
$$\frac{x+1}{n+2}$$
 (for uniform prior).

## From frequencies to probabilities

$$E(p) = \frac{x+1}{n+2}$$
Laplace's rule of successions
$$Var(p) = E(p) (1 - E(p)) \frac{1}{n+3}.$$

For 'large' n, x and n - x: asymptotic behaviors of f(p):

$$\begin{aligned} \mathsf{E}(p) &\approx p_m = \frac{x}{n} \quad [\text{with } p_m \text{ mode of } f(p) \\ \sigma_p &\approx \sqrt{\frac{p_m \left(1 - p_m\right)}{n}} \xrightarrow[n \to \infty]{} 0 \\ p &\sim \mathcal{N}(p_m, \sigma_p) \,. \end{aligned}$$

Under these conditions the frequentistic "definition" (evaluation rule!) of probability (x/n) is recovered.

$$f(p \mid 0, n, \mathcal{B}) = (n+1)(1-p)^n$$

$$F(p \mid 0, n, \mathcal{B}) = 1 - (1-p)^{n+1}$$

$$p_m = 0$$

$$\mathsf{E}(p) = \frac{1}{n+2} \longrightarrow \frac{1}{n}$$

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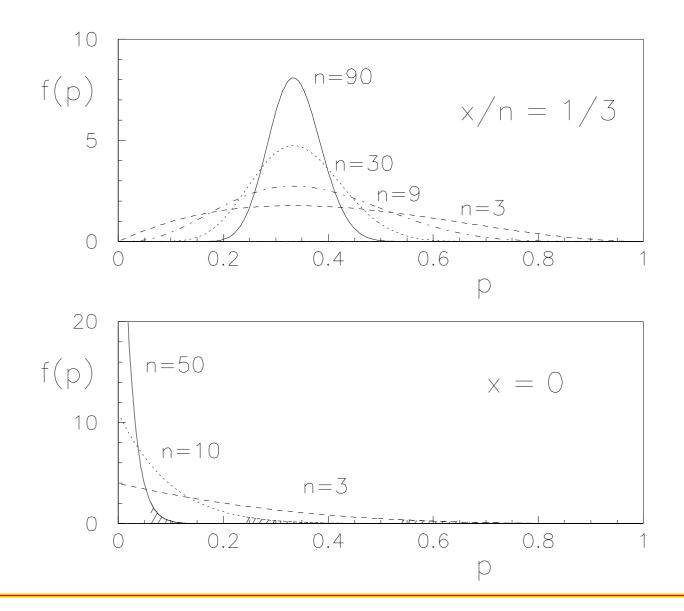
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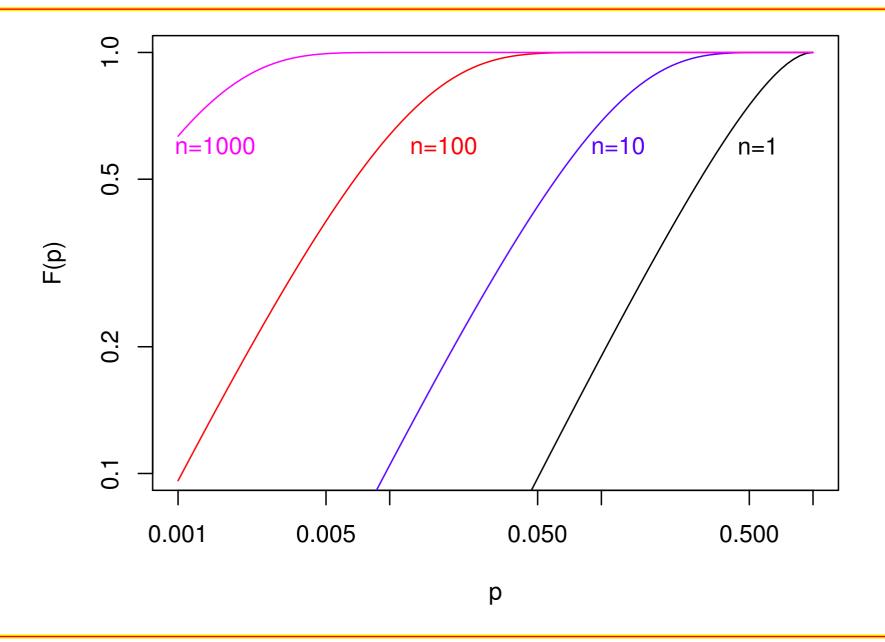
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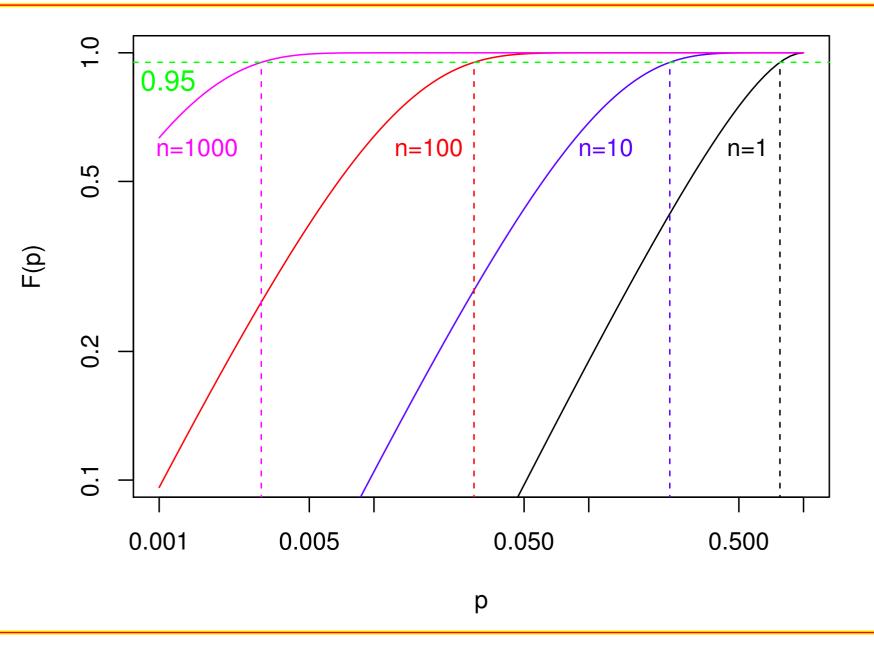
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$$P(p \le p_u | 0, n, \mathcal{B}) = 95\%$$
  
 $\Rightarrow p_u = 1 - \sqrt[n+1]{0.05} :$ 

Probabilistic upper bound







For the case x = n(like 'observing' a 100% efficiency):

 $\rightarrow$  just reason on the complementary parameter

$$q = 1 - p$$

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 (Diffidate chi vi promette di far germogliar zecchini nel Campo dei Miracoli! – Pinocchio docet)

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