

Proposed exercise

Extract  $N$  random numbers distributed as an exponential function with lifetime  $\tau$

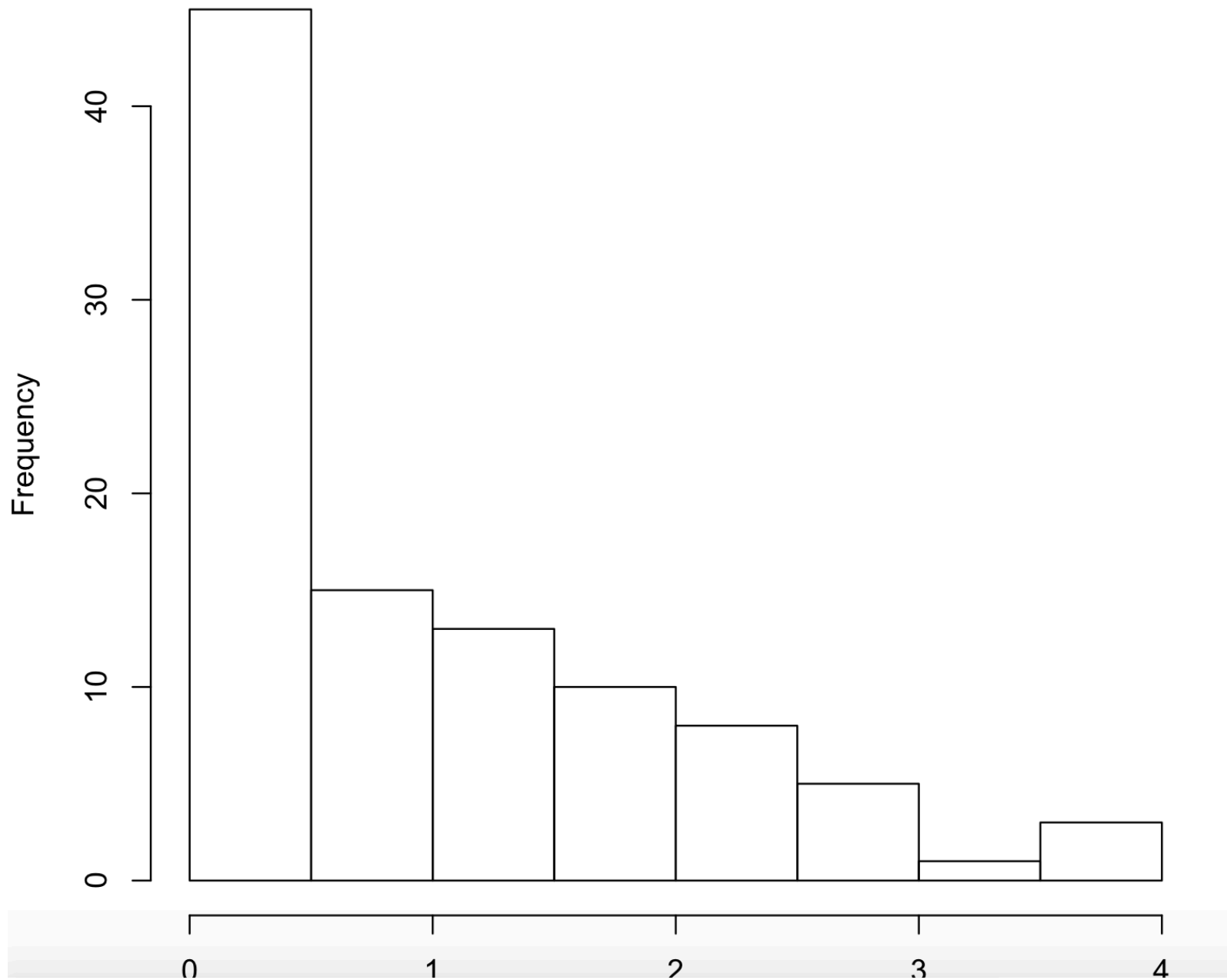
Fill an histogram

Write the likelihood in the  $L(t|\tau)$  in the binned and unbinned case

```
N=100; x<-runif(N) ; x
```

```
[1] 0.405059710 0.028044254 0.758571449 0.382914253 0.231949128 0.457176317  
[7] 0.736658152 0.038088207 0.104203774 0.513283288 0.742335360 0.368812945  
[13] 0.898926650 0.884993284 0.029905424 0.510855547 0.976764989 0.163296696  
[19] 0.312905139 0.172199152 0.789298260 0.518792378 0.076755612 0.187093519  
[25] 0.613189997 0.007589616 0.476067148 0.091391122 0.254679165 0.642145047  
[31] 0.068187724 0.213190998 0.284391620 0.652574104 0.375936000 0.938753973  
[37] 0.768648992 0.934079373 0.576549295 0.822300084 0.963397188 0.677318145  
[43] 0.804149516 0.278122875 0.918408046 0.161690666 0.816283114 0.219679127  
[49] 0.247514679 0.144359027 0.238819577 0.499138632 0.801599954 0.882881265  
[55] 0.817341159 0.484859340 0.865183191 0.866059658 0.375084123 0.287952191  
[61] 0.832247817 0.392507337 0.292606502 0.018239798 0.980023583 0.892270450  
[67] 0.843237637 0.927634800 0.204098272 0.763523759 0.545941953 0.600462520  
[73] 0.078878091 0.445519178 0.375912647 0.614324038 0.194723071 0.839467755  
[79] 0.265073122 0.870599505 0.696728359 0.085964346 0.004559065 0.710412472  
[85] 0.824518329 0.868817609 0.730170102 0.016328960 0.087571226 0.173662371  
[91] 0.367700928 0.491316323 0.085512807 0.738371863 0.977629644 0.378448315  
[97] 0.194459494 0.754219429 0.376693783 0.939928670
```

Histogram of  $-\log((1 - x))$



## Rate measurement

$$L(\underline{n}/\lambda) = \prod_{i=1}^N \frac{e^{-\lambda} \lambda^{n_i}}{n_i!}$$

$$\ln L = \sum_{i=1}^N (-\lambda + n_i \ln \lambda - \ln n_i!)$$

$$\frac{\partial \ln L}{\partial \lambda} = -N + \sum_{i=1}^N \frac{n_i}{\lambda}$$

$$-\frac{\partial^2 \ln L}{\partial \lambda^2} \Big|_{\lambda=\hat{\lambda}} = \frac{\sum_{i=1}^N n_i}{\lambda^2}$$

$$\hat{\lambda} = \frac{\sum_{i=1}^N n_i}{N}$$

$$\text{Var}[\hat{\lambda}] = \frac{\hat{\lambda}^2}{\sum_{i=1}^N n_i} = \frac{\hat{\lambda}}{N}$$

$$\hat{r} = \frac{\hat{\lambda}}{\Delta t} \pm \frac{\sqrt{\hat{\lambda}}}{\sqrt{N \Delta t}}$$

Lifetime measurement

$$L(\underline{t}/\tau) = \prod_{i=1}^N \frac{1}{\tau} e^{-t_i/\tau}$$

$$\ln L = \sum_{i=1}^N \left( -\ln \tau - \frac{t_i}{\tau} \right)$$

$$\frac{\partial \ln L}{\partial \tau} = -\frac{N}{\tau} + \frac{1}{\tau^2} \sum_{i=1}^N t_i$$

$$-\frac{\partial^2 \ln L}{\partial \tau^2} \Big|_{\tau=\hat{\tau}} = -\frac{1}{\hat{\tau}^2} \left( N - 2 \frac{\sum_{i=1}^N t_i}{\hat{\tau}} \right) = \frac{N}{\hat{\tau}^2}$$

$$\hat{\tau} = \frac{\sum_{i=1}^N t_i}{N}$$

$$Var[\hat{\tau}] = -\hat{\tau}^2 \frac{1}{N - 2N} = \frac{\hat{\tau}^2}{N}$$

Gaussian measurement

$$L(\underline{x}/\mu, \sigma) = \prod_{i=1}^N \frac{1}{\sqrt{2\pi\sigma_i}} e^{-\frac{(x_i - \mu)^2}{2\sigma_i^2}}$$

Estimate  $\mu$ , known  $\sigma$

$$\frac{\partial \ln L}{\partial \mu} = \sum_i \frac{(x_i - \mu)}{\sigma_i^2}$$

$$-\frac{\partial^2 \ln L}{\partial \mu^2} = \sum_i \frac{1}{\sigma_i^2}$$

$$\hat{\mu} = \frac{\sum_i \frac{x_i}{\sigma_i^2}}{\sum_i \frac{1}{\sigma_i^2}}$$

$$\text{Var}[\hat{\mu}] = \frac{1}{\sum_i \frac{1}{\sigma_i^2}}$$

Gaussian measurement

$$L(\underline{x}/\mu, \sigma) = \prod_{i=1}^N \frac{1}{\sqrt{2\pi}\sigma_i} e^{-\frac{(x_i - \mu)^2}{2\sigma_i^2}}$$

Estimate  $\sigma$ , known  $\mu$

$$\begin{aligned} \frac{\partial \ln L}{\partial \sigma} &= -\frac{N}{\sigma} + \frac{\sum_i (x_i - \mu)^2}{\sigma^3} \\ + \frac{\partial^2 \ln L}{\partial \sigma^2} &= \frac{N}{\sigma^2} - 3 \frac{\sum_i (x_i - \mu)^2}{\sigma^4} \end{aligned}$$

$$\hat{\sigma}^2 = \frac{\sum_i (x_i - \mu)^2}{N}$$

$$\text{Var}[\hat{\sigma}] = \frac{\hat{\sigma}^2}{2N}$$

## Linear fit

- each measurement of  $y_i$  is characterized by a gaussian pdf with a known variance  $\sigma_i^2$ ;
- the  $x_i$  values are assumed to be known with no or negligible uncertainty<sup>26</sup>;  
( $\sigma(x_i) \ll \sigma(y_i)/\hat{m}$ )
- the  $y_i$  measurements are not correlated;
- we make the hypothesis that the two physics quantities  $y$  and  $x$  are related by

$$y = mx + c$$

where  $m$  (the slope) and  $c$  (the intercept) are free parameters we want to measure from the data.

$$L(\underline{y}/m, c) = \prod_{i=1}^N \frac{1}{\sqrt{2\pi}\sigma_i} e^{-\frac{(y_i - mx_i - c)^2}{2\sigma_i^2}}$$

$$-2 \ln(L) = \chi^2 = \sum_{i=1}^N \frac{(y_i - mx_i - c)^2}{\sigma_i^2}$$

that we have called  $\chi^2$  since, within the hypotheses done and discussed above, it is a test statistics with a  $\hat{\chi}^2$  pdf with  $N - 2$  degrees of freedom.



Linear fit

Minimizing  $X^2$

$$\overline{x^2}m + \bar{x}c = \overline{xy}$$

$$\bar{x}m + c = \bar{y}$$

$$\bar{z} = \frac{\sum_{i=1}^N \frac{z_i}{\sigma_i^2}}{\sum_{i=1}^N \frac{1}{\sigma_i^2}}$$

$$\hat{m} = \frac{\overline{xy} - \bar{x} \cdot \bar{y}}{\overline{x^2} - \bar{x}^2}$$

$$\hat{c} = \frac{\overline{x^2} \cdot \bar{y} - \bar{x} \cdot \overline{xy}}{\overline{x^2} - \bar{x}^2}$$

## Linear fit

The covariance matrix of the 2 parameters is determined evaluating first the Hessian matrix (see eq.125), and by inverting it with the usual methods of matrix inversions. The Fisher matrix is:

$$\begin{pmatrix} \sum_i \frac{x_i^2}{\sigma_i^2} & \sum_i \frac{x_i}{\sigma_i^2} \\ \sum_i \frac{x_i}{\sigma_i^2} & \sum_i \frac{1}{\sigma_i^2} \end{pmatrix}$$

and the covariance matrix is:

$$\begin{pmatrix} \frac{1}{\sum_i (1/\sigma_i^2) Var[x]} & \frac{-\bar{x}}{\sum_i (1/\sigma_i^2) Var[x]} \\ \frac{-\bar{x}}{\sum_i (1/\sigma_i^2) Var[x]} & \frac{x^2}{\sum_i (1/\sigma_i^2) Var[x]} \end{pmatrix}$$

where the variance of  $x$  is not the uncertainty on  $x$  but the lever arm of the fit, namely the spread of the  $x$  values on the  $x$  axis.

$$\begin{aligned} \sigma(\hat{m}) &= \frac{\sigma}{\sqrt{N} \sqrt{Var[x]}} \\ \sigma(\hat{c}) &= \frac{\sqrt{\bar{x}^2} \sigma}{\sqrt{N} \sqrt{Var[x]}} \\ cov(\hat{m}, \hat{c}) &= -\frac{\sqrt{\bar{x}} \sigma}{\sqrt{N} \sqrt{Var[x]}} \end{aligned}$$

Generic linear fit

$$y = f(x/\underline{\theta}) = \sum_{k=1}^M \theta_k f_k(x)$$

$$\chi^2 = \sum_{i=1}^N \frac{(y_i - \sum_k \theta_k f_k(x_i))^2}{\sigma_i^2} = -2\ln L$$

M equations

$$\frac{\partial \chi^2}{\partial \theta_j} = \sum_i \frac{-2f_j(x_i)(y_i - \sum_k \theta_k f_k(x_i))}{\sigma_i^2} = 0$$

$$\sum_k \left[ \sum_i \frac{f_j(x_i) f_k(x_i)}{\sigma_i^2} \right] \theta_k = \sum_i \frac{y_i f_j(x_i)}{\sigma_i^2}$$

$$\hat{\theta}_k = \sum_i \sum_j V_{kj} \frac{y_i f_j(x_i)}{\sigma_i^2}$$

## Generic linear fit

$i$  runs on events  
 $j, k$  on coefficients

$$\hat{\theta}_k = \sum_i \sum_j V_{kj} \frac{y_i f_j(x_i)}{\sigma_i^2}$$

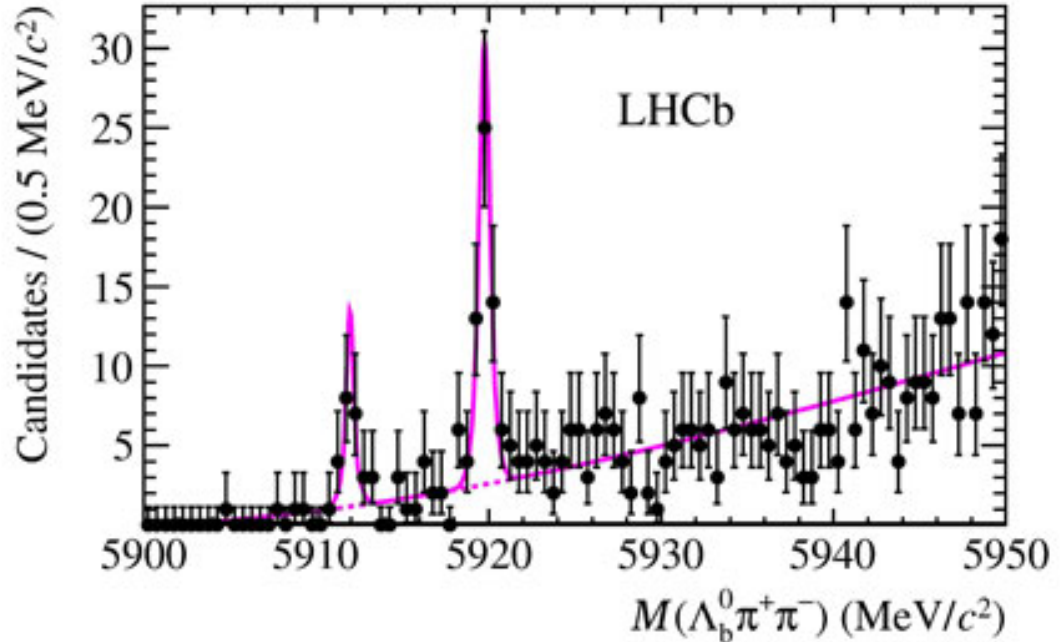
$V_{kj}$  covariance matrix of the parameters

Parameter coefficient  
matrix

$$(V^{-1})_{kj} = \sum_i \frac{f_k(x_i) f_j(x_i)}{\sigma_i^2}$$

Analytical solution

## Nuisance parameters



We define<sup>28</sup>  $N_s$  and  $N_b$  the total number of signal and background events respectively,  $f_s(x/M)$  and  $f_b(x/\underline{\alpha})$  the two functions of the mass  $x$  describing the signal and background respectively.  $f_s$  is assumed to be gaussian with mean  $M$  and a width  $\sigma$  assumed to be known<sup>29</sup>:

$$(184) \quad f_s(x/M) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-M)^2}{2\sigma^2}}$$

$f_b$  is assumed to be a polynomial function<sup>30</sup>,  $\underline{\alpha}$  being the vector of parameters describing the polynomial background (together with  $N_b$ ). Both functions are normalized to 1. The parameters describing the background are free parameters and have to be evaluated by the fit or have to be known independently (e.g. from Montecarlo). However, since they have not a deep physical meaning they are called generically **nuisance parameters**. On the other hand  $N_s$  and  $M$  are the parameters we are interested in.

## Nuisance parameters

Let's consider first the unbinned case. The test statistics can be written as an extended likelihood ( $N$  is the number of events entering the histogram):

$$L(\underline{x}/N_s, N_b, M, \underline{\alpha}) = \frac{e^{-(N_s+N_b)} (N_s + N_b)^N}{N!} \prod_{i=1}^N [N_s f_s(x_i/M) + N_b f_b(x_i/\underline{\alpha})]$$

For the histogram fit we have to define the signal and background contents  $s_i$  and  $b_i$  in each of the  $M$  bins of width  $\delta x$ :

$$s_i = N_s \int_{\bar{x}_i - \delta x/2}^{\bar{x}_i + \delta x/2} f_s(x/M) dx$$
$$b_i = N_b \int_{\bar{x}_i - \delta x/2}^{\bar{x}_i + \delta x/2} f_b(x/\underline{\alpha}) dx$$

$$L(\underline{n}/N_s, N_b, M, \underline{\alpha}) = \prod_{i=1}^M \frac{e^{-(s_i+b_i)} (s_i + b_i)^{n_i}}{n_i!}$$

where  $n_i$  is the experimental content in the bin  $i$ .

## Nuisance parameters

In both cases the minimization and the evaluation of the hessian matrix of this likelihood will be done numerically. As a result we'll have estimates of the 2 relevant parameters  $N_s$  and  $M$  and of the nuisance parameters. Moreover the value of  $L$  at the minimum will be used for hypothesis test.

The possibility to move the nuisance parameters in the fit, allows to obtain a better agreement between data and theory at the expense of having larger uncertainties on the relevant parameters  $N_s$  and  $M$ . Any knowledge of the nuisance parameters can be added in the likelihood as additional constraint. For example if  $N_b$  is known to be  $\bar{N}_b \pm \sigma(N_b)$  with a gaussian shape, an additional gaussian factor can be added to the likelihood forcing  $N_b$  to stay within its gaussian limits. The lower is  $\sigma(N_b)$  the lower will be its impact on the final uncertainties on  $N_s$  and  $M$ . From this example we see that the method of the nuisance parameters can be used to include the evaluation of systematic uncertainties directly in the fit.

## Proposed exercise

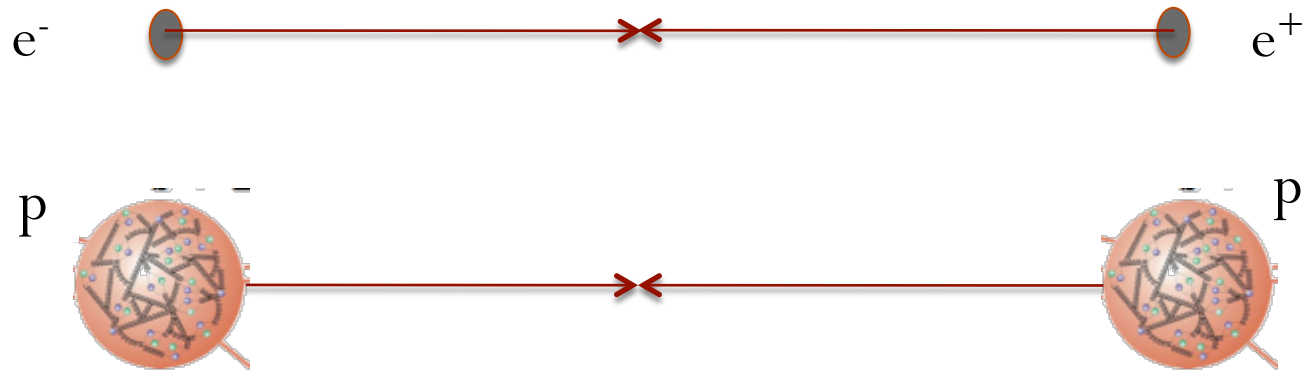
$X = -0.6, -0.2, 0.2, 0.6$

$Y(X) = 5 \pm 2, 3 \pm 1, 5 \pm 1, 8 \pm 2$

- 1) Find the best fit for  $Y(X) = a + bX + cX^2$
- 2) Find the best estimate for  $Y(1)$
- 3) Find the uncertainty of the best estimate for  $Y(1)$
- 4) Find the p-value for the best fit
- 5) Find the best fit and p-value for  $Y(X) = a + bX$



# Hadron colliders



The proton is a complex object done by “partons”:

*valence quarks / sea quarks / gluons*

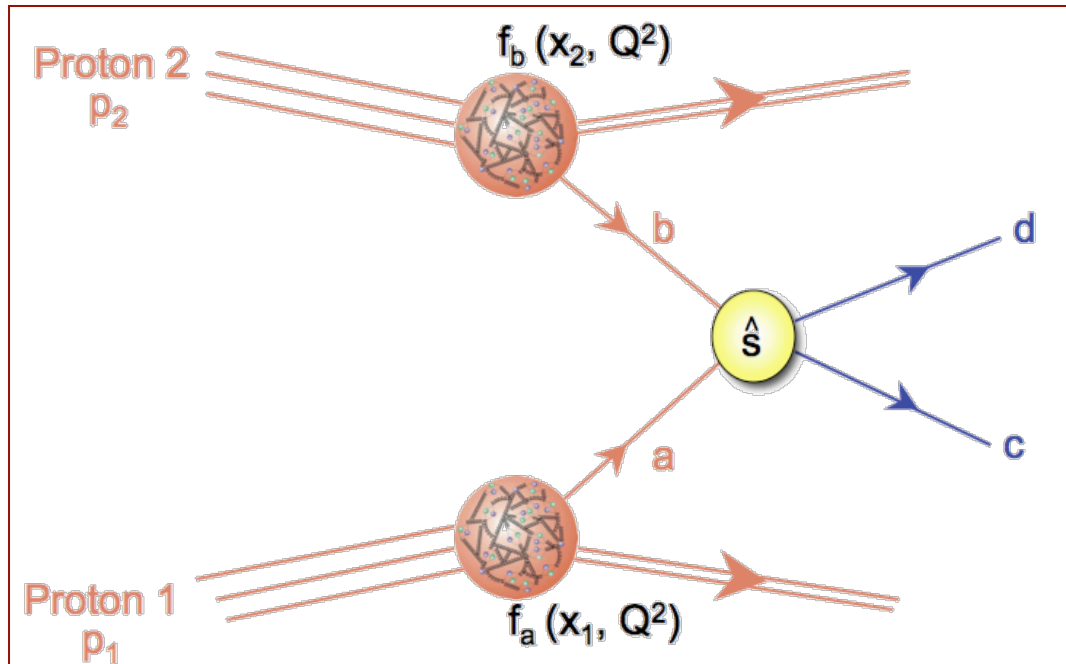
$$s = (\text{center of mass energy of interaction})^2$$

$$\hat{s} = (\text{center of mass energy of elementary interaction})^2$$

$e^+e^-$ : interactions btw point-like particles with  $\sqrt{\hat{s}} \approx \sqrt{s}$

pp: interactions btw point-like partons with  $\sqrt{\hat{s}} \ll \sqrt{s}$

Parton-parton collision:  $a+b \rightarrow d+c$ .



$a, b$  = quarks or gluons;  
 $d, c$  = quarks, gluons, or leptons, vector bosons, ...;  
 $x$  = fraction of proton momentum carried by each parton;  
 $\hat{s}$  = parton-parton c.o.m. energy =  $x_1 x_2 s$  (see later);

Theoretical method: the *factorization theorem*

$$d\sigma(pp \rightarrow cd) = \int_0^1 dx_1 dx_2 \sum_{a,b} f_a(x_1, Q^2) f_b(x_2, Q^2) d\hat{\sigma}(ab \rightarrow cd)$$

Two ingredients to predict pp cross-sections:

→ proton pdfs ( $f_a$  and  $f_b$ )

→  $\hat{\sigma}$  “fundamental process” cross-section

# parton-parton collisions – let's define the relevant variables

- Parton momentum fractions:  $x_1$  and  $x_2$

- Assume no transverse momentum
- Assume proton mass negligible

$$p_1 = x_1 P_1 = x_1 \frac{\sqrt{s}}{2} (1, 0, 0, 1)$$

$$p_2 = x_2 P_2 = x_2 \frac{\sqrt{s}}{2} (1, 0, 0, -1)$$

$$\hat{s} = (p_1 + p_2)^2 = x_1 x_2 s$$

- Rapidity: I evaluate the “velocity” of the parton system in the Lab frame:

- It measures how fast the parton c.o.m. frame moves along z

$$\beta = \frac{p_z}{E} = \frac{(p_1 + p_2)_z}{(p_1 + p_2)_E} = \frac{x_1 - x_2}{x_1 + x_2}$$

$$y = \frac{1}{2} \ln \frac{E + p_z}{E - p_z} = \frac{1}{2} \ln \frac{1 + \beta}{1 - \beta} = \frac{1}{2} \ln \frac{x_1}{x_2}$$

- Relation between parton rapidity and each single x:

$$x_1 = \sqrt{\frac{\hat{s}}{s}} e^y$$

$$x_2 = \sqrt{\frac{\hat{s}}{s}} e^{-y}$$

# Rapidity limit for a resonance of mass M

- Suppose that we want to produce in a partonic interaction a resonance of mass M then decaying to a given final state (e.g.  $pp \rightarrow Z+X$  with  $Z \rightarrow \mu\mu$ ). Limits in x and y of the collision ?

- Completely symmetric case:  $x_1 = x_2 = x$

$$x^2 = \frac{M^2}{s}; x = \sqrt{\frac{M^2}{s}}; e^y = 1; y = 0$$

- Maximally asymmetric case:  $x_1 = 1, x_2 = x_{\min}$

$$x_1 = 1; x_2 = x_{\min} = \frac{M^2}{s}; y_{\max} = \frac{1}{2} \ln \frac{s}{M^2}$$

- Z production at LHC, Tevatron and SpS

	LHC (14 TeV)	Tevatron (1.96 TeV)	SpS (560 GeV)
$x_{\min}$	$4.2 \times 10^{-5}$	$2.1 \times 10^{-3}$	0.026
$y_{\max}$	5.03	3.07	1.82

# The $x$ - $Q^2$ plane

- $x - Q^2$  plane ( $Q^2=M^2=\hat{s}$ ) c.o.m. energy of parton interaction.  
LHC vs. previous experiments showing where PDF are needed to interpret LHC results.
- NB pp vs. ppbar  
ppbar  $\approx$  qqbar collider  
pp  $\approx$  gluon collider

