

Observables in EPP

Quantities to be measured in EPP

- *Physics quantities* (to be compared with theory expectations)
 - Cross-section
 - Branching ratio
 - Asymmetries
 - Particle Masses, Widths and Lifetimes
- *Quantities related to the experiment* (BUT to be measured to get physics quantities)
 - Efficiencies
 - Luminosity
 - Backgrounds

Cross-section - I

- Suppose we have done an experiment and obtained the following quantities for a given final state:

- $N_{cand}, N_b, \epsilon, \phi$

- What is ϕ ? It is the “**flux**”, something telling us how many collisions could take place per unit of time and surface.

- Consider a “**fixed-target**” experiment (transverse size of the target \gg beam dimensions):

$$\phi = \dot{N}_{proj} N_{tar} \delta x = \frac{\dot{N}_{proj} \rho \delta x}{A m_N} = \frac{\dot{N}_{proj} \rho (g / cm^3) N_A \delta x (cm)}{A}$$

- Consider a “**colliding beam**” experiment

$$\phi = f_{coll} \frac{N_1 N_2}{4\pi \Sigma_X \Sigma_Y} = L$$

(head-on beams: N_1 and N_2 number of particles per beam, Σ_X, Σ_Y beam transverse gaussian areas, f_{coll} collision frequency) In this case we normally use the word “**Luminosity**”. Flux or luminosity are measured in: **$cm^{-2}s^{-1}$**

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- Consider a “**colliding beam**” experiment

$$\Rightarrow \phi = f_{coll} \frac{N_1 N_2}{4\pi \Sigma_X \Sigma_Y} \frac{1}{n_b} = L \quad L = f_{coll} n_b \frac{n_1 n_2}{4\pi \Sigma_X \Sigma_Y}$$

with
 n_1, n_2 number of particles per bunch
 n_b number of bunches

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Cross-section - II

- In any case, the rate of events due to final state X is:

$$\dot{N}_X = \phi \sigma_X$$

- **σ_X is the cross-section**, having the dimension of an area.
 - it doesn't depend on the experiment but on the process only
 - can be compared to the theory
 - for a given σ_X , the higher is ϕ , the larger the event rate
 - given an initial state, for every final state X you have a specific cross-section
 - the “**total cross-section**” is obtained by adding the cross-sections for all possible final states: *the cross-section is an **additive** quantity.*
 - The unit is the “**barn**”. $1 \text{ barn} = 10^{-24} \text{ cm}^2$.

Cross-section - III

- Suppose we have taken data for a time Δt : the total number of events collected will be:

$$N_X = \sigma_X \times \int_{\Delta t} \phi dt$$

The flux integral over time is the *Integrated Flux* or (in case of colliding beams) *Integrated Luminosity*. Integrated luminosity is measured in: \mathbf{b}^{-1}

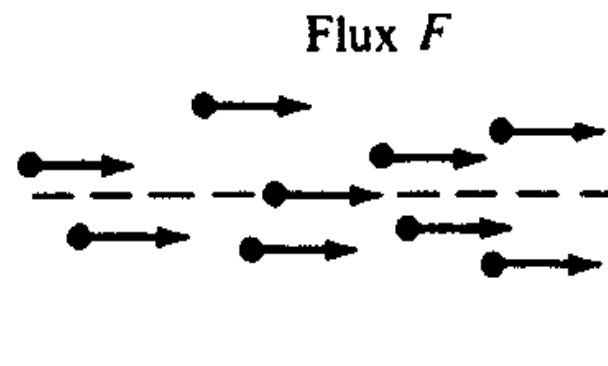
- How can we measure this cross-section ?

$$\sigma_X = \frac{N_X}{\int \phi dt} = \frac{1}{\int \phi dt} \frac{N_{cand} - N_b}{\epsilon}$$

- Sources of uncertainty: we apply the uncertainty propagation formula. We assume no correlations btw the quantities in the formula (L_{int} = integral of flux)

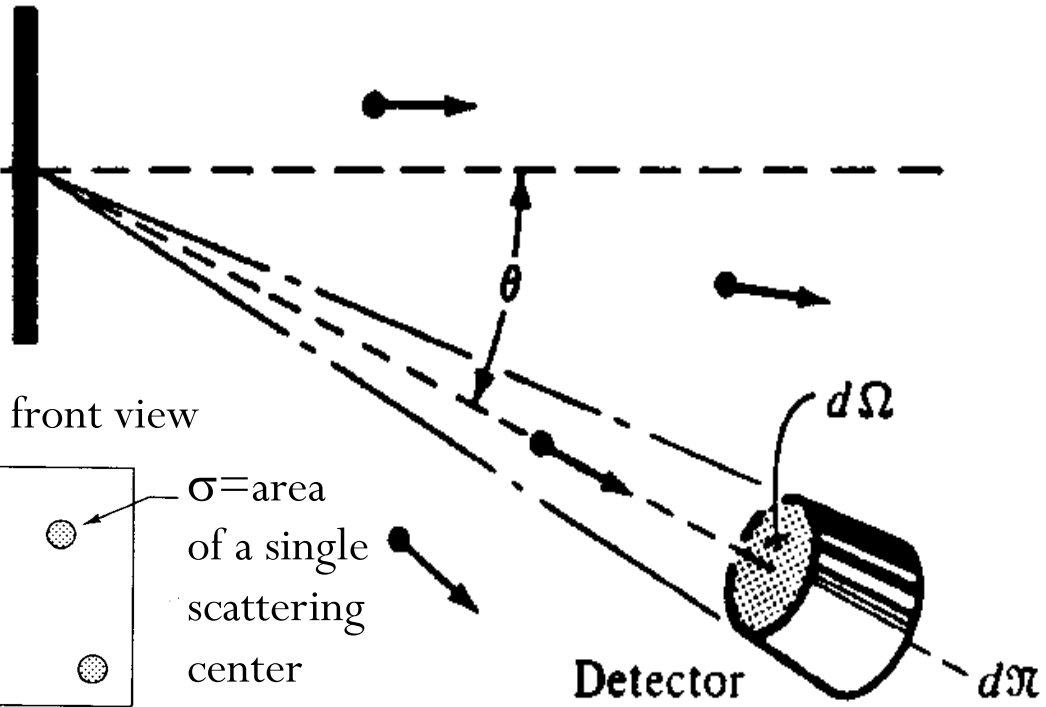
$$\left(\frac{\sigma(\sigma_X)}{\sigma_X} \right)^2 = \left(\frac{\sigma(L_{int})}{L_{int}} \right)^2 + \left(\frac{\sigma(\epsilon)}{\epsilon} \right)^2 + \frac{\sigma^2(N_{cand}) + \sigma^2(N_b)}{(N_{cand} - N_b)^2}$$

Incident
monoenergetic
beam



Target

Scattered beam



$$-dI = I n x \frac{d\sigma}{d\Omega} d\Omega$$

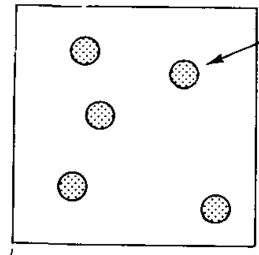
$$\left(-dI = I n x \frac{d\sigma}{dE} dE \right)$$

$$I(x) = I(0) e^{-n\sigma x}$$

$$\sigma = \int_{4\pi} \frac{d\sigma}{d\Omega} d\Omega$$

$$\left(\sigma = \int_0^{E_{MAX}} \frac{d\sigma}{dE} dE \right)$$

Target – front view



σ = area
of a single
scattering
center

x = target thickness

n = density of scattering centers

I = beam intensity

Branching ratio measurement - I

- Given an unstable particle a , it can decay in several (say N) final states, $k=1, \dots, N$. If Γ is the **total width** of the particle ($\Gamma=1/\tau$ with τ particle lifetime), for each final state we define a “**partial width**” in such a way that

$$\Gamma = \sum_{k=1}^N \Gamma_k$$

- The **branching ratio** of the particle a to the final state X is

$$B.R.(a \rightarrow X) = \frac{\Gamma_X}{\Gamma}$$

- To measure the B.R. the same analysis as for a cross-section is needed. In this case we need the number of decaying particles N_a (not the flux) to normalize:

$$B.R.(a \rightarrow X) = \frac{N_{cand} - N_b}{\epsilon} \frac{1}{N_a}$$

Branching ratio measurement - II

- Sometimes the normalization is done relative to another process of known B.R. (relative measurement):

$$\frac{B.R.(a \rightarrow X)}{B.R.(a \rightarrow Y)} = \left(\frac{N_{cand,X} - N_{b,X}}{N_{cand,Y} - N_{b,Y}} \right) \left(\frac{\epsilon_Y}{\epsilon_X} \right)$$

Differential cross-section - I

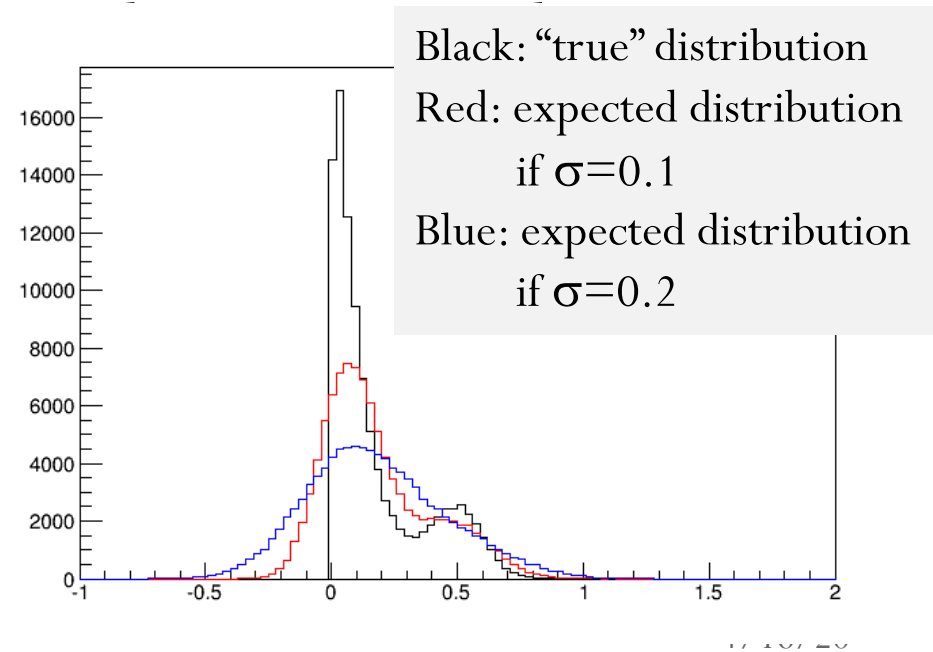
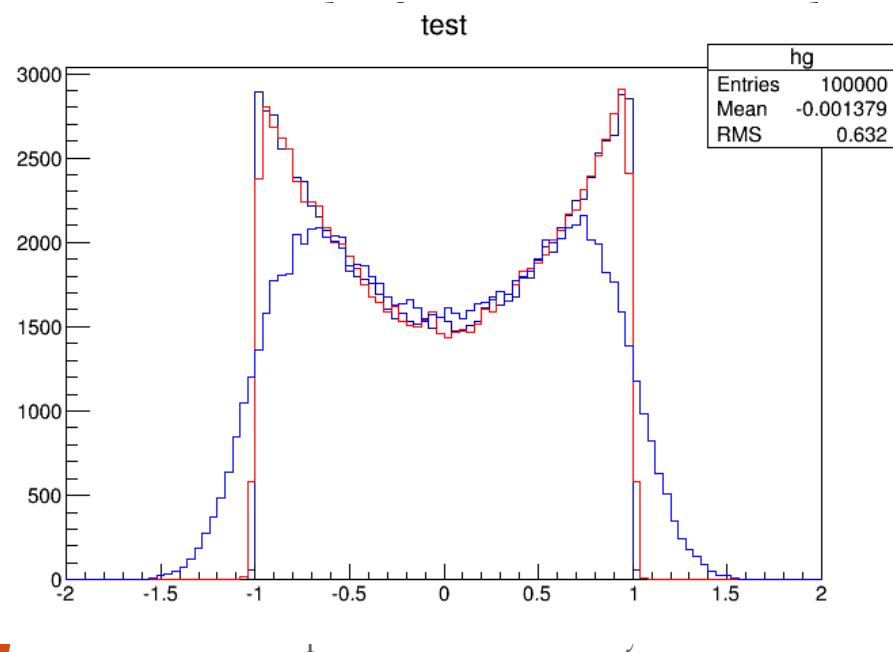
- If we want to consider only final states with a given kinematic configuration (momenta, angles, energies, ...) and give the cross-section as a function of these variables
- Experimentally we have to divide in bins and count the number of events per bin.
- Example: differential cross-section vs. scattering angle

$$\left(\frac{d\sigma}{d\cos\theta} \right)_i = \frac{1}{\int \phi dt} \left(\frac{N_{cand}^i - N_b^i}{\varepsilon_i} \right) \frac{1}{\Delta\cos\theta_i}$$

- NB: N_{cand} , N_b and ε as a function of θ are needed.

Differential cross-section - II

- Additional problems appear.
 - Efficiency is required per bin (can be different for different kinematic configurations).
 - Background is required per bin (as above).
 - The migration of events from one bin to another is possible:



Folding – Unfolding - II

- In case there is a substantial migration of events among bins (resolution larger than bin size), this affects the comparison btw exp.histo (n_i^{exp}) and theory (n_i^{th}). This can be solved in two different ways:

- **Folding** of the theoretical distribution: the theoretical function $f^{th}(x)$ is “smeared” through a smearing matrix M based on our knowledge of the resolution; $n_i^{th} \rightarrow n_i'^{th}$

$$n_i'^{th} = \sum_{j=1}^N n_j^{th} M_{i,j}$$

$$n_i^{th} = \int_{x_i}^{x_{i+1}} dx f^{th}(x)$$

- **Unfolding** of the experimental histogram: $n_i^{exp} \rightarrow n_i'^{exp}$. Very difficult procedure, mostly unstable, inversion of M required

$$n_i'^{exp} = \sum_{j=1}^N n_j^{exp} M_{i,j}^{-1}$$

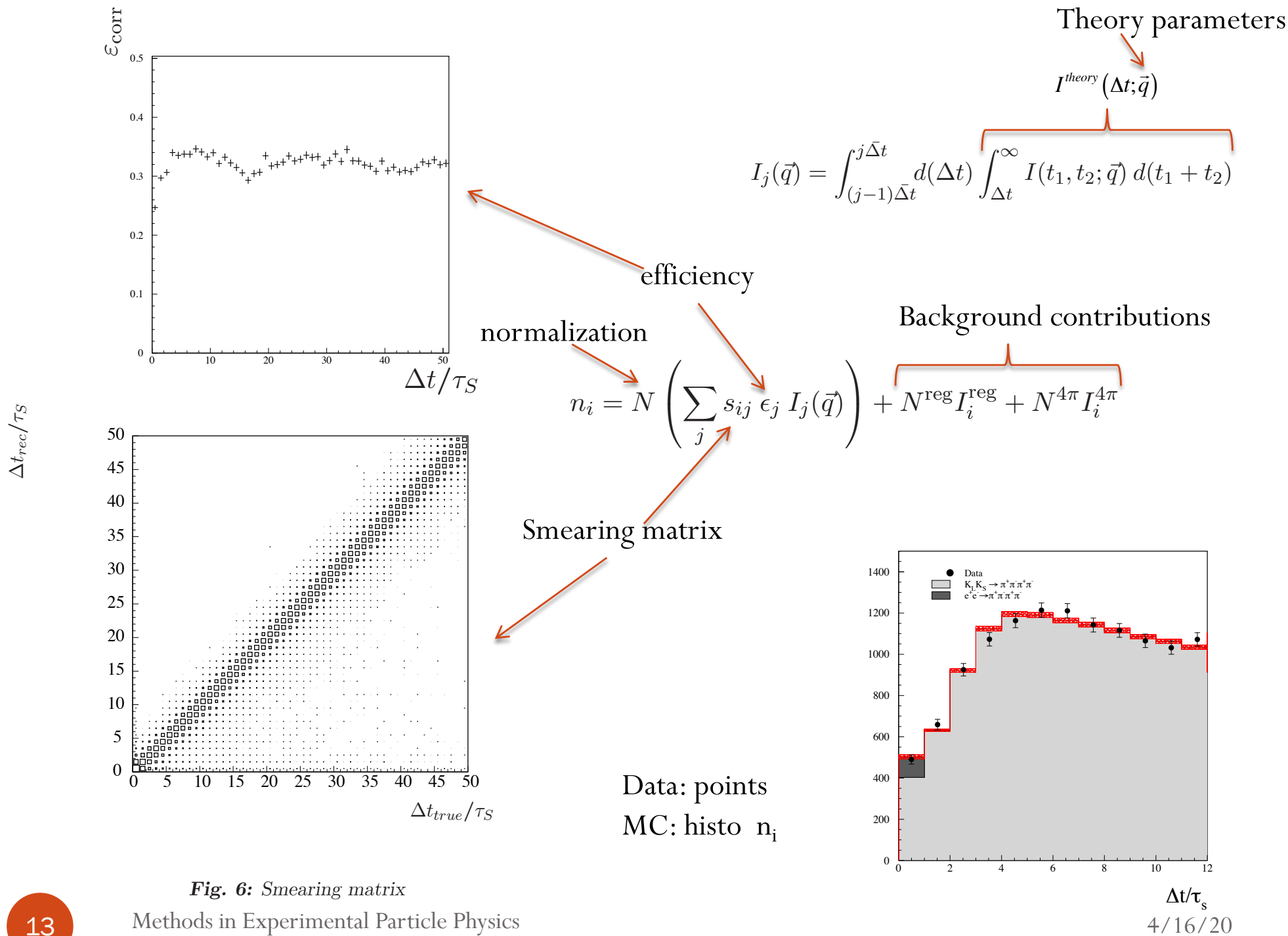


Fig. 6: Smearing matrix

Asymmetry measurement - I

- A very useful and powerful observable:

$$A = \frac{N^+ - N^-}{N^+ + N^-}$$

- It can be “charge asymmetry”, Forward-Backward asymmetry”, ...

- Independent from the absolute normalization
- (+) and (-) could have different efficiencies, but most of them could cancel:

$$A = \frac{N^+ / \epsilon^+ - N^- / \epsilon^-}{N^+ / \epsilon^+ + N^- / \epsilon^-}$$

- Statistical error ($N = N^+ + N^-$) :

$$\sigma(A) = \frac{1}{\sqrt{N}} \sqrt{1 - A^2}$$

Asymmetry measurement - II

Let us assume $\varepsilon^+ = \varepsilon^-$: the efficiencies cancel out in the asymmetry.

The statistical uncertainty on the asymmetry can be evaluate using a binomial model where $N = N^+ + N^-$, $n = N^+$, $f^+ = n/N$, so that $\mathcal{A} = 2f^+ - 1$. We get:

$$(87) \quad \sigma^2(\mathcal{A}) = 4\sigma^2(f^+) = 4\frac{f^+(1-f^+)}{N}$$

but, since

$$(88) \quad f^+ = \frac{1 + \mathcal{A}}{2}$$

we have also

$$(89) \quad \sigma(\mathcal{A}) = 2\sqrt{\frac{(1 + \mathcal{A})/2(1 - (1 + \mathcal{A})/2)}{N}} = \frac{2}{\sqrt{N}}\sqrt{\frac{1 + \mathcal{A}}{2}\frac{1 - \mathcal{A}}{2}} = \frac{1}{\sqrt{N}}\sqrt{1 - \mathcal{A}^2}$$

The uncertainty on the asymmetry goes as the inverse of the square root of the total number of events. The same result is obtained by assuming independent poissonian fluctuations for N^+ and N^- .

$$\sigma(\mathcal{A}) = \frac{1}{\sqrt{N}}\sqrt{1 - \mathcal{A}^2}$$