Dynamics in the Presence of Attractive Patchy Interactions

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We report extensive Monte Carlo and event-driven molecular dynamics simulations of a liquid composed of particles interacting via hard-sphere interactions complemented by four tetrahedrally coordinated short-range attractive ("sticky") spots, a model introduced several years ago by Kolafa and Nezbeda (Kolafa, J.; Nezbeda, I. *Mol. Phys.* **1987**, *87*, 161). To access the dynamic properties of the model, we introduce and implement a new event-driven molecular dynamics algorithm suited to study the evolution of hard bodies interacting, beside the repulsive hard-core, with a short-ranged interpatch square well potential. We evaluate the thermodynamic properties of the model in deep supercooled states, where the bond network is fully developed, providing evidence of density anomalies. Different from models of spherically symmetric interacting particles, the liquid can be supercooled without encountering the gas—liquid spinodal in a wide region of packing fractions ϕ . Around an optimal ϕ , a stable fully connected tetrahedral network of bonds develops. By analyzing the dynamics of the model we find evidence of anomalous behavior: around the optimal packing, dynamics accelerate on both increasing and decreasing ϕ . We locate the shape of the isodiffusivity lines in the ($\phi - T$) plane and establish the shape of the dynamic arrest line in the phase diagram of the model. Results are discussed in connection with colloidal dispersions of sticky particles and gel-forming proteins and their ability to form dynamically arrested states.

I. Introduction

This paper presents a detailed numerical study of the thermodynamics and the dynamics of a model introduced several years ago by Kolafa and Nezbeda¹ as a primitive model for water (PMW). The model envisions a water molecule as a hard sphere (HS) having a surface decorated by four short-ranged "sticky" spots, arranged according to a tetrahedral geometry, two of which mimic the protons and two the lone-pairs. Despite its original motivation, the Kolafa and Nezbeda model is representative of the larger class of particles interacting via localized and directional interactions, a class of systems that includes, besides network-forming molecular systems, also proteins²⁻⁴ and newly designed colloidal particles.⁵ Indeed, recent developments in colloidal science are starting to provide particles with specific directional interactions.⁶ In the same way as sterically stabilized colloids have become the ideal experimental model for realizing the hard-sphere fluid, novel physical chemical techniques will soon make available to the community colloidal analogues of several molecular systems. A colloidal water is probably not far from being realized.

Recent work⁷ has focused on the dynamics of colloidal particles interacting with a restricted number of nearest neighbors. In refs 7 and 8 particles are interacting via a limited-valency square well model,^{9–11} imposing a many-body constraint on the maximum number n_{max} of bonded interactions. It has been found that when $n_{\text{max}} < 6$, a significant shrinking of the liquid–gas (or colloidal rich–colloidal poor) spinodal takes place. A window of packing fraction values opens up in which it is possible to reach very low temperature (and hence states with extremely long bond lifetimes) without encountering phase

separation. This favors the establishment of a spanning network of long-living bonds, which in the colloidal community provides indication of gel formation but which, in the field of network-forming liquids, would be rather classified as glass formation. The study of the dynamics of the PMW provides a test of the $n_{\text{max}} = 4$ results, in the absence of many-body interactions and in the presence of a geometric correlation between the bonding sites, retaining the maximum valency. This paper, by reporting results on a model that can be at the same time considered to be a simple model for the new generation of patchy colloids or for network forming liquids, starts to bridge the gap between these two fields.

Thermodynamic and structural properties of several primitive models for water (and other bonded systems) have been studied in detail during the past 30 years, 1,12-15 because this type of primitive model has become one of the landmarks for testing theories of association.¹⁶⁻²² In particular, the theory of Wertheim^{16,17} has been carefully compared to early numerical studies, suggesting a good agreement between theoretical predictions and numerical data in the temperature and packing fraction regions where it was possible to achieve numerical equilibration.¹⁵ Recently, the increased numerical facilities, extending the range of studied state points, have clarified that deviations from the theoretical predictions start to take place as soon as the number of bonds (between different patches) per molecule increases and a network of bonded particles appears.^{20,23} Geometric correlations between different bonds, not included in the theory, are responsible for the breakdown of the theoretical and numerical agreement. Attempts to extend the perturbation theory beyond first order do not appear to be able to solve the problem.²³ The PMW is a good candidate for testing new theories of association and, for this reason, it is important to clearly establish numerically the low T behavior

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of the supercooled liquid state. The equilibrium PMW phase diagram, recently calculated,¹⁵ includes two crystal regions and a metastable fluid-gas coexistence.

All previous studies of primitive models for sticky directional interactions have focused on thermodynamic and static properties of the model. However, the ability to fully exploit the fast developments taking place in colloidal physics^{24,25} requires understanding of not only the equilibrium phases of systems of patchy particles and their modifications with the external fields but also the kinetic phase diagram,²⁶ that is, the regions in phase space where disordered arrested states can be expected, and when and how these states are kinetically stabilized with respect to the ordered lowest free energy phases. In this respect, it is worth starting to establish the dynamic properties of simple models of patchy interactions, because the simplicity of these models (based on hard-sphere and square well interactions) have the potential to provide us with an important reference frame and may play a relevant role in deepening our understanding of the dynamic arrest in network-forming liquids. Questions concerning arrest phenomena associated with gel formation^{7,27} (i.e., the establishment of a percolating network of long-lived bonds), arrest related to excluded volume effects, and the dependence of the general dynamic and thermodynamic features on the number and spatial location of patchy interactions can be properly addressed. The case of the PMW reported here is a good starting point. In this paper we report thermodynamic data, extending the previously available information to lower temperatures, and, for the first time, dynamic information obtained solving the Newton equations using a new algorithm based on event-driven propagation.

II. Model and Numerical Details

In the PMW, each particle is composed of a hard sphere of diameter σ (defining the length scale) and by four additional sites located along the direction of a tetrahedral geometry. Two of the sites (the proton sites H) are located on the surface of the hard sphere, that is, at a distance 0.5σ from the center. The two remaining sites (the lone-pair sites LP) are located at a distance of 0.45σ . Besides the hard-sphere interaction, preventing different particles from sample distances smaller than σ , only the H and LP sites of distinct particles interact via a square well (SW) potential u_{SW} of width $\delta = 0.15\sigma$ and depth u_0 , that is

$$u_{\rm SW} = -u_0 \quad r < \delta \tag{1}$$
$$= 0 \ r > \delta$$

where *r* is the distance between H and LP sites. The choice of $\delta = 0.15\sigma$ guarantees that multiple bonding cannot take place at the same site. The depth of the square well potential u_0 defines the energy scale. Bonding between different particles is thus possible only for specific orientations and distances. In the linear geometry, the maximum center-to-center distance at which bonding is possible is 1.1σ because the LP site is buried 0.05σ within the hard core, a value typical of short-range colloid—colloid interactions.

We have studied a system of N = 350 particles with periodic boundary conditions in a wide range of packing fraction $\phi \equiv \pi/6n\sigma^3$ (where *n* is the number density) and temperatures *T*, where *T* is measured in units of u_0 ($k_B = 1$). We perform both Monte Carlo (MC) and event-driven (ED) molecular dynamics. In MC, a move is defined as a displacement in each direction of a random quantity distributed uniformly between $\pm 0.05\sigma$ and a rotation around a random axis of a random angle distributed uniformly between ± 0.5 radiant. Equilibration was performed with MC and monitored via the evolution of the potential energy (a direct measure of the number of bonds in the system). The mean square displacement (MSD) was also calculated to guarantee that each particle has diffused on average more than its diameter. In evaluating the MSD we have taken care to subtract the center of mass displacement, an important correction in the low *T* long MC calculations. At low *T* simulations required $> 10^9$ MC steps, corresponding to several months of CPU time. Here a MC step is defined as *N* attempts to move (translation and rotation) a randomly selected particle.

We have also performed ED molecular dynamic simulations of the same system, modeling particles as constant density spheres of diameter σ and mass m. The momentum of inertia is diagonal and equal to $m\sigma^2/10$. The algorithm implemented to propagate the Newtonian trajectory in the presence of patchy square well interaction is described in detail in Appendix VII. In ED dynamics, time is measured in units of $\sigma\sqrt{m/u_0}$. Assuming as m the mass of the water molecule, as u_0 a typical value for hydrogen bond (≈ 20 kJ/mol), and as σ the nearestneighbor distance in water (0.28 nm), the unit of time corresponds to ≈ 0.3 ps. All static quantities have been evaluated with both MC and MD configurations with no differences found.

Pressure, measured in units of u_0/σ^3 , has been calculate as sum of three contributions. A trivial kinetic contribution, equal to nk_BT . A positive HS contribution and a negative contribution arising from the SW interaction. Details of the calculation of *P* in both MC and ED simulations is provided in the Appendix VIII.

III. Results: Static

A. Potential Energy *E*. Because in the PMW each site can take part in only one bond, due to geometric constraints fixed by the small value of δ , the lowest energy configuration is defined by four bonds per particles, corresponding to a ground-state energy per particle $E_{gs} = -2$ (in units of u_0). Of course, this absolute ground-state value may not be accessible at all ϕ , due to the strong constraints introduced by the bonding geometry. According to Wertheim's first-order thermodynamic perturbation theory, complemented by an appropriate choice of the shape of the radial distribution function of the reference hard-sphere system, the *T* and ϕ dependence of the potential energy per particle *E* is given by^{1,13-15}

$$E - E_{\rm gs} = \frac{2}{1+c} \tag{2}$$

where

$$c = 0.5[1 + 192(e^{1/T} - 1)\phi J]^{0.5} - 1$$
 (3)

$$J = \frac{c_1(1 - \phi/2) - c_2\phi(1 + \phi)}{(1 - \phi)^3} \tag{4}$$

with $c_1 = 2.375 \times 10^{-5}$ and $c_2 = 2.820^{-6}$.^{14,15} The Wertheim theory, which assumes uncorrelated independent bonds, predicts as low *T* limit of eq 2 an Arrhenius *T* dependence

$$\lim_{T \to 0} E - E_{\rm gs} = \frac{4}{\sqrt{192\phi J}} e^{-0.5/T}$$
(5)

that is, with an activation energy of half bond energy. It is worth observing that such an Arrhenius law, with an activation energy equal to $0.5u_0$, characterizes the low *T* dependence of the energy in the $n_{\text{max}} \mod el^{7.8}$ (a model of particles interacting via a SW



Figure 1. Potential energy for the PMW: (a) data for all studied isochores as a function of *T*; (b) enlargement of the low *T* region, where the network is fully developed. Note that for this model, the lowest possible energy is $E_{\rm gs} = -2$.

potential with an additional constraint on the maximum number of bonds), where no geometric correlation between bonds is imposed.

Figure 1 shows the *T* dependence of the potential energy for different isochores. As discussed in detail in the following, for $\phi \leq 0.24$ a phase separation is encountered on cooling, preventing the possibility of equilibrating one-phase states below $T \approx 0.11$. For $\phi > 0.24$ the system remains homogeneous down to the lowest investigated T. The low T behavior is expanded in Figure 1 (bottom). With the extremely long equilibration runs performed, proper equilibration is reached only for $T \ge 0.09$. The enlargement of the low T region shows that the absolute ground-state value of $-2u_0$ is closely approached at $\phi \approx 0.3$. At higher or smaller ϕ , the potential energy appears to approach a constant value larger than $-2u_0$. Consistent with previous claims,¹⁵ high T data are very well represented by first-order thermodynamic perturbation theory. Systematic deviations between theory and simulation data appear as soon as the number of bonds per particle becomes >1. Comparison of the simulation data with the Wertheim theory confirms that the physics of the network formation is completely missing in the first-order perturbation theory.

Figure 2 shows the ρ dependence of *E* along isochores. At high *T* (T > 0.13), a monotonic decrease of *E* is observed, caused by the increased bonding probability induced by packing. In this *T* region, the number of bonds is at most of the order of two per particle. Completely different is the situation for lower *T*. The ϕ dependence becomes nonmonotonic. There is a specific value of the packing fraction ($\phi \approx 0.3$) at which the lowest energy states are sampled. In the following we define the optimal



Figure 2. Potential energy versus ϕ along isotherms: (symbols) simulation data; (lines) Wertheim's theory.

network packing fractions as the range of packing fractions for which it is possible to fully satisfy the bonds in a disordered homogeneous structure. At $\phi \approx 0.3$, the number of bonds at the lowest investigated T (the lowest T at which equilibration is feasible with several months of computation time) is about 3.8 per particle; that is, about 95% of the bonds are satisfied. The range of optimal ϕ values appears to be rather small. Indeed, for packing fractions lower or higher than this optimal $\phi \approx$ 0.314, the formation of a fully connected network is hampered by geometric constraints: at lower ϕ , the large interparticle distance acts against the possibility of forming a fully connected network, whereas at large ϕ , packing constraints, promoting close packing configurations, are inconsistent with the tetrahedral bonding geometry. Not surprisingly, $\phi = 0.314$ is within the range of ϕ values that allow for a stable open diamond crystal phase $(0.255 \le \phi \le 0.34)$.¹⁵ A reduction of the geometric constraints (as in the n_{max} model^{7,28}) increases the range of optimal ϕ . It is worth also noting that the liquid side of the spinodal curve is close to the region of optimal network ϕ .

The existence of a convex form for the potential energy (here for $\phi \ge 0.3$) has been observed in several other models for tetrahedral networks, including models for water (and water itself²⁹). It has been pointed out that a negatively convex ϕ dependence is indicative of a destabilization of the free energy²⁹ and a precursor of a possible liquid—liquid critical point (in addition to the lower ϕ gas—liquid one). Liquid—liquid critical points have been observed in several models for water.^{30–35} Indeed, the Helmholtz free energy *A* is related to *U* (the sum of the kinetic and potential energy) via A = U - TS, where *S* is the entropy. The curvature of an isotherm of *A* must be positive for a homogeneous phase of a specified volume *V* to be thermodynamically stable. The curvature of *A* can be expressed as

$$\left(\frac{\partial^2 A}{\partial V^2}\right)_T = \left(\frac{\partial^2 U}{\partial V^2}\right)_T - T\left(\frac{\partial^2 S}{\partial V^2}\right)_T \tag{6}$$

Because $P = -(\partial A/\partial V)_T$, the inverse compressibility $K_T = -1/V(\partial V/\partial P)_T$ is related to the curvature of A by

$$\frac{1}{K_T} = V \left[\left(\left(\frac{\partial^2 U}{\partial V^2} \right)_T - T \left(\frac{\partial^2 S}{\partial V^2} \right)_T \right) \right]$$
(7)

The curvature of A is thus proportional to $1/K_T$ for fixed V. Because $1/K_T$ must be positive for a thermodynamically stable state, for the range of V in which $(\partial^2 U/\partial V^2)_T < 0$, the



Figure 3. Arrhenius representation $(E - E_{\rm gs} \text{ vs } 1/T)$ of the potential energy around the optimal network density. The dashed line, shown as a reference, has an activation energy of $1u_0$.

contribution of the internal energy reduces the thermodynamic stability of the liquid phase. The liquid remains stable where U has negative curvature only because the contribution of the entropic term in eq 6 is large enough to dominate. Yet entropic contributions to these thermodynamic quantities are suppressed as T decreases, due to the occurrence of the factor of T in the second term on the right-hand side of eq 6. Hence, the U - V data suggest that at lower T a single homogeneous phase of the liquid will not be stable for certain values of V, leading to a separation into two distinct liquid phases of higher and lower volume. Due to the predominant role of E in the free energy at low T, the possibility of a phase separation of the PMW liquid into two liquid phases of different ϕ , for $\phi > 0.3$ and T lower that we are currently able to equilibrate should be considered.

Figure 3 shows $\ln(E - E_{\rm gs})$ versus 1/T. At the optimal ϕ , the energy of the fully connected state is approached with an Arrhenius law, characterized by an activation energy of $\approx 1u_0$, clearly different from the 0.5 value predicted by the Wertheim theory. For larger ϕ values, data suggest that the lowest reachable state has an energy different from $-2u_0$, consistent with the expectation that on increasing ϕ , geometric constraints forbid the development of a fully connected network even at the lowest *T*.

B. *P*. The Wertheim prediction for the *T* and ϕ dependence of the PMW pressure (the equation of state, EOS) is

$$P = P_{\rm HS} - nk_{\rm B}T \frac{96(e^{1/T} - 1)}{(1+c)^2} \frac{c_1\phi(1+\phi - 0.5\phi^2) - 2c_2\phi^2(1+2\phi)}{(1-\phi)^4}$$
(8)

where $P_{\rm HS}$ is the pressure of the HS fluid at the same packing fraction. $P_{\rm HS}$ can be very well represented by the Carnahan–Starling EOS³⁶

$$P_{\rm HS} = nk_{\rm B}T \frac{(1+\phi+\phi^2-\phi^3)}{(1-\phi)^3}$$
(9)

The Wertheim EOS predicts a vapor-liquid critical point at $T_c = 0.1031$ and $\phi_c = 0.085$.¹⁵ The vapor-liquid spinodals calculated according to the Wertheim theory and from simulation data are reported in Figure 4. The numerical estimate is provided by locating, along isochores, the highest *T* state point in which phase separation is observed and the *T* at which the small *q* limit of the structure factor is <5. These two state points bracket the spinodal locus. It is interesting to compare the liquid–gas



Figure 4. Thermodynamic phase diagram for the PMW. The theoretical Wertheim prediction for the locus at which $(\partial P/\partial V)_T = 0$ is compared with numerical estimates of the spinodal, calculated by bracketing it via the locus of point at which $S(0) \approx 5$ and the locus of points where a clear phase separation is detected. The location of the bond percolation line is also reported.

spinodal of the PMW with the corresponding spinodal of the symmetric spherical square well potential with the same depth and well width $\delta = 0.15$. In that case, the critical point is located at $T_{\rm c} \approx 0.56$ and $\phi_{\rm c} \approx 0.212^{37}$ and the high packing fraction (the liquid) side of the spinodal extends beyond $\phi = 0.6$. The net result of decreasing the surface available to bonding and of limiting to four the maximum number of nearest neighbors that can form bonds is the opening of a wide region of ϕ values where (in the absence of crystallization) a homogeneous fluid phase is stable (or metastable). This finding is in full agreement with the recent work of ref 7, in which a saturated square well model was studied for different values of the maximum valency. Indeed, it was found that when the number of bonds becomes < 6, the unstable region [the surface in the ($\phi - T$) plane encompassed by the spinodal line] significantly shrinks, making it possible to access low T states under single-phase conditions.

Figure 5 shows P(T) for different isochores. In agreement with previous analysis, P is well represented by the Wertheim theory only at high temperature. At low T several interesting features are observed: (i) For $\phi < 0.25$, isochores end in the spinodal line. (ii) In the simulation data, a clear difference in the low T behavior is observed between the two studied isochores $\phi = 0.288$ and $\phi = 0.314$. Whereas in the $\phi = 0.288$ case P(T) decreases continuously on cooling, in the $\phi = 0.314$ case the low T behavior of P is reversed and P approaches a positive finite value on cooling. This different low T trend indicated that for $\phi \leq 0.3$, on cooling, the network becomes stretched (negative pressures), in an attempt to preserve the connected bonded state. This implies that at low T there is a driving force for phase separation into a fully connected unstressed network and a gas phase. This also suggests that the spinodal curve ends at T = 0 around $\phi = 0.3$. At $\phi \approx 0.3$, the packing fraction is optimal for the formation of an unstressed fully connected network at low T. The bond formation on cooling does not require any stretching, and it reverses the Tdependence of P. (iii) At 0.3 $\leq \phi \leq 0.38$ a minimum of P appears. The existence of a minimum in P(T) along isochores demonstrates the presence of density anomalies (i.e., expansion on cooling along isobars) because points in which $(\partial P/\partial T)_{\rm V} =$ 0 coincide with points in which $\alpha \equiv (\partial V/\partial T)_P = 0$, that is, with points in which density anomalies are present. Indeed, by using the rules for derivatives of implicit functions $(\partial V/\partial T)_P = -(\partial P/\partial T)_P$ ∂T _V $(\partial V/\partial P)_T$, and mechanical stability guarantees that $(\partial V/\partial P)_T$ > 0.



Figure 5. Isochores of *P* according to the Wertheim theory (a) and as calculated from the simulation data (b). Symbols refer to simulation data. The same sequence of ϕ values is shown in both panels.



Figure 6. Components of the pressure at $\phi = 0.314$. The total *P* is decomposed in ideal gas, HS, and bonding components. Note the isochoric minimum in *P* and T = 0.105, a signature of an isobaric density maximum.

The simplicity of the model allows us to access the different contributions to *P* and investigate the origin of the increase of *P* on cooling (Figure 6). In the PMW, apart from the trivial kinetic component contribution, the only positive component to *P* arises from the HS interaction. Interestingly enough, the HS component increases on cooling. Such an increase in the HS repulsion, indirectly induced by the formation of the bonding pattern, in the range $0.30 \le \phi \le 0.36$, appears to be able to compensate for the decrease in the bonding component of *P*.

To confirm the presence of density anomalies, it is instructive to look at the V dependence of P along isotherms, shown in



Figure 7. Isotherms of *P* according to the Wertheim theory [full continuous lines in (a)] and as calculated from the simulation data [symbols in both (a) and (b)] as a function of the volume per particle $v \equiv n^{-1}$. Note the crossing of the different isotherms at v = 1.4 and 1.7.

Figure 7. Again, the simulation data are consistent with the Wertheim theory predictions only at large *T*, and indeed it was already noted that no density anomalies are found within the theory¹. The simulation data also show a clear crossing of the isotherms around a volume per particle v = 1.4 and 1.7, corresponding to $\phi = 0.314$ and $\phi = 0.38$. Again, crossing is indicative of the presence of density anomalies. The increase of *P* on cooling, between $\phi = 0.314$ and $\phi = 0.38$, suggests also a possible emergence of a second van der Waal-type loop (in addition to the gas-liquid one) for *T* lower than the one we are currently able to equilibrate. The possibility of a second critical point between two liquid phases of different densities has been discussed at length in the past,³⁸ following the discovery of it³⁰ in one of the first models for water.³⁹

C. g(r). The PMW radial distribution functions for T > 0.15 have been reported previously.¹ Here we focus on the interesting structural changes observed during the development of the bond network in g_{OO} and g_{H-LP} , a *T* region that was not possible to access in the previous simulations. g_{OO} provides information on the center to center particle correlation, whereas $g_{H-LP}(r)$ contains information on the bonding and on the attractive component of the pressure.

Figure 8 shows $g_{OO}(r)$ at three different packing fractions. In the interval $1 \le r \le 1.1$ the function is highly peaked, a consequence of the distance imposed by bonding. Outside the bonding distance $(r \ge 1.1)$, $g_{OO}(r)$ shows significant oscillations only at low *T*. A peak, beside the bonding one, is observed at $r \approx 1.7$ corresponding to the characteristic distance between



Figure 8. Particle–particle radial distribution function at $\phi = 0.105$ (a), $\phi = 0.288$ (b), and $\phi = 0.380$ (c).

two particles bonded to the same central particle in a tetrahedral geometry. The absence of information about the geometry of the bonding sites in the theory of Wertheim is responsible for the absence of the peak at 1.7σ and the breakdown of the predictive ability of the Wertheim theory as soon as a particle is engaged in more than two bonds. A few observations are in order when the ϕ dependence of $g_{OO}(r)$ is analyzed: At low ϕ , the tetrahedral peak at $r \approx 1.7$ is the only peak in $g_{OO}(r)$. When ϕ approaches the optimal network density, a clear tetrahedral pattern develops and $g_{OO}(r = 1.7)$ becomes >2. The tetrahedral peak at ≈ 1.7 is followed by oscillations extending up to 4σ . At even larger ϕ , there is still a residual signature of tetrahedral bonding at 1.7 σ , but the depletion region for $r > 1.1\sigma$ is not developed any longer, signaling a competition between the HS packing (which favors peaks at positions multiple of σ) and the local low density required by bonding.

Figure 9 compares, at $\phi = 0.314$, the OO, HH, and H–LP radial distribution functions in linear scale. In all three functions, the progressive structuring induced by the bonding is clearly



Figure 9. Radial distribution functions for OO (a), HH (b), and H–LP (c) pairs at the optimal network density $\phi = 0.314$. Insets in g_{OO} and g_{H-LP} provide enlargements of the contact region. On cooling, a significant structure appears, associated with the intense bonding.

evident. Even $g_{HH}(r)$ shows very clear signs of spatial correlations, which are induced by the tetrahedral geometry of the bonding and by the geometry by which the bonding between H and LP propagates. Indeed, in the PMW model the interaction between different *H* sites is zero.

D. S(q). The structure factor of the system, defined in terms of the particle's center coordinates \vec{r}_i as

$$S(\vec{q}) = \left\langle \frac{1}{N} \sum_{i=1}^{N} \sum_{j=1}^{N} e^{i\vec{q} \cdot (\vec{r}_i - \vec{r}_j)} \right\rangle$$
(10)

provides information on the wave vector dependence of the density fluctuations. In isotropic systems, S(q) is a function of the modulus q. The behavior of S(q) at small q provides an indication on the phase behavior, because an increase of S(q)

at small q indicates the development of inhomogeneities with length scale comparable to the system size studied. As an indicator of the location of the phase boundaries (of the liquidgas spinodal line), we estimate the locus of points in (T,ϕ) , where S(q) for the particle centers becomes >5 at small q. This locus is reported in Figure 4. For $\phi \gtrsim 0.28 S(q)$ does not show any sign of growth at small q in the region of T where equilibration is feasible, being characterized by values of S(q) at small q of the order of 0.1. This confirms that, at this packing fraction, there is no driving force for phase separation, because the average density has reached a value such that the formation of a fully connected network of bonds does not require a local increase of the packing fraction. It is also important to stress that at $\phi = 0.288$, at the lowest studied T, the average number of bonds per particle is 3.8, and hence the system is rather close to its ground state and no more significant structural changes are expected on further cooling.

Figure 10 shows S(q) at $\phi = 0.105$, $\phi = 0.288$, and $\phi = 0.385$. The $\phi = 0.105$ case has been chosen to show the significant increase in S(q) associated with the approach of the spinodal curve. The case $\phi = 0.288$ shows both the absence of a small *q*-vector divergence and the clear development of the typical *q*-pattern of tetrahedral networks. On cooling, the peak at $q\sigma = 2\pi$ characteristic of excluded volume interactions splits in two parts: a prepeak around $q\sigma \approx 5$ and an intense peak around $q\sigma \approx 8$. The case $\phi = 0.385$ confirms that the packing fraction is now so high that a full tetrahedral network cannot develop, and the splitting of the main peak in two distinct components is very weak and visible only at the lowest investigated *T*.

E. Percolation. The PMW, as all other models based on HS and SW interactions, is particularly suited for calculation of bond properties, because a bond between particles i and j can be unambiguously defined when the pair interaction energy between i and j is $-u_0$. In the case of continuous potentials such a clear-cut bond definition is not possible and several alternative propositions have been put forward.^{40,41} We focus here on the connectivity properties of the equilibrium configurations. We use first standard algorithms to partition particles into distinct clusters and then check for the spanning properties of each of these clusters. To implement a strict definition of percolation, we do not limit ourselves to the comparison of the largest intracluster distance with the simulation box length, but make sure that the cluster is spanning in the infinite system limit. More explicitly, to test for percolation, the simulation box is duplicated in all directions, and the ability of the largest cluster to span the replicated system is controlled. If the cluster in the simulation box does not connect with its copy in the duplicated system, then the configuration is assumed to be nonpercolating. The boundary between a percolating and a nonpercolating state point has been defined by the probability of observing infinite clusters in 50% of the configurations. The resulting percolation line is reported in Figure 4. State points on the right side of the line are characterized by the presence of an infinite cluster in > 50% of the configurations. This definition of percolation locus is strictly a geometric measure and does not provide any information on the lifetime of the spanning cluster. Along the percolation line, about 1.5 bonds per particle are observed, with a small trend toward an increase of this number on decreasing ϕ . In terms of bond probability $p_{\rm b}$, this corresponds to $p_{\rm b} \approx$ 0.375, not too different from the bond percolation value of the diamond lattice, known to be 0.388.42



Figure 10. Particle-particle structure factor at $\phi = 0.105$ (a), $\phi = 0.288$ (b), and $\phi = 0.385$ (c). Note that at $\phi = 0.105$, an intense signal develops at small q, related to the approach to the spinodal instability. Small q intensity is completely missing at the higher ϕ shown.

line crosses the spinodal curve close to the critical point, on the left side of the spinodal curve. In this respect, the equilibrium gas phase at ϕ smaller than this crossing point is always nonpercolating. Percolation at very small ϕ can be achieved only as a result of an out-of-equilibrium process, quenching the system inside the spinodal curve.

The high ϕ side of the percolation locus—different from the SW case—does not extend to infinite *T*, because at high *T*, even at large ϕ , the reduced particle surface available for bonding prevents the possibility of forming a spanning network with a random distribution of particle orientations.

IV. Dynamics

Thermodynamic and static properties of the PMW presented in the previous section clarify the location of the regions in



Figure 11. Mean square displacement for different *T* values, at three different ϕ values: (a) $\phi = 0.131$; (b) $\phi = 0.314$; (c) $\phi = 0.450$.

which the bond network forms, the region where the liquidgas phase separation takes place and the region at high ϕ where packing phenomena start to be dominant. In the following we present a study of the diffusion properties of the model in the phase diagram, with the aim of locating the limit of stability of the liquid state imposed by kinetic (as opposed to thermodynamic) constraints.

A. MSD. We focus on the mean square displacement $\langle r^2(t) \rangle$ of the particle centers, as a function of *T* and ϕ , calculated from the Newtonian dynamic trajectories. Figure 11 shows $\langle r^2(t) \rangle$ for a few selected isochores. For short time $\langle r^2(t) \rangle = \langle v_T^2 \rangle t^2$, where $\langle v_T^2 \rangle = \frac{3}{2}k_BT$ is the thermal velocity. At high *T*, the short-time ballistic behavior crosses over to a diffusion process ($\langle r^2 \rangle \sim t$) directly. At low *T*, the ballistic short-time and the diffusive long-time laws are separated by an intermediate time window in



Figure 12. Mean square displacement along a constant *D* path. Note the ϕ dependence of the plateau at intermediate times, which provides an estimate of the caging length.

which $\langle r^2(t) \rangle$ is approximatively constant, an indication of particle caging.

Several features of $\langle r^2(t) \rangle$ are worth pointing out: (i) For ϕ \leq 0.209, the spinodals are encountered on cooling before the caging process is visible. The phase separation process sets in well before particles start to feel the caging process. (ii) The static percolation curve reported in Figure 4 has no effect on dynamics. There is no dynamic arrest at the static percolation transition. (iii) For ϕ such that a well-developed tetrahedral network can form, it is possible to cool the system to temperatures at which, on the scale of simulation, arrest is observed, in the absence of any phase separation. $\langle r^2(t) \rangle$ develops a clear intermediate region where only the dynamic inside the cage is left. At this ϕ , the caging is not associated with excluded volume interactions, but with the formation of energetic bonds.⁴⁵ (iv) The plateau value in $\langle r^2(t) \rangle$ is a measure of the localization length induced by the cage. To visualize the ϕ dependence of the localization length, we show in Figure 12 $\langle r^2(t) \rangle$ for three different state points ($\phi - T$) with the same long-time diffusivity. The cage length is always significantly larger than the typical HS value ($\langle r^2(t) \rangle \sim 0.01$) and grows on decreasing ϕ .

B. Diffusion Coefficient. The long-time limit of $\langle r^2(t) \rangle$ is, by definition, 6Dt, where D is the diffusion coefficient. The ϕ and T dependence of D is shown in Figure 13. We show log-(D) both versus T and versus 1/T. Again, a few considerations are in order: (i) The range of D data covers about 5 orders of magnitude. The data for $\phi < 0.24$ are limited in T by the phase separation process, whereas the data for $\phi > 0.26$ are limited by computational resources, because equilibration cannot be reached within several months of calculations. (ii) Data for ϕ > 0.26 cross around $T \approx 0.105$, suggesting a nonmonotonic behavior of the ϕ dependence of the dynamics. (iii) The early decay of D with T can be described with a power law, |T - T| = 1 $T_{\text{MCT}}|^{\gamma}$. Power law fits, limited to the region of T between T =0.11 and T = 0.15, cover the first 2–3 orders of magnitude in D, in agreement with previous studies of more detailed models for water⁴⁵⁻⁴⁷ and with the previously proposed MCT interpretation of them.^{47–50} (iv) A crossover to an Arrhenius activated dynamics is observed at low T. Activated processes become dominant in controlling the slowing of the dynamics. The activation energy is $\approx 4u_0$, close to the optimal network ϕ , suggesting that at low T diffusion requires breaking of four bonds. The crossover from an apparent power-law dependence to an Arrhenius dependence has also been observed in simulations of other network-forming liquids, including silica^{51,52} and more recently water.⁵³ The low T Arrhenius dependence also



Figure 13. Temperature dependence of the diffusion coefficient along isochores. The dashed line is an Arrhenius dependence with activation energy equal to $4u_0$.



Figure 14. Diffusion coefficient along isotherms. Note the nonmonotonic behavior that develops for T < 0.11.

suggests that in the region where bonding is responsible for caging, the vanishing D locus coincides with the T = 0 line.

Particularly interesting is the behavior of $D(\phi)$ along isotherms. An almost linear dependence at small ϕ (up to $\phi =$ 0.235) is followed by a nonmonotonic behavior. Below T =0.11 (Figure 14), a diffusion anomaly is observed in the *T* and ϕ region, where the tetrahedral network develops. Around $\phi =$ 0.34 an isothermal compression of the system generates an acceleration of the dynamics. Above $\phi \approx 0.35$, *D* starts to decrease again on increasing packing. Diffusivity anomalies of the type observed in the PMW are found in several tetrahedral network-forming liquids, including water.⁵⁴ The explanation for



Figure 15. Isodiffusivity lines in the $(T - \phi)$ plane. An excursion of 5 orders of magnitude in *D* values is explored. All lines start from the spinodal and end at infinite *T* at the corresponding HS location. At small *D*, lines cannot be continued above $\phi = 0.5$ because there the HS interaction is dominant and the system crystallizes. Extrapolating along isochores the observed Arrhenius functional form suggests an ideal D = 0 arrest line at T = 0.

this counterintuitive ϕ dependence of the dynamics is to be found in the geometric constraints requested by the tetrahedral bonding requiring an open local structure. Increasing ϕ destroys the local bonding order with a resulting acceleration of the dynamics.

C. Isodiffusivity (and Arrest) Lines. A global view of the dynamics in the $(T - \phi)$ plane is offered by the isochronic lines, that is, the locus of state points with the same characteristic time.⁵⁵ In the present case we focus on the isodiffusivity lines. The shape of the isodiffusivity lines, extrapolated to $D \rightarrow 0$, provides a useful indication of the shape of the glass transition line.^{56–58} Figure 15 shows the isodiffusivity lines for several different values of D, separated from each other by 1 order of magnitude. The slowest isodiffusivity lines are only weakly T dependent at low ϕ . For small values of D, isodiffusivity lines start from the right side of the spinodal, confirming that slow dynamics is only possible for states with $\phi > \phi_c$. At large ϕ the isodiffusivity lines bend and become parallel to the T axis, signaling the crossover to the hard-sphere case. Extrapolation to 0 of the T (or ϕ) dependence of D provides estimates of the dynamic arrest line. In the present model, the low T dependence of D along isochores is well modeled by the Arrhenius law, and hence technically arrest is expected at T = 0. The shape of the isodiffusivity lines suggests that the vertical repulsive glass line (controlled by excluded volume effects) starting at high Tfrom the HS glass packing fraction meets at a well-defined ϕ the T = 0 bond glass line.

The shape of the PMW isodiffusivity lines is very similar to the short-range square well case, for which a flat *T*-independent "attractive" glass line crosses (discontinuously) into a perpendicular ϕ independent "repulsive" glass line.^{58,59} Differently from the SW case, in the PMW the equivalent of the attractive glass line extends to much smaller ϕ values, because the reduced valency has effectively reduced the space in which phase separation is observed.⁷ It is also worth pointing out that the shape of the isodiffusivity lines at low ϕ is similar to the shape of the percolation line. As in all previously studied models,^{7,58} crossing the percolation line does not coincide with dynamics arrest, because the bond lifetime is sufficiently short that each particle is able to break and re-form its bonds.

D. *D* versus $E - E_{gs}$. At the optimal network density, the low *T* behavior of both *D* and $E - E_{gs}$ (which, as discussed



Figure 16. Diffusion coefficient versus $E - E_{gs}$ for different ϕ values. The dashed line is a power law with exponent four.

above, is also a measure of the number of broken bonds) is Arrhenius. This suggests the need for a more careful look into the relationship between the activation energy of the two processes. One possibility is offered by a parametric plot of Dversus $E - E_{gs}$ in log-log scale, so that the slope of the straight line provides the ratio of the two activation energies. Such a plot is shown in Figure 16. We find the remarkable result that, close to the optimal network ϕ , the slope of the curve has exponent four, that is, $D \sim (E - E_{gs})$.⁴ Because the fraction of broken bonds in the system is exactly $(E - E_{gs})/E_{gs}$, the previous relationship suggests that D is proportional to the fourth power of the fraction of broken bonds, that is, to the fraction of particles with no bonds, and that the elementary diffusive process requires the breaking of four bonds. A functional law for diffusion in a tetrahedral model of this type was proposed by Teixera⁶⁰ to interpret the T dependence of D in water in the context of the percolation model developed in ref 61. A similar dependence has been recently reported for a model of gel-forming fourarmed DNA dendrimers.62

E. D – **MD versus MC.** All dynamic data presented above refer to ED Newtonian dynamics. Indeed, MC simulations intrinsically miss dynamic information, being based, in their simpler formulations, on random displacements of the individual particles. Still, if the random displacement in the trial move is small compared to the particle size, the sequence of MC steps can be considered a possible trajectory in configuration space. When this is the case, the number of MC steps (each step being defined as an attempted move per each particle) plays the role of time in the evolution of the configurations in configuration space. In the absence of interactions, a particle evolved according to the MC scheme diffuses with a bare diffusion coefficient $D^0_{
m MC}$ fixed by the variance $\delta^2_{
m MC}$ of the chosen random displacement along each direction [in our calculations we have used a uniform distribution of displacements with a variance of $\delta_{\rm MC}^2 = (0.1)^2/12$, corresponding to $D_{\rm MC}^0 = 3\delta_{\rm MC}^2/6$ in units of $\sigma^2/\rm MC$ step]. If needed, $D_{\rm MC}^0$ provides a means to associate a physical time to the MC step. At low T, when slow dynamic processes set in (favored by bonding or by packing), it is expected that the microscopic dynamics becomes irrelevant (except for a trivial scaling of time). The escape from the cage created by neighboring particles is indeed a much rarer event as compared to the rattling of the particles in the cage. Under these conditions, the slow dynamic processes become independent of the microscopic dynamics, and hence Newtonian, Brownian, and MC show the same trends. Figure 17 shows that this is the case for three ϕ values. In all cases, at low T, the T



Figure 17. Comparison between the MD and MC diffusion coefficients at three different ϕ values. The MC data are also shown multiplied (by a common factor of 0.1) to better visualize the low *T* overlap.

dependencies of D^{MC} and D are identical. Moreover, the scaling factor between MC and MD dynamics is independent of ϕ , suggesting that at low T, with the chosen units, the relationship $D^{\text{MC}}/D_{\text{MC}}^0 = \xi$ holds. From comparing MC and MD data we find that the proportionality constant $\xi \approx 10$ and shows no statepoint dependence. To confirm that caging is fundamental to the observance of independence of the slow dynamics from the microscopic one, we look at the shape of $\langle r^2(t) \rangle$ (Figure 11), finding that at the T at which MC and MD dynamics start to coincide a significant caging is present.

Because the microscopic time of the MC dynamics is not affected by temperature (being always fixed by the variance of the random displacements), it is interesting to consider the relationship between D and $E - E_{gs}$ also for D^{MC} , shown in Figure 18 at the optimal network density $\phi = 0.314$. Again, the slope of the curve has exponent four, but compared to the MD case, the region of validity of the power law covers the entire range of T studied, from very high T (where the number of bonds is negligible) to the lowest equilibrated temperature,



Figure 18. Relationship between D^{MC} , normalized by the bare MD diffusion constant D^0_{MC} and $E - E_{\text{gs}}$ for MC dynamics. Note that the MC data follow over 5 orders of magnitude a simple fourth-power law (full red line).

covering more than 4 orders of magnitude. The validity of the relationship $D \sim (E - E_{\rm gs})^4$ extends to high *T*, when the system is well above percolation and there is no evidence of a tetrahedral network (as shown in the structural data reported in Figures 10 and 8). The extended validity of the power law, with an exponent exactly equal to the valence of the model, is highly suggestive and, in principle, very important for theoretical considerations, because it appears to cover either the region of temperature where liquid dynamics is observed or the low *T* states where signatures of slow dynamics (see Figure 11) are very well developed. The limit of validity of this finding needs to be carefully checked in other primitive models with different valence and with more realistic models of network-forming liquids.

V. Conclusions

Results presented in this paper cover several apparently distinct fields. To start with, results presented here can be discussed in relation to the dynamic and thermodynamic properties of water. We have shown that the thermodynamics of the PMW includes, besides the compressibility anomalies reported before,¹ also density anomalies (at much lower T). The source of the density anomalies is shown to be associated with the establishment of the bond network in the tetrahedral geometry. On cooling (along isochores) the energetic driving force that favors the formation of the bond, due to geometric constraints associated with the formation of the open tetrahedral structure, forces the pressure to increase, hence generating a density maximum state point. The simplicity of the PMW allows us also to clearly detect an optimal network density, at which the ground state of the system (i.e., the state in which each particle is involved in four bonds) can be closely approached. At this packing fraction ϕ the T dependence of the potential energy is the most pronounced, generating a minimum in the isothermal ϕ dependence. The presence of a minimum in $E(\phi)|_T$ is highly suggestive because it indicates⁶³ the possibility of a liquid—liquid phase separation at *T* lower than the one we have been able to equilibrate. We have also shown that at this optimal ϕ , low T dynamics slows with the fourth power of the probability of broken bonds; that is, the dominant component to dynamics arises from single-particle motions and, specifically, from the particles that happen to have all four bonds broken at the same time. We have also shown that, as in real water, diffusion anomalies are observed. At low T, the decrease of the diffusivity on increasing ϕ is reversed once the optimal network density is

reached. For higher ϕ , the progressive destruction of the bond network due to the increased packing accelerates the dynamics. For even higher ϕ , $D(\phi)$ resumes its standard decreasing behavior associated with the approach of the excluded volume glass transition. Diffusion and density anomalies in the PMW models are thus strongly related, similarly to what has been observed in more realistic models for water.⁶⁴ The simplicity of the model is crucial in clarifying these aspects because the hard-core and square well interactions guarantee the absence of volumetric effects related to the *T* dependence of the vibrational amplitudes.

A second interesting aspect of the presented results concerns the dynamics in network-forming systems. The present study provides a complete characterization of the dynamics in the entire $(\phi - T)$ plane, from the smallest possible ϕ liquid state points to the close-packed state. From the reported data, the relative role of the energy and of the packing in controlling the dynamics stands out clearly. The isodiffusivity lines are essentially parallel to the ϕ -axis (i.e., *T* controlled) in the network low ϕ region and are essentially parallel to the *T*-axis (i.e., ϕ controlled) at larger ϕ . Interestingly enough, along isochores, low T dynamics follows an Arrhenius law, the landmark of strong glass-forming behavior.65,66 The Arrhenius law is foreseen by a T region where dynamics has a strong T dependence, compatible with a power-law dependence. In this power-law region the first signatures of caging in the mean square displacement are observed. Similar changes in the dynamics have been observed in previous studies of silica, 51,52,67 water, 53 and silicon.⁶⁸ In particular, for the cases of silica and water, it has been suggested that the region where dynamics starts to feel the presence of energetic cages can be interpreted in terms of mode coupling theory. 45,52,67,69-73

The dynamics at the optimal network ϕ is particularly suggestive. Although in the present model slowing of the dynamics prevents equilibration of the supercooled liquid to very low T, at the lowest T simulations the average number of bonds has gone up to 3.8 per particle. In this respect, further structural and dynamic changes are hard to foresee. This suggests that the Arrhenius behavior is retained down to T = 0. Such speculation is reinforced by the numerical values of the activation energy of D, which is found to be $\approx 4u_0$, that is, corresponding to the breaking of four bonds. This suggests that in network liquids, the limited valency imposed by the directional forces fixes a well-defined energy of the local configuration and a discrete change of it, which is reflected in the Arrhenius behavior. The presence of a limited valency and a well-defined bond energy scale appears to be the key ingredient of the strong liquids behavior.8 It is also worth exploring in future works the possibility that the optimal network density plays, in studies of one-component systems, the same role as the reversibility window⁷⁴ in bulk alloy glasses. Connections with the concept of self-organization in network glasses⁷⁵ should also be pursued.

A further aspect of this work concerns the relative location between the liquid–gas spinodal and the kinetics arrest lines, the shapes of which are inferred by the study of the isodiffusivity lines. As in the short-range SW model,^{43,76} the kinetics arrest lines end in the right side of the spinodal, that is, in the liquid phase. However, differently from the SW case, the limited valency has shifted the right side of the spinodal to very small ϕ values, $\phi \leq 0.25$. Indeed, the limited valency effectively disfavors condensation of the liquid phase, reducing the driving force for phase separation and making it possible to generate low packing fraction arrested states in the absence of phase

separation, that is, homogeneous single phase stable in equilibrium, at low T.⁷⁷ The possibility to access low T homogeneous supercooled states for $\phi > 0.25$ characterized by a glassy dynamics, driven by the bonding energy as opposed to packing, confirms the findings of the zeroth-order model with limited valency reported in ref 7. The absence of geometric correlation between the bonding sites, the key ingredient of the maximum valency model,⁷ is thus not crucial for the stabilization of the network. The role of the geometric constraint appears to be the reduction in the range of ϕ values where the fully bonded disordered state can be reached. Two different arrest mechanisms characterize the dynamics of network systems: arrest due to the formation of energetic cages, with an arrest line that runs almost parallel to the ϕ -axis, and arrest due to excluded volume effects, with an arrest line parallel to the T-axis. These two lines are reminiscent of the attractive and repulsive glass lines observed in short-range attractive colloids.^{26,58,59,70,78} Connecting the results presented in this paper with previous studies of network-forming liquids,^{45,52} it is tempting to speculate that mode-coupling theory predicts satisfactorily the shape in the $(\phi - T)$ plane of the dynamics arrest lines. Still, although in the region where excluded volume controls caging the relative error in the location of the glass line is limited, in the case in which the bonding mechanism is dominant in generating arrest, the location of the MCT line can be significantly distant from the actual dynamic arrest line (technically located at T = 0, being dynamics Arrhenius), due to the role of activated bondbreaking processes, which offer a faster channel for the decay of the correlations. The evaluation of the MCT lines for the present model, in principle feasible within the site-site approach developed by Chong and Goetze^{79,80} or within the molecular approach developed by Schilling,48,81 can help to clarify this issue.

The possibility of an intersection between the excluded volume arrest line (starting at high *T* from the HS glass-packing fraction) and the bond-controlled T = 0 arrest line is particularly suggestive. The shape of the isodiffusivity lines supports the possibility that the vertical repulsive glass line meets at a well-defined ϕ the T = 0 bond-controlled glass line. If this scenario is correct and general, one would conclude that the fragile and strong kinetic behavior is intimately connected to the dominant mechanism of arrest (fragile for excluded volume and strong for bonding) and, more interestingly, that strong behavior can be observed only when the interaction potential is such that fewer than six neighbors are present (i.e., in network-forming systems). Indeed, only under these circumstances does the suppression of the liquid–gas phase separation make it possible to approach the T = 0 bond-controlled glass line.

An additional comment concerns the relationship between gel and glass arrest states. Results reported in this paper confirm, once more, that in this class of models the geometric percolation line does not have any impact on the dynamic arrest, because at percolation the lifetime of the bond is still rather small. Only when the system is well inside the percolation region has the bond lifetime slowed significantly to affect all measurements of global connectivity with an intrinsic time scale shorter than the bond lifetime (as, for example, finite frequency shear viscosity). Indeed, already long ago it was noted for the case of water⁶¹ that bond percolation is irrelevant to any thermodynamic or dynamic anomaly. More sophisticated models, incorporating bond cooperativity or significant entropy contributions to bonding (as in the case of polymeric gels), may reduce the distance between dynamic arrest states and percolation.62

Despite the difference between percolation and arrest lines, if one considers the present model as a system of colloidal particles with sticky interactions, one would be led to call the arrested state at $0.3 \leq \phi \leq 0.5$ a gel, led by the fact that the arrested state has a low ϕ open connected structure. Similarly, if one considers the PMW to be a model for a network liquid, one would be led to name the same arrested state a network glass. Although we cannot offer any resolution to this paradox with the present set of data, future work focusing on the shape of the wavevector dependence correlation functions and the resulting nonergodicity parameters can help to clarify this issue and confirm/dispute the hypothesis on the differences between gels and glasses recently proposed.7,78,82 At the present time, we can only call attention to the fact that a continuous change from energetic cages to excluded volume cages takes place on increasing ϕ .

A final comment refers to the propensity of the system to form disordered arrested states. Despite the relevant amount of supercooling,¹⁵ in all studied state points where a network structure is present, we have not observed any sign of crystallization. The kinetic suppression of the crystallization phenomenon can be traced to the similar energy characterizing the crystal state and the fully bonded disordered state, fading the energetic driving force toward crystallization. The observed propensity to form gel states as opposed to crystalline states manifested by the studied model (which can be seen also as a model for short-range sticky colloidal particles as well as globular proteins with aeolotopic interactions²) may well explain the difficulty of crystallizing some class of proteins. It also warns us about the relevance of the dynamic arrest phenomenon in the future attempts to build a colloidal diamond photonic crystal made of particles with short-ranged patchy interactions.

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VII. Appendix: Event-Driven Algorithm for Hard Spheres with Patches

In an ED algorithm, events such as times of collisions between particles and cell crossing have to be taken into account. All of these events have to be ordered. Code must be written in such a way that locating the next event and insertion/deletion of new events have to be performed efficiently. In the literature, several ED algorithms for simulating hard-sphere systems exist, and several propositions on how to handle such events efficiently have been reported. One elegant approach, proposed 20 years ago by Rapaport,83 arranges events into an ordered binary tree (calendar of events) so that insertion, deletion, and retrieving of events can be done with efficiencies of $O(\log N)$, O(1), and $O(\log N)$, respectively, where N is the number of events in the calendar. We adopted this solution to handle the events calendar in our simulation, adding only a redefinition of event time to avoid round-off problems that are found when extremely long simulation runs are performed.

A. Motion of Rigid Bodies. The orientation of a rigid body can be conveniently represented by the three column eigenvectors \mathbf{u}_i (with i = 1, 2, 3) of the inertia tensor expressed in the laboratory reference system. These vectors form an orthogonal set and can be arranged in a matrix \mathbf{R} , that is

$$\mathbf{R} = {}^{t}(\mathbf{u}_0 \mathbf{u}_1 \mathbf{u}_2) \tag{11}$$

such that if x are the coordinates of the laboratory reference system and x' are the coordinates of the rigid body reference system, it turns out that

$$\mathbf{x}' = \mathbf{R}\mathbf{x} \tag{12}$$

In what follows, we assume that the three eigenvalues of the inertia tensor are all equal to *I*. Naming $\mathbf{w} = (w_x, w_y, w_z)$ the angular velocity of a free rigid body, the matrix Ω is defined as

$$\Omega = \begin{pmatrix} 0 & -w_z & w_y \\ w_z & 0 & -w_x \\ -w_y & w_x & 0 \end{pmatrix}$$
(13)

Knowing the orientation at time t = 0, the orientation $\mathbf{R}(t)$ at time t is^{84,85}

$$\mathbf{R}(t) = \mathbf{R}(0)(\mathbf{I} + \mathbf{M}) \tag{14}$$

where \mathbf{M} is the matrix

$$\mathbf{M} = -\frac{\sin(wt)}{w}\Omega + \frac{1 - \cos(wt)}{w^2}\Omega^2$$
(15)

and $w = ||\mathbf{w}||$. Note that if w = 0 then $\mathbf{R}(t) = \mathbf{R}(0)$. To derive eq 14, consider that

$${}^{t}R(t) = [\mathbf{u}_{1}(t)\mathbf{u}_{2}(t)\mathbf{u}_{3}(t)]$$

$$= [{}^{t}(\mathbf{I} + \mathbf{M})\mathbf{u}_{1} {}^{t}(\mathbf{I} + \mathbf{M})\mathbf{u}_{2} {}^{t}(\mathbf{I} + \mathbf{M})\mathbf{u}_{3})$$
(16)

where we remember that \mathbf{u}_i are column vectors. Hence, if $\mathbf{w} = w \hat{\mathbf{n}}$, we have after some algebra

$$\mathbf{u}_{i}(t) = \mathbf{u}_{i} \cdot \hat{\mathbf{n}}\hat{\mathbf{n}} + \cos(wt)(\mathbf{u}_{i} - \hat{\mathbf{n}} \cdot \mathbf{u}_{i}\hat{\mathbf{n}}) + \sin(wt) \hat{\mathbf{n}} \times \mathbf{u}_{i}$$
(17)

that is the so-called Rodriguez's formula or rotation formula, that is, a rotation of an angle wt around the axis \hat{n} . To conclude if one has to update position and orientation of a rigid body, which is freely moving, this can be accomplished doing

$$\mathbf{x}(t) = \mathbf{x}(0) + \mathbf{v}t \tag{18a}$$

$$\mathbf{R}(t) = \mathbf{R}(0)(\mathbf{I} + \mathbf{M}) \tag{18b}$$

where $\mathbf{x}(t)$ is the position of the center of mass of the rigid body at time *t* and **v** is its velocity.

B. Hard Sphere with Interacting Patches. In the present model, each particle is modeled as a hard sphere with *n* spherical patches arranged in fixed site locations. In the present case, the site—site interaction is a SW potential

$$u_{\rm SW} = \begin{cases} -u_0 & \text{if } r < \delta\\ 0 & \text{otherwise} \end{cases}$$
(19)

where δ and u_0 are the width and the depth of the SW. For the following discussion, the SW interaction can be visualized as a sphere of diameter δ centered on the site location. Similarly, one can visualize the particle as a rigid body composed by the hard sphere joined to the spheres located on the sites. In what follows, we identify a particle with the resulting surface. The distance d_{AB} between two particles *A* and *B* is defined as the shortest line connecting two points on distinct particles, that is

$$d_{AB} = \min_{i_A, i_B} d_{i_A i_B} \tag{20}$$

where $i_A, i_B \in \{0, ..., n\}$ and 0 labels the hard sphere, 1...*n* labels the *n* spherical patches, and $d_{i_{A}i_B}$ is the distance between the two spherical patches i_A and i_B .

l

C. Prediction of Time of Collision. *1. Finding the Contact Time.* We separate the collisions between two particles in the hard-sphere part of the potential and the site—site interaction part. The time of collision $t_{\rm hs}$ between the hard-sphere cores can be evaluated as usual.⁸³ The smallest time of collision among all n^2 spherical patch pairs is $t_{\rm st}$. The time of collision of the two particles is

$$t_{\rm c} = \min\{t_{\rm hs}, t_{\rm st}\}\tag{21}$$

To find the time of collision of two interacting patches, we assume that it is possible to bracket it. That is, we assume (see further subsections) that the time of collision t_{st} is such that $t_1 < t_{st} < t_2$, where the product $d(t_1)d(t_2) < 0$. Thus, the "exact" time of collision is provided by the root of the equation

$$||r_{i_{4}}(t) - r_{i_{p}}(t)|| = \delta$$
(22)

where r_{i_A} and r_{i_B} are the two site locations.

2. Linked Lists and Centroids. As described in ref 83 to speed an ED molecular dynamics of hard spheres, one can use linked lists. For a system of N identical particles inside a cubic box of edge L, we define the "centroid" 86,87 as the smallest sphere that contains the particle (the HS and the spherical patches). Linked lists of centroids may be quite useful to reduce the number of objects to check for possible collisions; in addition they can be used to restrict the time interval within which searching for the collision is performed. We divide the box into M^3 cells so that each cell contains at most one centroid. After that, we build the linked lists of these centroids and handle these lists as done in a usual ED molecular dynamics of hard spheres.⁸³ This means that whenever an object crosses a cell boundary, one has to remove such object from the cell the particle is coming from and add this object to the cell it is going to.

Now consider that one has to predict all of the possible collisions of a given particle, which is inside a certain cell m. As for the hard spheres case we take into account only the particles inside the adjacent cells (see ref 83 for more details), and we predict the times of collisions with these objects. Consider now two particles A and B at time t = 0 and their centroids C_A and C_B . Three possible cases arise:

1. C_A and C_B do not overlap and, from an evaluation of their trajectory, no collision between the two centroids is predicted. In this case *A* and *B* will not collide either.

2. C_A and C_B do not overlap, but they will collide: in this case, we calculate two times t_1 and t_2 , bracketing the possible collision between A and B: t_1 is defined as the time when the two centroids collide and start overlapping, and t_2 is the time when the two spheres have completely crossed each other and do not overlap any longer.

3. C_A and C_B overlap: in this case $t_1 \equiv 0$ and t_2 is defined as the time at which the two centroids stop overlapping.

3. Fine Temporal Bracketing of the Contact Time. Here we show how a refined bracketing of solution of eq 22 can be accomplished. First of all, we give an overestimate of the rate of variation of the distance between two patches i_A and i_B , that is

$$\dot{d}_{i_{A}i_{B}}(t) = \frac{d}{dt}(||\mathbf{r}_{i_{A}} - \mathbf{r}_{i_{B}}|| - \delta)$$

$$\leq \frac{\mathbf{r}_{i_{A}i_{B}} \cdot \mathbf{r}_{i_{A}i_{B}}}{||\mathbf{r}_{i_{A}i_{B}}||} \leq ||\mathbf{v}_{i_{A}i_{B}}||$$

$$= ||\mathbf{V}_{AB} + \omega_{A} \times (\mathbf{r}_{i_{A}} - \mathbf{R}_{A}) - \omega_{B} \times (\mathbf{r}_{i_{B}} - \mathbf{R}_{B})||$$

$$\leq ||\mathbf{V}_{AB}|| + ||\omega_{A}||L_{A} + ||\omega_{B}||\text{LB} = \dot{d}_{i_{A}i_{B}}^{\max}$$
(23)

where the dot indicates the derivation with respect to time, \mathbf{r}_{i_A} and \mathbf{r}_{i_B} are the positions of the two sites with respect to a laboratory reference system, $\mathbf{v}_{i_A i_B}$ is the relative velocity of the two sites, \mathbf{V}_{AB} is the relative velocity between the centers of mass of the two particles, and \mathbf{R}_A and \mathbf{R}_B are the positions of their centers of mass and

$$L_A \ge \max_{\mathbf{r}' \in A} \{ ||\mathbf{r}' - \mathbf{R}_A| \}$$
(24a)

$$L_B \ge \max_{\mathbf{r}' \in B} \{ |\mathbf{r}' - \mathbf{R}_B| \}$$
(24b)

Having calculated an overestimate of $d_{i_{AB}}(t)$, we can evaluate an overestimate of d_{AB} that we call d_{max} :

$$\dot{d}_{\max} = \max_{i_A i_B} \{ \dot{d}_{i_A i_B}^{\max} \}$$
 (25)

Using eq 25 we can easily find an efficient strategy to bracket the solution. In fact, the following algorithm can be used:

1. Evaluate the distances between all sites that may interact $\{d_{i_A i_B}(t)\}_{i_A i_B}$ at time *t* (starting the first time from t_1).

2. Choose a time increment Δt as

$$\Delta t = \begin{cases} \frac{d_{AB}(t)}{\dot{d}_{\max}} & \text{if } d_{AB}(t) > \epsilon_f \\ \frac{\epsilon_d}{\dot{d}_{\max}} & \text{otherwise} \end{cases}$$
(26)

where the two arbitrary parameters ϵ_d and ϵ_f satisfy $\epsilon_d < \epsilon_f \ll \min\{L_A, L_B\}$.

3. Evaluate the distances at time $t + \Delta t$.

4. If for at least one pair of patches (i_A, i_B) we find that the product $d_{i_A i_B}(t + \Delta t) d_{i_A i_B}(t) < 0$, we have bracketed a solution. We then find the collision times and the collision points solving eq 22 for all pairs. Choose the smallest collision time and terminate.

5. If pairs of patches are such that $0 < |d_{i_Ai_B}(t + \Delta t)| < \epsilon_d$ and $0 < |d_{i_Ai_B}(t)| < \epsilon_d$, for each of these pairs evaluate the distance $d_{i_Ai_B}(t + \Delta t/2)$, perform a quadratic interpolation of these three points $[t, d_{i_Ai_B}(t); t + \Delta t/2, d_{i_Ai_B}(t + \Delta t/2); t + \Delta t, d_{i_Ai_B}(t + \Delta t)]$, and find if the resulting parabolas have zeros. If yes, refine the smallest zero, solving again eq 22 for all of these pairs.

6. Increment time by Δt , that is

$$t \to t + \Delta t \tag{27}$$

7. Go to step 1 if $t < t_2$.

If two spherical patches of two particles undergo a "grazing" collision, that is, a collision in which the modulus of the distance stays smaller than ϵ_d during the collision, the collision could not be located by the previous algorithm due to failure of the quadratic interpolation. If during the grazing collision no further collisions involving one of the two particles are scheduled, the collision will pass unnoticed. Instead, if during the grazing collision a collision with other particles is scheduled, then energy

may not be conserved and the grazing collision can be detected. This event is so rare with $\epsilon_d \approx 10^{-6}$ that it has never been observed in our simulations.

The basic algorithm can be improved with simple optimizations. For example, one can calculate \dot{d}_{i,i_e}^{\max} as

$$\dot{d}_{i_{A}i_{B}}^{\max} = ||\mathbf{V}_{AB}|| + ||\omega_{A}||L_{i_{A}} + ||\omega_{B}||L_{i_{B}}$$
(28)

where

$$L_{i_A} = ||\mathbf{r}_{i_A}' - \mathbf{R}_A|| \tag{29a}$$

$$L_{i_B} = ||\mathbf{r}_{i_B}' - \mathbf{R}_B|| \tag{29b}$$

and if $d_{AB}(t) > \epsilon_{j}$, the time increment can be evaluated in the following optimized way:

$$\Delta t = \min_{i_A i_B} \{ d_{i_A i_B}(t) / d_{i_A i_B}^{\max} \}$$
(30)

D. Collision of Two Particles. At the collision time, one has to evaluate the new velocities of centers of mass and the new angular velocities. If \mathbf{x}_{C} is the contact point, then the velocities after the collision can be evaluated as

$$\mathbf{v}_A \rightarrow \mathbf{v}_A + m_A^{-1} \Delta p_{AB} \hat{\mathbf{n}}$$
(31a)

$$\mathbf{v}_B \rightarrow \mathbf{v}_B - m_B^{-1} \Delta p_{AB} \hat{\mathbf{n}}$$
(31b)

$$\mathbf{w}_A \rightarrow \mathbf{w}_A + \Delta p_{AB} I_A^{-1} (\mathbf{r}_A - \mathbf{x}_C) \times \hat{\mathbf{n}}$$
 (31c)

$$\mathbf{w}_{B} \rightarrow \mathbf{w}_{B} - \Delta p_{AB} I_{B}^{-1} (\mathbf{r}_{B} - \mathbf{x}_{C}) \times \hat{\mathbf{n}}$$
(31d)

where $\hat{\mathbf{n}}$ is a unit vector perpendicular to both surfaces at the contact point \mathbf{x}_{C} , I_{A} and I_{B} are the moments of inertia of the two colliding sticky particles, m_{A} and m_{B} are their masses, and the quantity Δp_{AB} depends on the type of the collision. If we define

$$v_{c} = (\mathbf{v}_{A} + \mathbf{w}_{A} \times (\mathbf{x}_{C} - \mathbf{r}_{A}) - \mathbf{v}_{B} - \mathbf{w}_{B} \times (\mathbf{x}_{C} - \mathbf{r}_{B})) \cdot \hat{\mathbf{n}} \quad (32)$$

If the collision occurring between particles is a hard-core collision, one has

$$\Delta p_{AB} = -2v_{\rm c} \tag{33}$$

if the collision occurred between two spherical patches already bonded (i.e., if prior to the collision the distance between the two sites is $<\delta$, one has

$$\Delta p_{AB} = \begin{cases} -2v_c & \text{if } v_c^2 < 2u_0/M_{\text{red}} \\ -v_c + \sqrt{v_c^2 - 2u_0/M_{\text{red}}} & \text{otherwise} \end{cases}$$
(34)

where

$$M_{\rm red}^{-1} = m_A^{-1} + m_B^{-1} + I_A^{-1} ||(\mathbf{r}_A - \mathbf{x}_C) \times \hat{\mathbf{n}}|| + I_B^{-1} ||(\mathbf{r}_B - \mathbf{x}_C) \times \hat{\mathbf{n}}||$$
(35)

Finally, if the collision occurs between two patches that are not bonded (i.e., the distance between the two sites is $> \delta$ prior to the collision), we have

$$\Delta p_{AB} = -v_{\rm c} + \sqrt{v_{\rm c}^2 - 2u_0/M_{\rm red}}$$
(36)

VIII. Appendix: Evaluating the Pressure

A. Evaluating the Pressure in the ED Code. We define the quantity

$$\Delta A_{\alpha\beta}(t) = V \int_0^t \mathscr{P}_{\alpha\beta}(t') \,\mathrm{d}t' \tag{37}$$

where $\mathscr{L}_{\alpha\beta}$ is the molecular pressure tensor

$$\mathscr{D}_{\alpha\beta}V = \sum_{i=1}^{N} M_i V_{i\alpha} V_{i\beta} + \sum_{i=1}^{N} \sum_{j>i}^{N} F_{ij\alpha} (R_{i\beta} - R_{j\beta}) \qquad (38)$$

The sums in the previous expression involve components (denoted by Greek letters), \vec{V}_i , \vec{R}_i , and \vec{F}_{ij} , which are the velocity, the position of center of mass of the *i*th particle (mass M_i), and the total force acting between particles *i* and *j*, respectively.

In the presence of impulsive forces, the stress tensor defined in eq 38 is not well-defined, whereas the integral in eq 37 is well-defined. Consider the time interval $(t, t + \Delta t)$. During this interval the quantity $\Delta A_{\alpha\beta}(t)$ will vary due to the collisions occurring between particles. The variation $\delta A(t)$ of $\Delta A(t)$ is

$$\delta A_{\alpha\beta}(t) = \sum_{i}^{N} M_{i} V_{i\alpha} V_{i\beta} \delta t + R_{i\alpha} \delta P_{i\beta}$$

where δt is the time elapsed from the last collision occurring in the system and $\delta \mathbf{P}_i$ is the variation of momentum of particle *i* after the collision, that is

$$\delta P_{i\alpha} = \Delta p_{AB} \hat{n}_{\alpha} \tag{39}$$

where Δp_{AB} is the quantity defined in eq 32.

From $\Delta A_{\alpha\beta}(t)$ and $\Delta A_{\alpha\beta}(t + \Delta t)$ the average pressure over the interval Δt can be evaluated as follows:

$$P = \frac{1}{3V} \sum_{\alpha} \frac{\Delta A_{\alpha\alpha}(t + \Delta t) - \Delta A_{\alpha\alpha}(t)}{\Delta t}$$
(40)

B. Evaluating *P* in MC. In the analysis of MC configurations, pressure has been calculated as the sum of three contributions: a trivial kinetic contribution, equal to $nk_{\rm B}T$; a positive HS contribution, which requires the evaluation of the hard-sphere radial distribution function $g_{\rm HS}(r)$ at distance σ ; and a negative contribution arising from the SW interaction, which requires the evaluation of the H–LP radial distribution function $g_{\rm H-LP}(r)$ at distance δ as well as the evaluation of $\langle R_{\rm H-LP}(r) \rangle$. For a pair of H and LP sites whose distance is *r*, the quantity $R_{\rm H-LP}$ is defined as the projection of the vector joining the centers of the two particles associated with the two sites along the direction of the unitary vector joining the two sites. The ensemble average $\langle \cdots \rangle$ is performed over all pairs of H and LP sites at relative distance r^1 .

The resulting expression for P is

$$P = nk_{\rm B}T \left(1 + 4\phi \left[g_{\rm HS}(\sigma) - 8\frac{\delta^2}{\sigma^3}(1 - e^{-1/T}) < R_{\rm H-LP}(\delta) > g_{\rm H-LP}(\delta)\right]\right) (41)$$

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