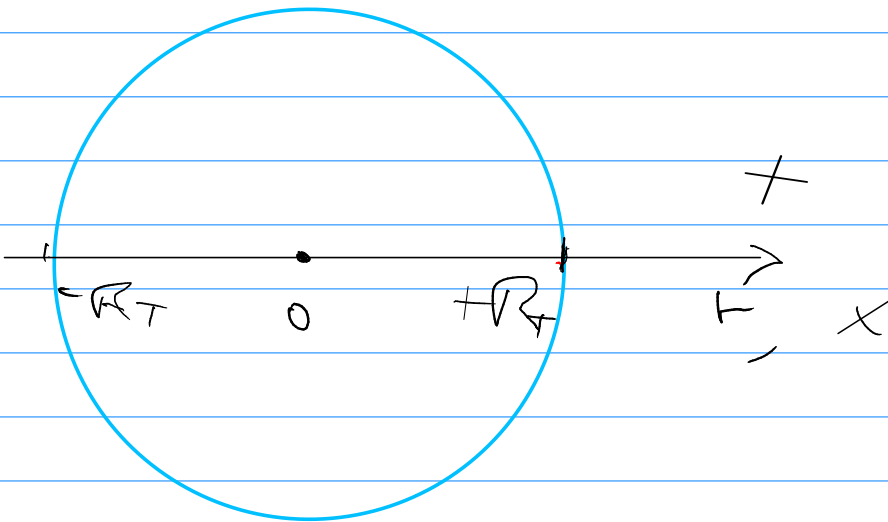
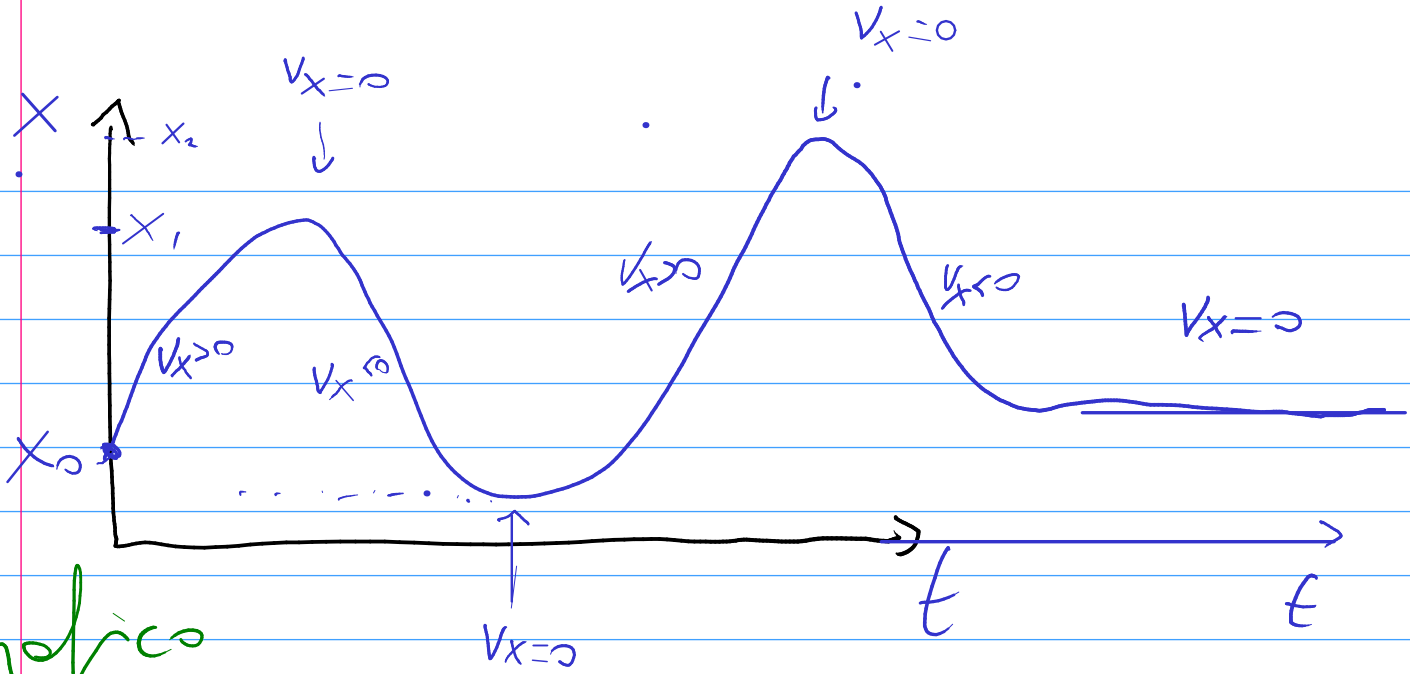


$$v_x = \frac{dx}{dt} \rightarrow \text{"pendente"}$$



$$dx = v_x \cdot dt \quad \parallel \quad \begin{array}{l} v_x > 0 \quad dt > 0 \Rightarrow dx > 0 \\ v_x < 0 \quad dt > 0 \Rightarrow dx < 0 \end{array}$$

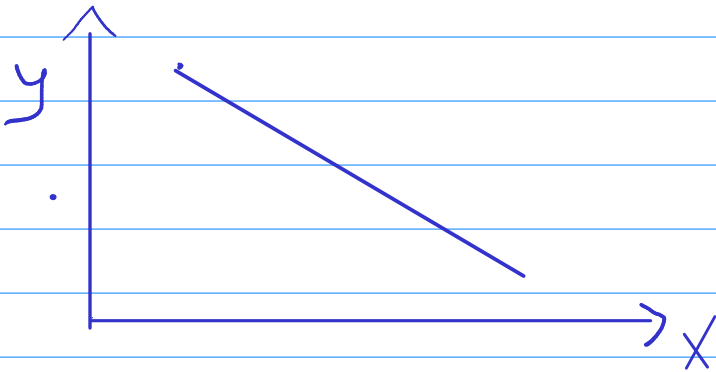
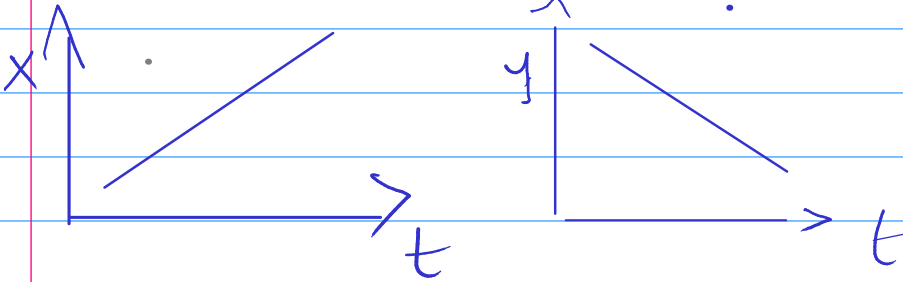
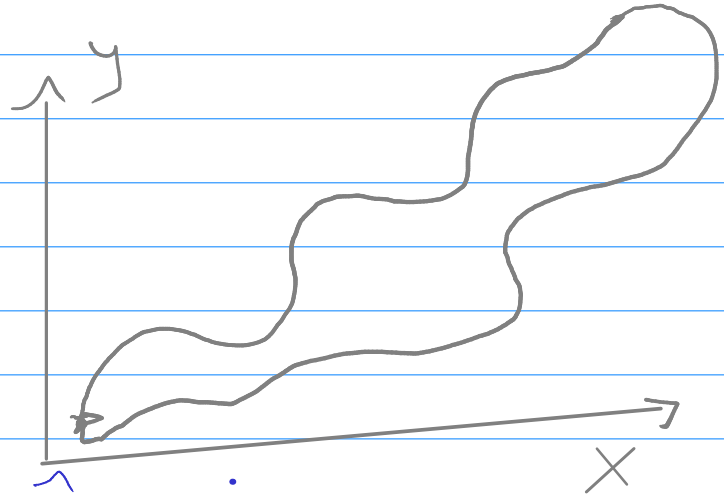
$$\Delta t \rightarrow 0 \quad \Delta x = \bar{v}_x \cdot \Delta t$$



|| gndrica  
ononno

$x$  vs  $t$   
 $y$  vs  $t$   
 $z$  vs  $t$

→ Traiettorie



$$v = \frac{2\pi R}{T}$$

velocità lungo la circonferenza

(f)

$$f = \frac{1}{T}$$

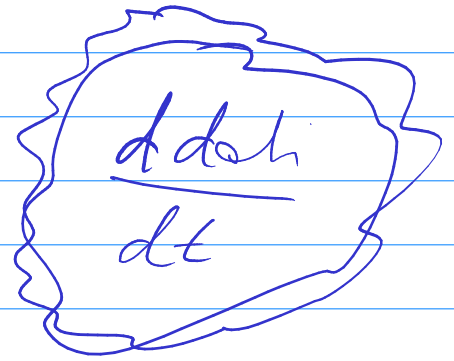
frequenza di rotazione

$$\omega = \frac{2\pi}{T}$$

velocità angolare

$$\left( \frac{360^\circ}{T} \right)$$

$R, T, v, f, \omega$

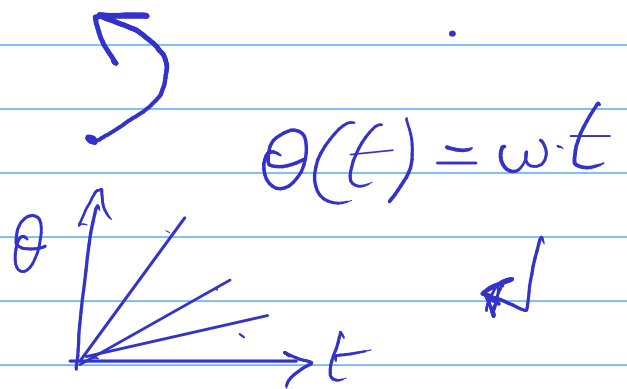


$$\omega = \frac{d\theta}{dt}$$

Componenti

$$\begin{cases} x = R \cdot \cos(\omega t) \\ = R \cdot \cos(\theta(t)) \end{cases}$$

$$y = R \cdot \sin(\omega t)$$



$$r = \sqrt{x^2 + y^2} = R$$

≡

!

$$\begin{cases} v_x = \frac{dx}{dt} = -\omega R \sin \omega t \\ v_y = \frac{dy}{dt} = \omega R \cos \omega t \end{cases}$$

$$v = \sqrt{v_x^2 + v_y^2} \\ = \sqrt{\omega^2 R^2 (\sin^2 \omega t + \cos^2 \omega t)} \\ = \omega R$$

$$\begin{cases} a_x = \frac{dv_x}{dt} = -\omega^2 R \cos \omega t = -\omega^2 \cdot x \\ a_y = \frac{dv_y}{dt} = -\omega^2 R \sin \omega t = -\omega^2 \cdot y \end{cases}$$

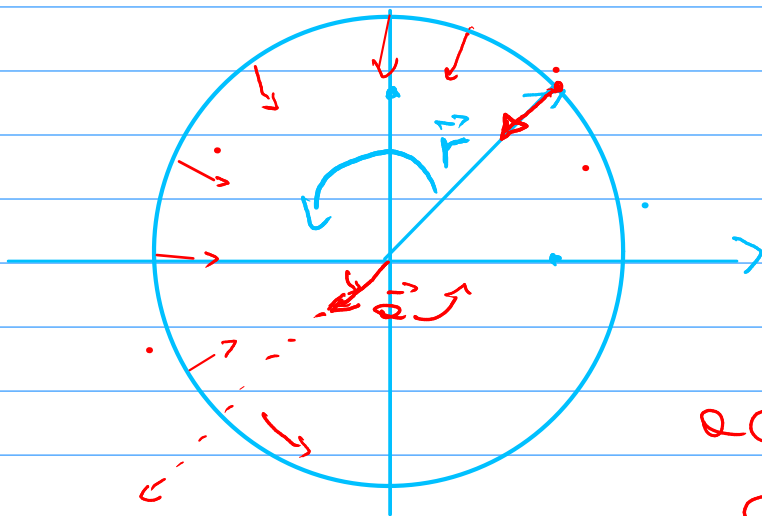
$$a = \sqrt{a_x^2 + a_y^2} = \omega^2 R$$

$$|\vec{F}| = a \cdot m$$

$$v = \omega R \rightarrow \omega = \frac{v}{R}$$

$$|\vec{F}| = m \frac{v^2}{R}$$

$$Q = \frac{v^2}{R^2} \cdot R = \frac{v^2}{R}$$

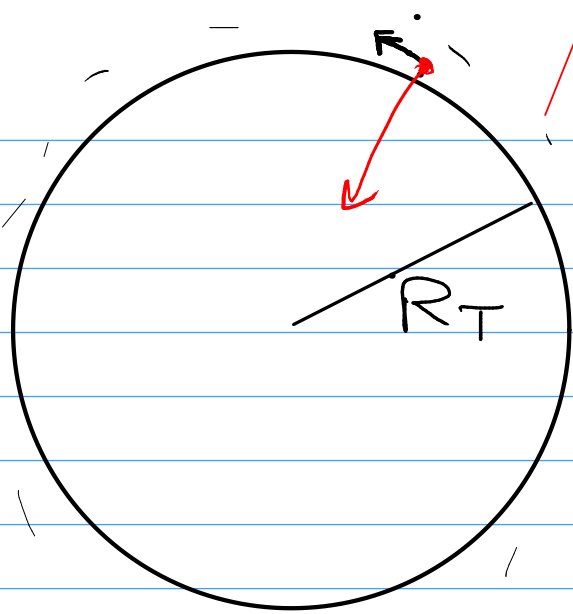


$$\vec{r} = (x, y)$$

$$\underline{Q = -\omega^2 \cdot \vec{r}}$$

acceleration  
centripeta

$$\vec{F} = m \vec{Q} \Rightarrow \text{for } \omega \text{ antipeta!}$$



$$|F| = m g$$

$$|a| = \cancel{g} g$$

$$a = \omega R$$

$$g = \omega R_T$$

$$a = \frac{v^2}{R}$$

$$g = \frac{v^2}{R_T}$$



1) "on the outside"  $\rightarrow v$

2)  $g_{ISS} \rightarrow$  proportional

$$\frac{R_T^2}{R_{ISS}^2}$$

$$\rightarrow v_{ISS}$$

$$\rightarrow T_{ISS}$$

