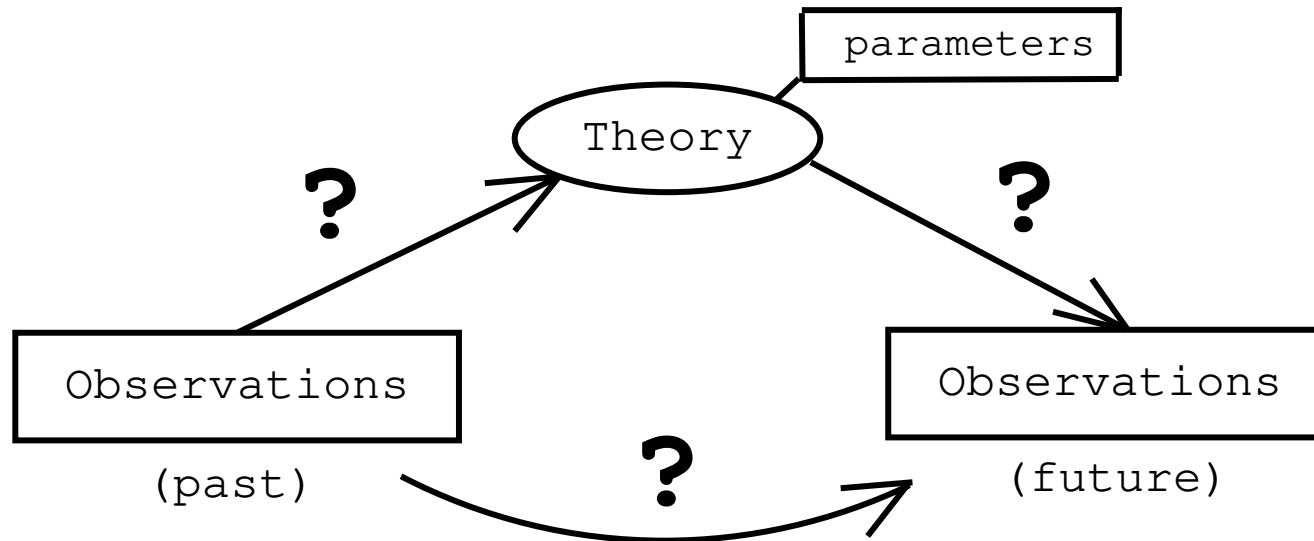


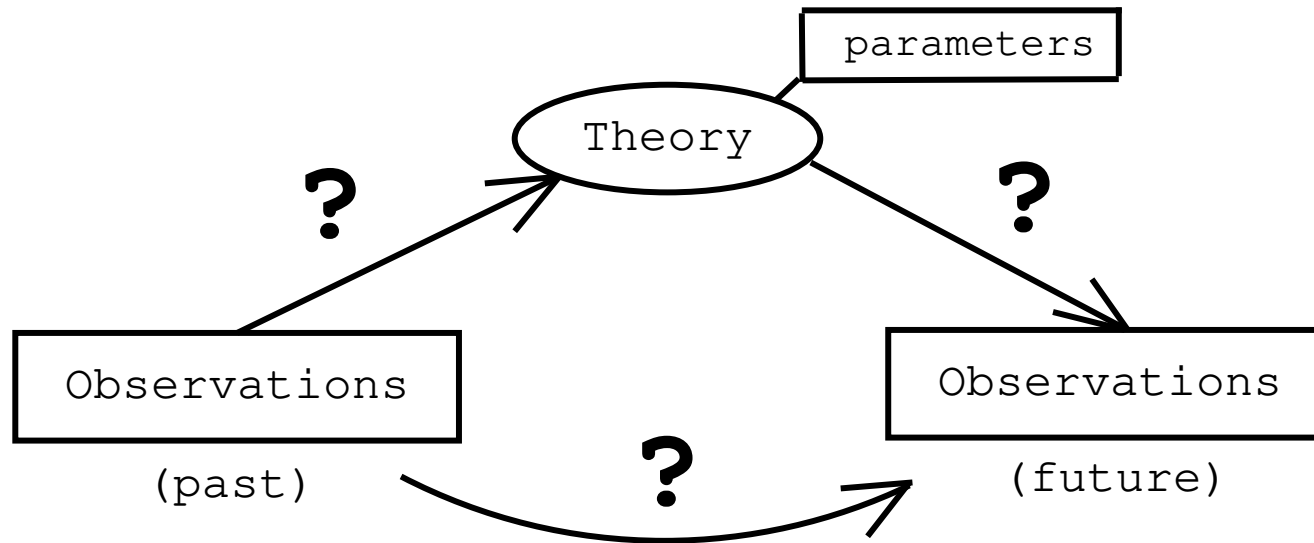
Uncertainty



⇒ Uncertainty:

1. Given the past observations, in general we are not sure about the parameters of the model (and/or the model itself)
2. Even if we were sure about theory and parameters, there could be internal ("noise", variables out of our control) or external effects (initial/boundary conditions, 'errors', etc) that make the forecasting uncertain.

Uncertainty



⇒ Uncertainty:

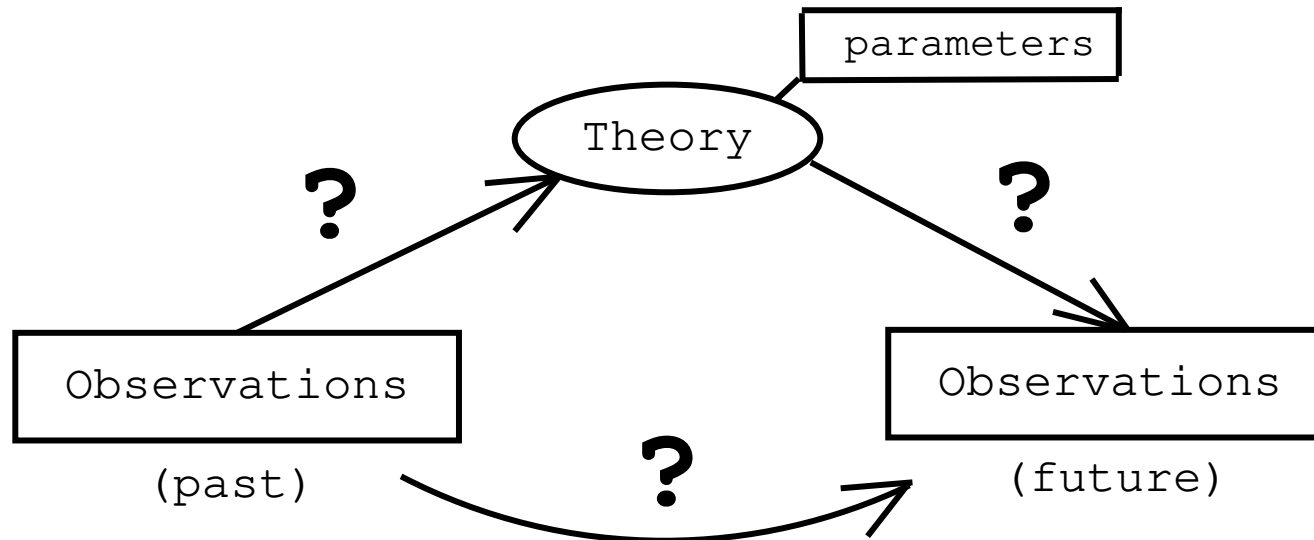
▶ No certainties, only probabilities

▶ $P(\Theta \mid X_{past})$

▶ $P(X_{future} \mid \Theta)$

▶ $P(X_{future} \mid X_{past})$

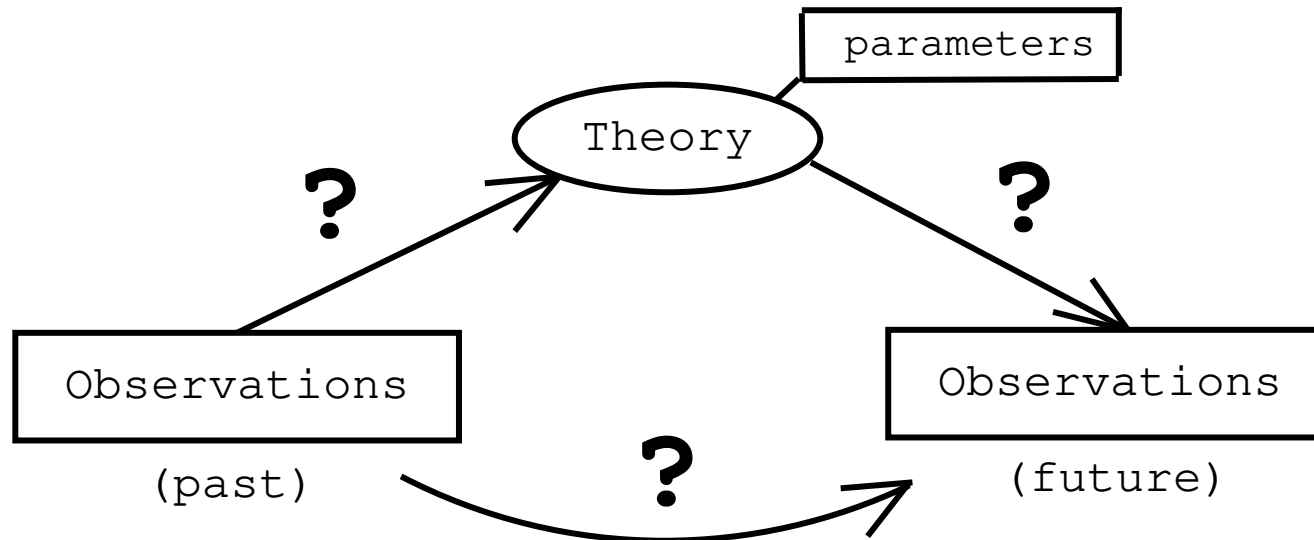
Deep source of uncertainty



Uncertainty:

Theory	— ? —→	Future observations
Past observations	— ? —→	Theory
Theory	— ? —→	Future observations

Deep source of uncertainty

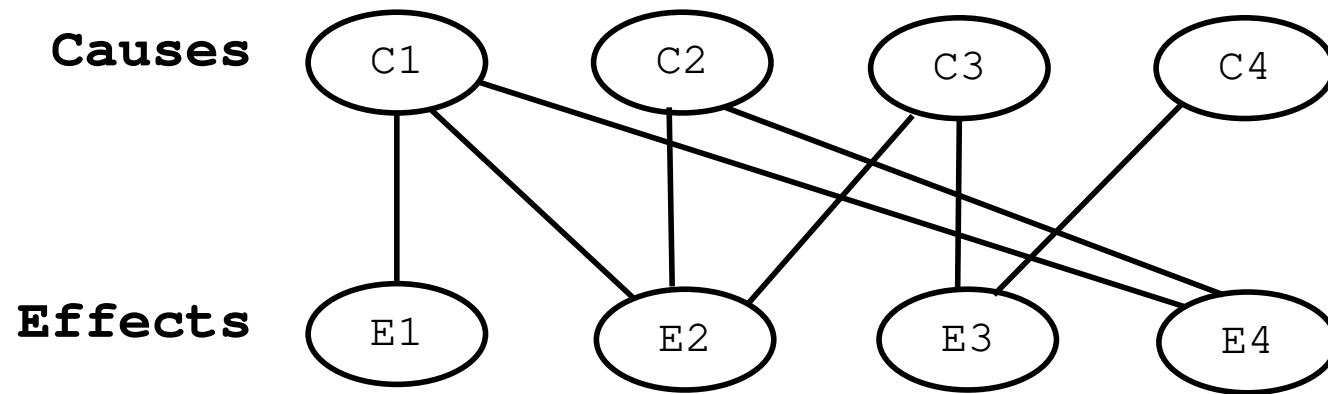


Uncertainty:

Theory — ? → Future observations
Past observations — ? → Theory
Theory — ? → Future observations
⇒ **Uncertainty about causal connections**
CAUSE ⇌ EFFECT

Causes → effects

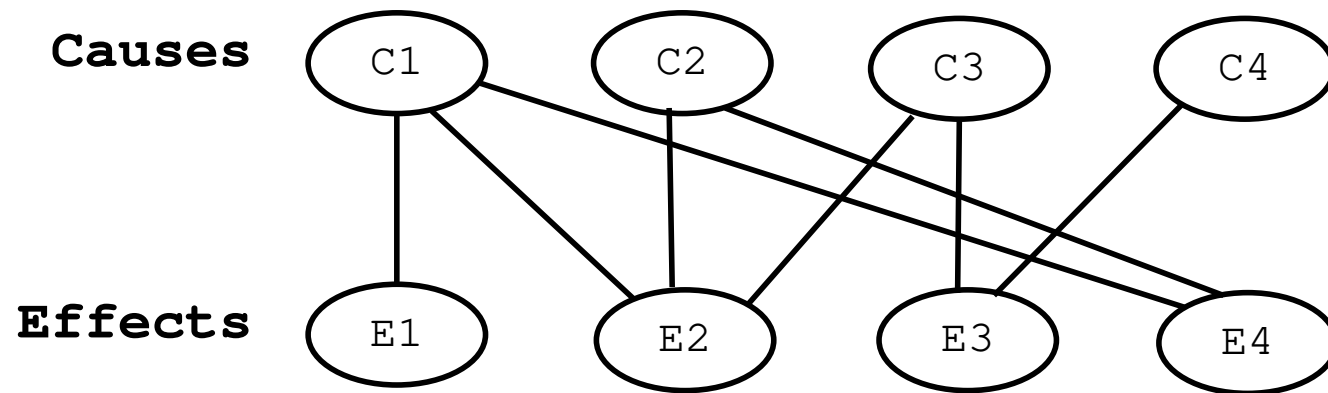
The same *apparent* cause might produce several, different effects



Given an observed effect, we are not sure about the exact cause that has produced it.

Causes → effects

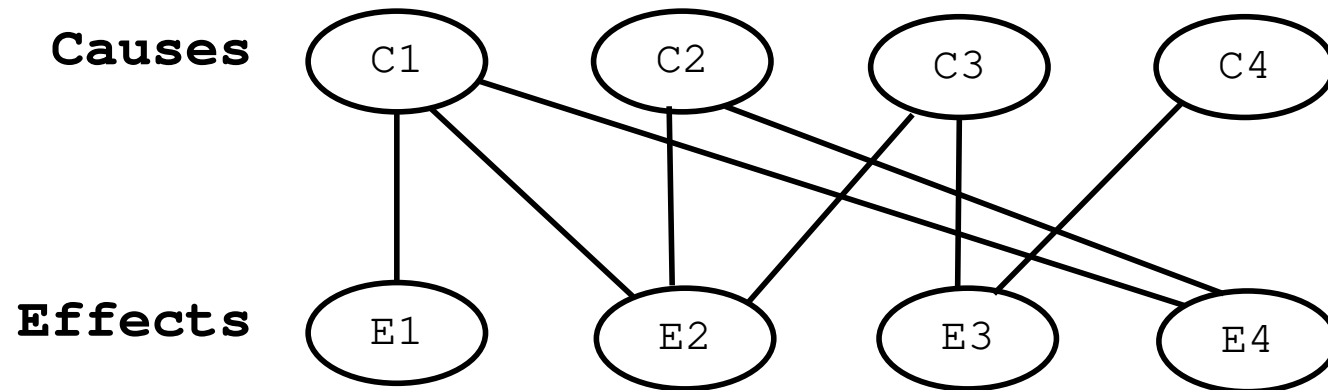
The same *apparent* cause might produce several, different **effects**



Given an **observed effect**, we are not sure about the **exact cause** that has produced it.

Causes → effects

The same *apparent* cause might produce several, different effects



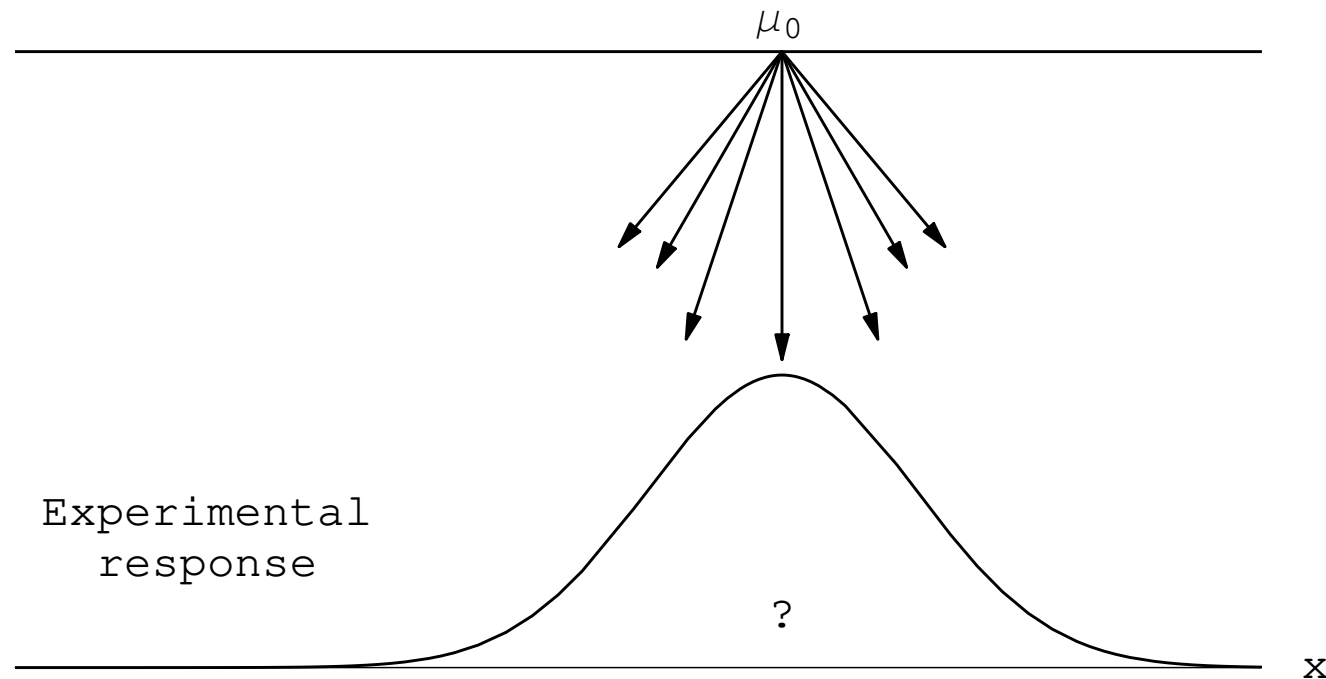
Given an observed effect, we are not sure about the exact cause that has produced it.

$$E_2 \Rightarrow \{C_1, C_2, C_3\}?$$

→ Probability of causes

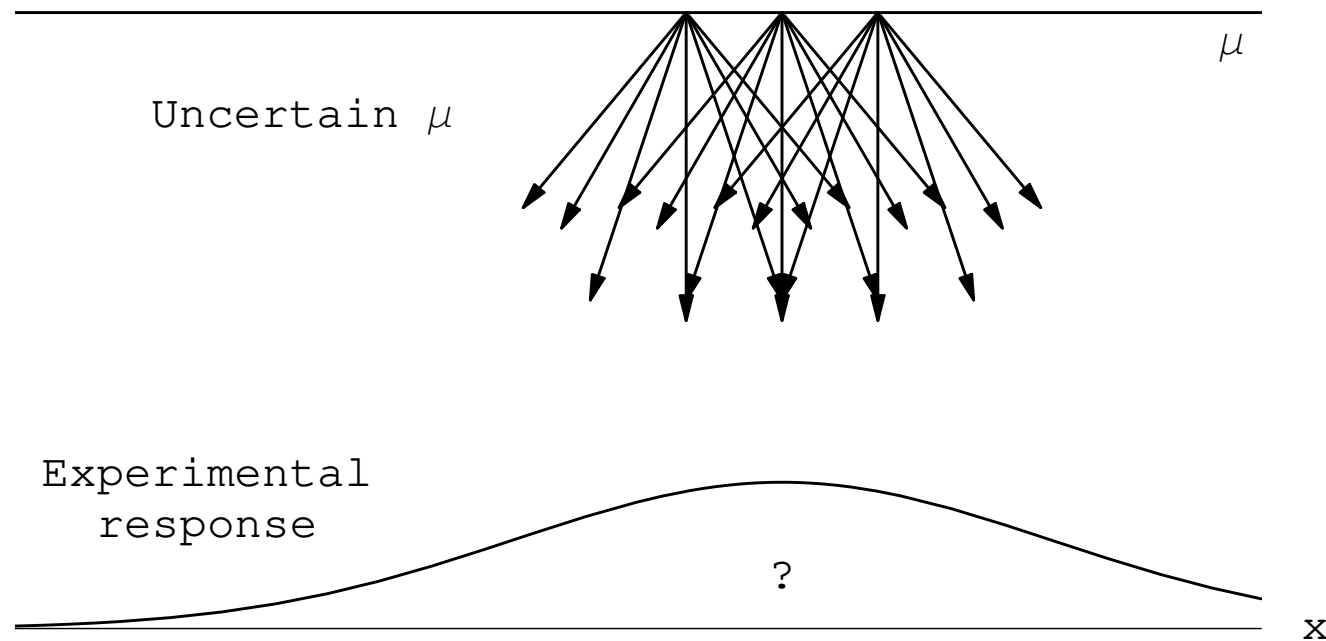
“the essential problem of the experimental method”

From 'true value' to observations



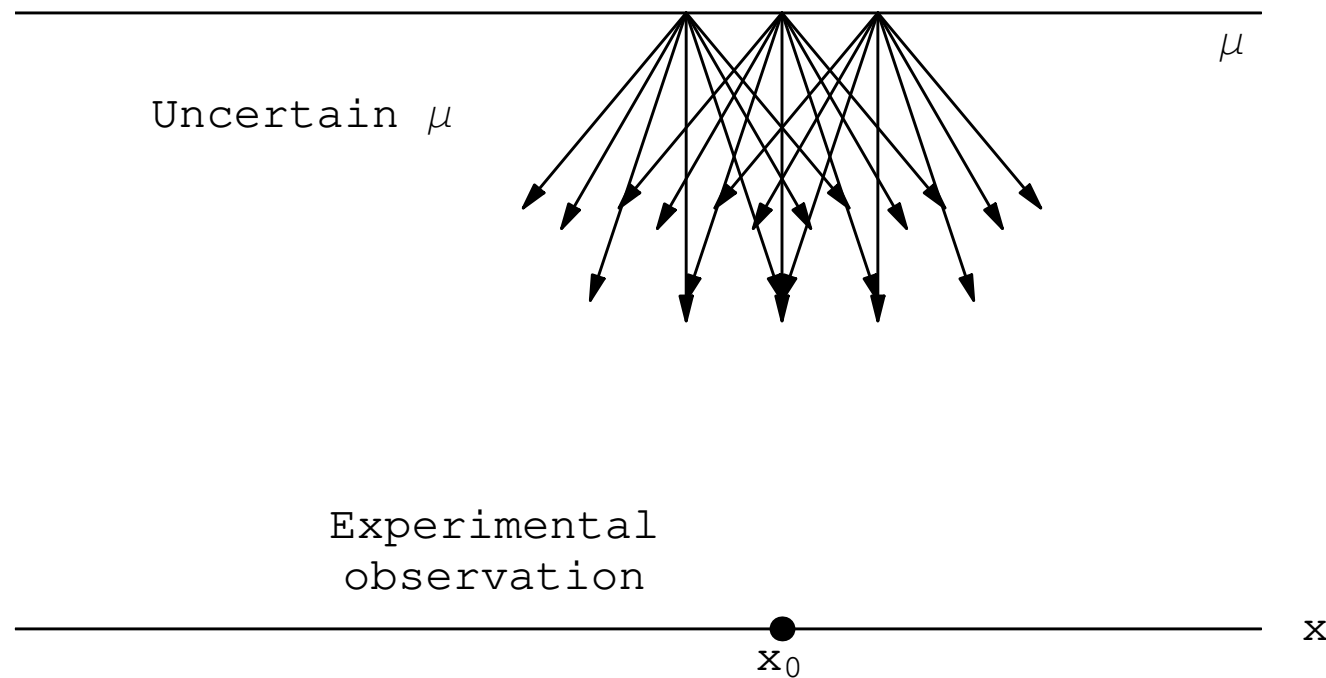
Given μ (exactly known) we are uncertain about x

From 'true value' to observations



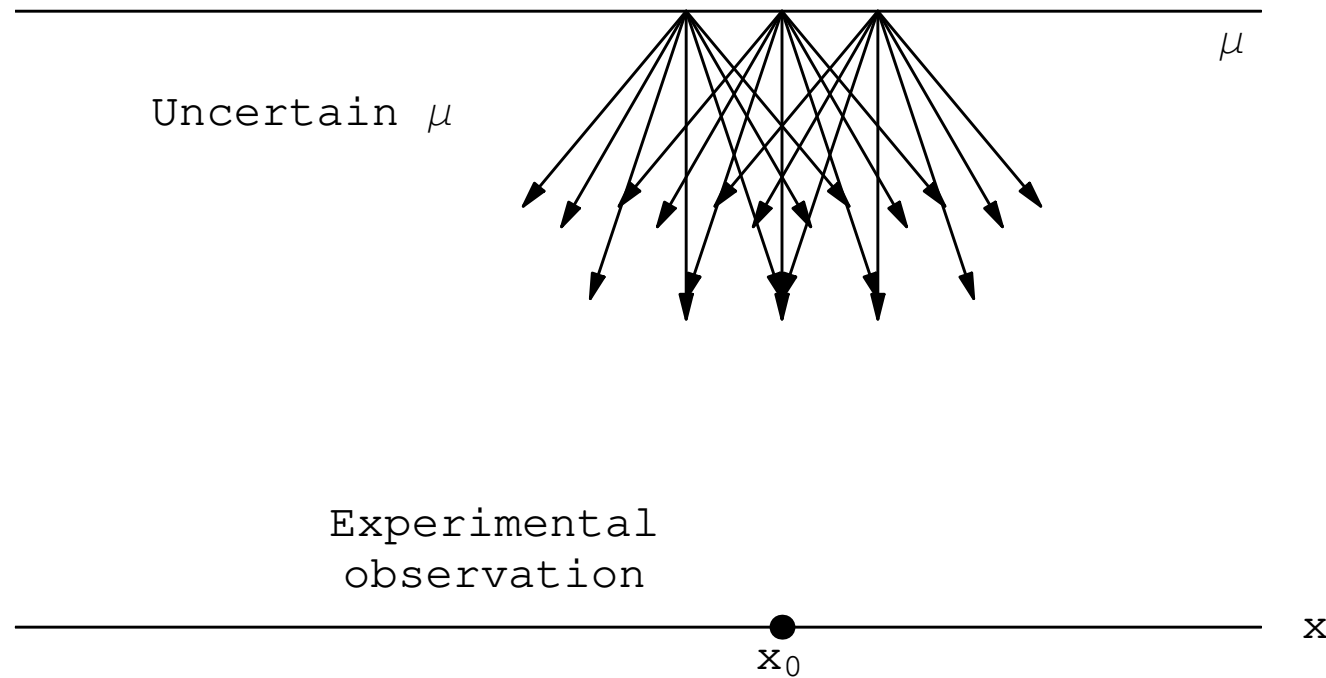
Uncertainty about μ makes us more uncertain about x

...and back: Inferring a true value



The observed data is certain: \rightarrow 'true value' uncertain.

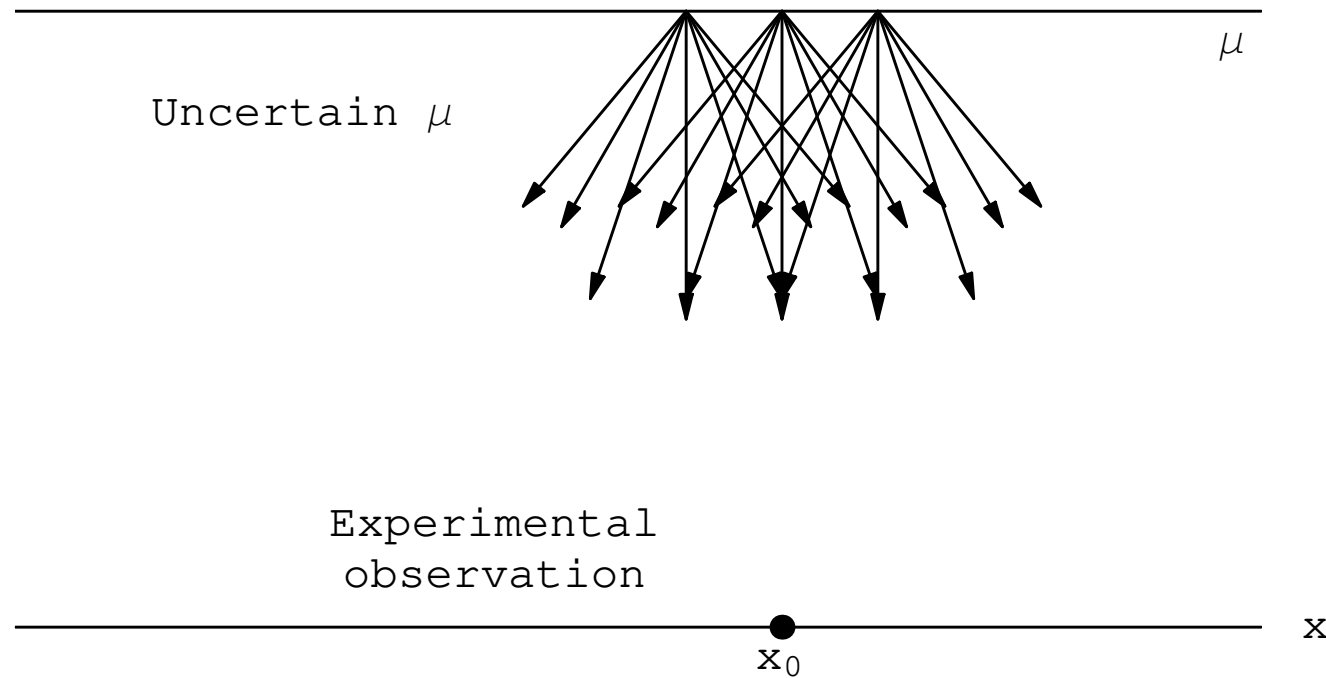
...and back: Inferring a true value



The observed data is certain: \rightarrow 'true value' uncertain.

“data uncertainty” ?

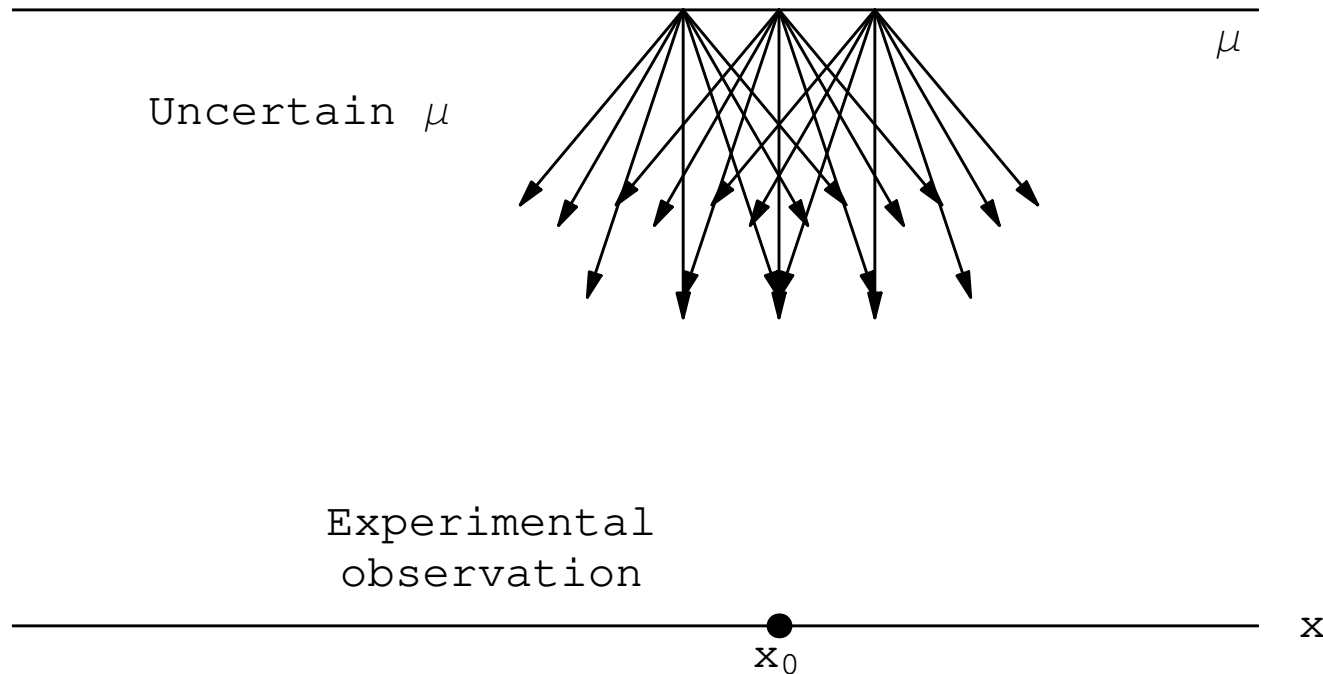
...and back: Inferring a true value



The observed data is certain: \rightarrow 'true value' uncertain.

“data uncertainty” ? Data corrupted?

...and back: Inferring a true value

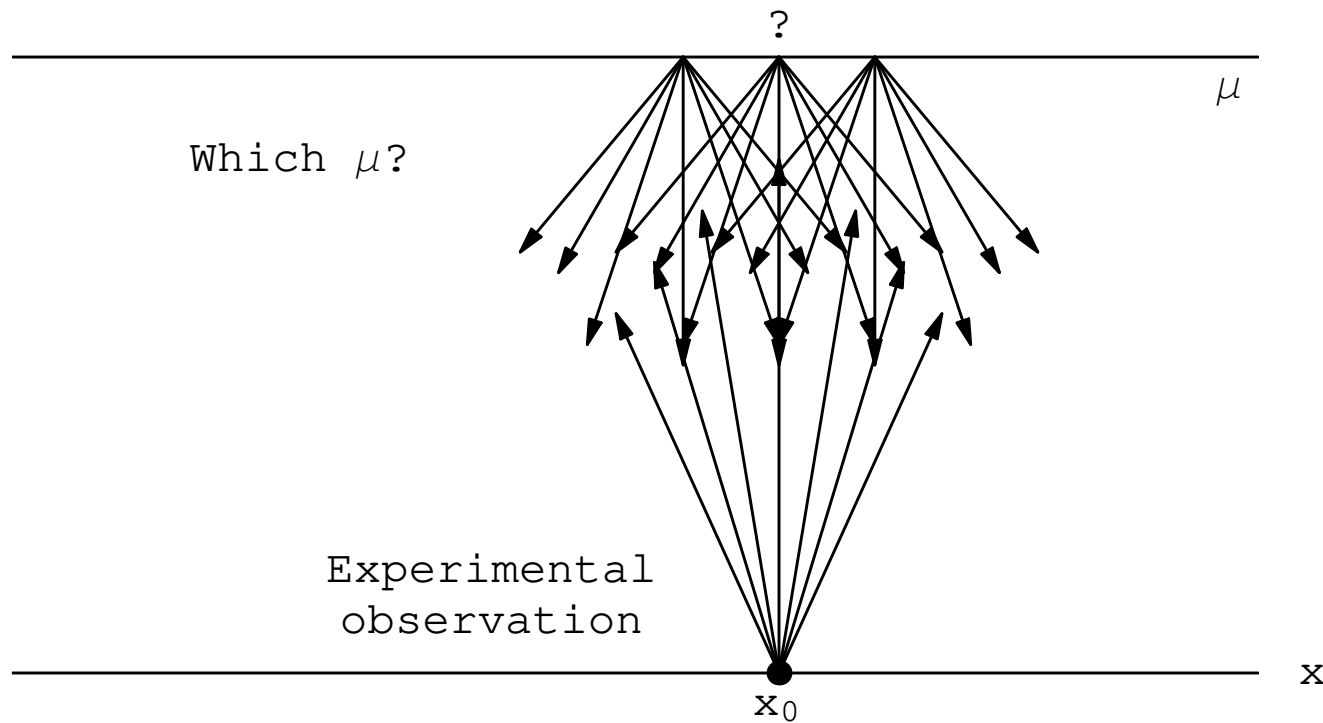


The observed data is certain: \rightarrow 'true value' uncertain.

“data uncertainty” ? Data corrupted?

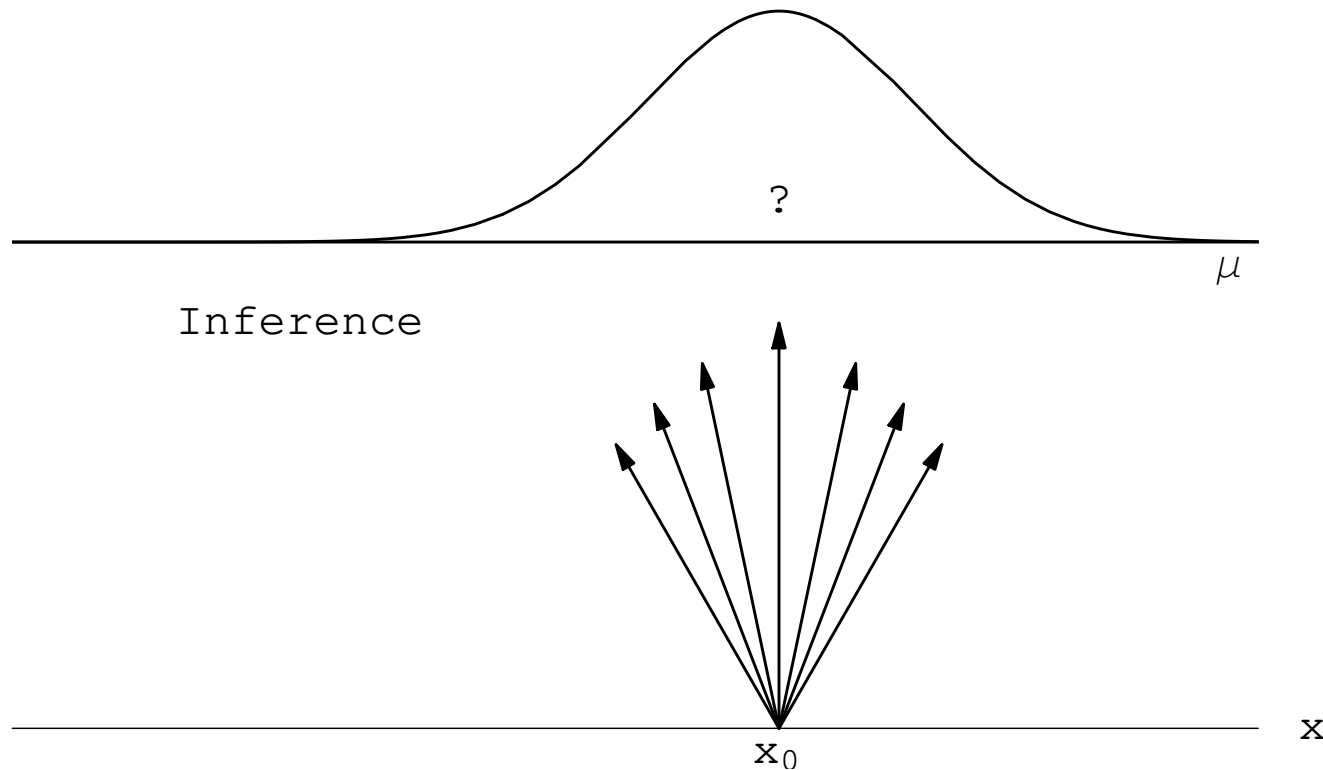
Even if the data were corrupted, the data were the corrupted data!!...

...and back: Inferring a true value



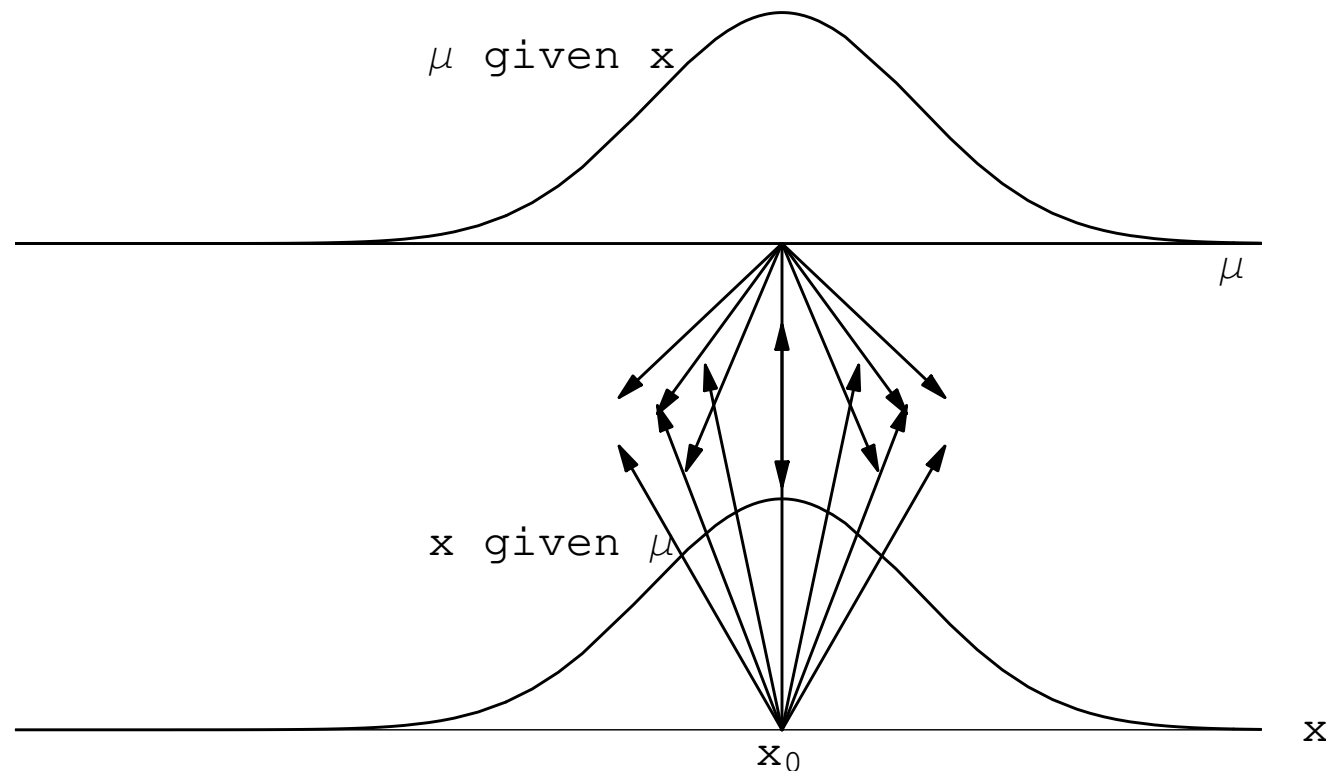
Where does the observed value of x comes from?

...and back: Inferring a true value



We are now uncertain about μ , given x .

...and back: Inferring a true value



Note the symmetry in reasoning.

A very simple experiment

Let's make an experiment

A very simple experiment

Let's make an experiment

- ▶ Here
- ▶ Now

A very simple experiment

Let's make an experiment

- ▶ Here
- ▶ Now

For simplicity

- ▶ μ can assume only six possibilities:

0, 1, ..., 5

- ▶ x is binary:

0, 1

[(1, 2); Black/White; Yes/Not; ...]

A very simple experiment

Let's make an experiment

- ▶ Here
- ▶ Now

For simplicity

- ▶ μ can assume only six possibilities:

$0, 1, \dots, 5$

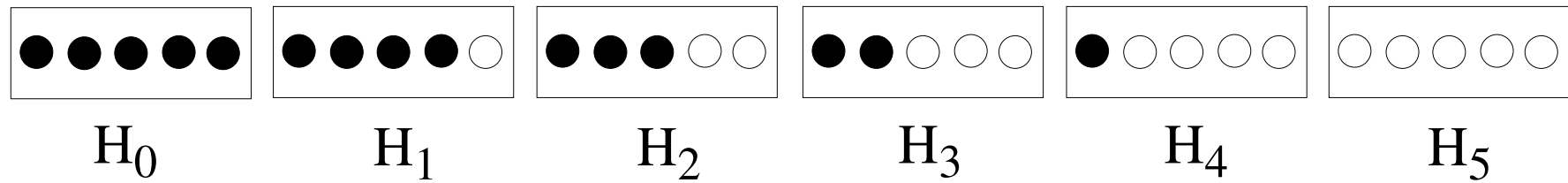
- ▶ x is binary:

$0, 1$

$[(1, 2); \text{Black/White}; \text{Yes/Not}; \dots]$

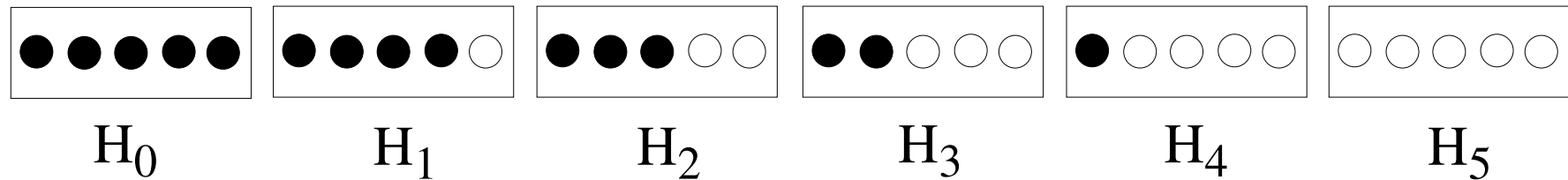
\Rightarrow Later we shall make μ continuous.

Which box? Which ball?



Let us take randomly one of the boxes.

Which box? Which ball?



Let us take randomly one of the boxes.

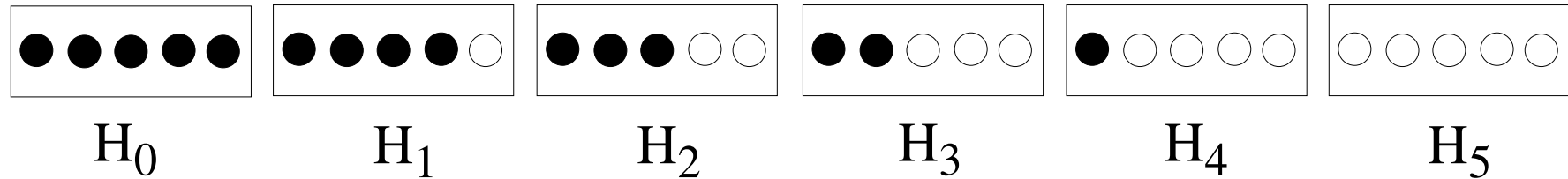
We are in a state of uncertainty concerning several *events*, the most important of which correspond to the following questions:

- (a) Which box have we chosen, H_0, H_1, \dots, H_5 ?
- (b) If we extract randomly a ball from the chosen box, will we observe a white ($E_W \equiv E_1$) or black ($E_B \equiv E_2$) ball?

Our certainties:

$$\bigcup_{j=0}^5 H_j = \Omega$$
$$\bigcup_{i=1}^2 E_i = \Omega.$$

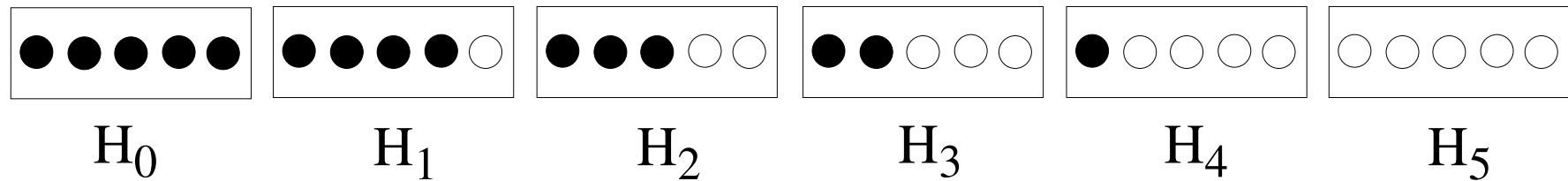
Which box? Which ball?



Let us take randomly one of the boxes.

- ▶ What happens after we have extracted one ball and looked its color?
 - ▶ Intuitively feel *how to roughly change* our opinion about
 - ▶ the possible cause
 - ▶ a future observation

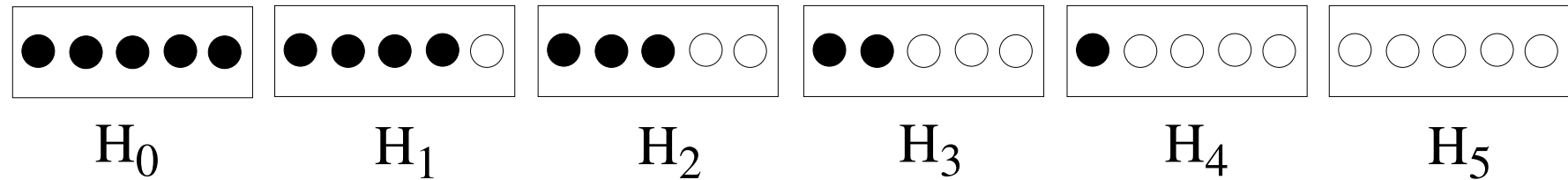
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 - ▶ Intuitively feel *how to roughly change* our opinion about
 - ▶ the possible cause
 - ▶ a future observation
 - ▶ Can we do it *quantitatively*, in an 'objective way'?
- ▶ And after a sequence of extractions?

The toy inferential experiment

The aim of the experiment will be to **guess** the content of the box **without looking inside it**, only extracting a ball, record its color and reintroducing in the box

The toy inferential experiment

The aim of the experiment will be to **guess** the content of the box **without looking inside it**, only extracting a ball, record its color and reintroducing in the box

This toy experiment is conceptually very close to what we do in the pure and applied sciences

⇒ try to guess what we cannot see (the electron mass, a magnetic field, etc)

...from what we can see (somehow) with our senses.

The rule of the game is that we are not allowed to watch inside the box! (As **we cannot open and electron and read its properties**, unlike we read the MAC address of a PC interface.)