Propagating uncertanties via linearization

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Propagation on uncertainties: rewriting the expressions of the linear combinations

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This observation suggest that we can make use of the results obtained for linear combinations if we linearize the generic functions [Note: Y_k () stands for the *k*-th function.]

$$Y_k = Y_k(\underline{X})$$

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We start making the expansion around the expected values of the X_i . It will be clear why this is the correct choice.

$$Y_{k} = Y_{K} (\mathsf{E}(\underline{X})) + \sum_{i} \frac{\partial Y_{k}}{\partial X_{i}} \Big|_{\mathsf{E}(\underline{X})} \cdot (X_{i} - \mathsf{E}(X_{i})) + \dots$$

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because

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2. A conventient way to rewrite Y_k

$$Y_k = \sum_i \left. \frac{\partial Y_k}{\partial X_i} \right|_{\mathsf{E}(\underline{X})} \cdot X_i + Y_k^{(0)},$$

with $Y_k^{(0)}$ including all terms non depending on X_i , and then irrelevant for variances and covariances of the Y_k

We have then reduced the problem to (approximatley) a linear combination

$$Y_k = \sum_{i=1}^n c_{ki} X_i + c_{k0}$$

with

$$c_{ki} = \frac{\partial Y_k}{\partial X_i} \Big|_{\mathsf{E}(\underline{X})}$$
$$c_{k0} = Y_k^{(0)} = Y_K \left(\mathsf{E}(\underline{X})\right) + \sum_{i=1}^n \frac{\partial Y_k}{\partial X_i} \Big|_{\mathsf{E}(\underline{X})} \cdot \mathsf{E}(X_i)$$



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 \Rightarrow We apply the rule of expected value of linear combinations, in particular,

$$\operatorname{Var}(Y_k) = \sum_{i=1}^n c_{ki}^2 \operatorname{Var}(X_i)$$

exercise: measuring an A4 paper

Imagine we have measured the two sides of an A4 paper, obtaining

$$a = 29.73 \pm 0.03 \,\mathrm{cm}$$

 $b = 21.45 \pm 0.04 \,\mathrm{cm}$.

Evaluate (expected values, standard uncertainty and correlation)

- perimeter, p = 2a + 2b;
- Area, A = a b;
- diagonal, $d = \sqrt{a^2 + b^2}$.

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Matching the general notation:

▶
$$\underline{X} = \{a, b\}, \ \underline{Y} = \{p, A, d\}$$

▶ $E[a] = 29.73 \text{ cm}; \ \sigma(a) = 0.03 \text{ cm}; \ \text{Var}(a) = (0.03 \text{ cm})^2; \text{ etc.} ...$
▶ $\partial Y_1 / \partial X_1 = \partial p / \partial a = 2; \quad \partial Y_1 / \partial X_2 = \partial p / \partial b = 2;$
▶ $\partial Y_2 / \partial X_1 |_{E(\underline{X})} = \partial A / \partial a |_{E(\underline{X})} = b |_{E(\underline{X})} = 21.45 \text{ cm}$
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▶ etc. etc, ...

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(neglecting an irrelevant numerical factor).

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- Inearization formulae should be used with care
- ...and possibly avoided!
- But, nevertheless, when used correctly they offer useful insights in the dependence of the final result on the *input quantities* in terms of relative uncertainties.

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$$\frac{\partial Y}{\partial X_i} = \alpha_i \cdot X_1^{\alpha_1} \cdot X_2^{\alpha_2} \cdot \ldots \cdot X_i^{\alpha_i-1} \cdot \ldots \cdot X_n^{\alpha_n}$$

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The coefficients of the linear expansion around the expected values acquire a very simple and useful form

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In the case of several Y's the elements c_{ki} of the tranformation matrix **C** are therefore

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$$Y_{k} = X_{1}^{\alpha_{k1}} \cdot X_{2}^{\alpha_{k2}} \cdot \ldots \cdot X_{i}^{\alpha_{ki}} \cdot \ldots \cdot X_{n}^{\alpha_{kn}}$$
$$c_{ki} = \frac{\partial Y_{k}}{\partial X_{i}} \Big|_{\mathsf{E}(\underline{X})} = \alpha_{ki} \cdot \frac{Y_{K}}{X_{i}} \Big|_{\mathsf{E}(\underline{X})}$$

$$\sigma^2(\mathbf{Y}) \approx \sum_i \alpha_i^2 \left(\frac{\mathbf{Y}}{\mathbf{X}_i} \Big|_{\mathsf{E}(\underline{\mathbf{X}})} \right)^2 \sigma^2(\mathbf{X}_i)$$

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$$\left(\frac{\sigma(\mathbf{Y})}{|\mathsf{E}(\mathbf{Y})|} \right)^{2} \approx \sum_{i} \alpha_{i}^{2} \cdot \left(\frac{\sigma(\mathbf{X}_{i})}{|\mathsf{E}(\mathbf{X}_{i})|} \right)^{2}$$

$$\begin{split} \sigma^{2}(Y) &\approx \sum_{i} \alpha_{i}^{2} \left(\frac{Y}{X_{i}} \Big|_{\mathsf{E}(\underline{X})} \right)^{2} \sigma^{2}(X_{i}) \\ &= \sum_{i} \alpha_{i}^{2} \left(Y |_{\mathsf{E}(\underline{X})} \right)^{2} \frac{\sigma^{2}(X_{i})}{\mathsf{E}^{2}(X_{i})} \\ &\approx \sum_{i} \alpha_{i}^{2} \cdot \mathsf{E}^{2}(Y) \cdot \frac{\sigma^{2}(X_{i})}{\mathsf{E}^{2}(X_{i})} \\ \left(\frac{\sigma(Y)}{|\mathsf{E}(Y)|} \right)^{2} &\approx \sum_{i} \alpha_{i}^{2} \cdot \left(\frac{\sigma(X_{i})}{|\mathsf{E}(X_{i})|} \right)^{2} \\ r_{Y}^{2} &\approx \sum_{i} \alpha_{i}^{2} \cdot r_{X_{i}}^{2}, \end{split}$$

Special subcase: variance from independent variables In the case of a single Y and independent X, we get

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having indicated with *r* the relative (standard) uncertainties $\sigma()/|E()|$.

Exercise

Imagine we want to measure g with a pendulum:

$$T = 2\pi \sqrt{\frac{I}{g}}$$

from which it follows

$$g = (2\pi)^2 I T^{-2}$$

Q.: How precisely we have to measure I and T if we require they contribute equally to r_g , that we want to keep $\leq 1\%$?

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$$p_g \leq 1$$

 $p_l = 2p_T \leq 1/\sqrt{2} = 0.71$
 $p_T \leq 1/(2\sqrt{2}) = 0.35$

Last remarks on linearization

- Linerization formulae rely on the fact that the trasformations are 'enough' linear in the regions where the probability mass of the input quantities are concentrated (around their expected values).
- Always check by Monte Carlo!